

PREDICTIVE SOIL MAPPING SEMINAR:

Summary Report

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EXECUTIVE SUMMARY

Traditional soil mapping has been conducted in Alberta for decades and has provided valuable information to support industrial development plans and regulatory oversight. However, recent advances in remote sensing, modelling and data processing capabilities have produced opportunities to develop soil maps cheaper, faster, more effectively, and with greater reproducibility. Predictive Soil Mapping (PSM) is a suite of tools that allow for streamlining the entire soil mapping workflow – from sample design, to efficiencies in field data collection, field sampling, identification and numbering of samples from initial site ID, through lab processing to database entry, and finally to map production.

InnoTech Alberta has initiated a project to work collaboratively with numerous users of spatial soils data to develop the Forested Region of Alberta Soil Information System (FORASIS) utilizing existing data and predictive mapping techniques. For the forested regions of Alberta, the need for FORASIS exists because:

- Fit-for-purpose maps and GIS layers of soils information are not available
- The large quantity of soil information collected across the region is not available in a standardized digital database

The long term goal is that FORASIS be used as resource tool that fills these gaps and thereby to assists industry and government in making land management decisions at regional, local and/or operational scales.

A Seminar was held at the InnoTech Alberta facility in Edmonton on March 6, 2019 and was also accessible through a webinar to invited participants. A total of 148 people had registered to participate in the Seminar.

The objective of the seminar was to develop a collective understanding of the benefits and opportunities of Predictive Soil Mapping (PSM) as they relate to Alberta. It was not intended to be a high level training session in PSM; rather, it was intended to be an introduction to highlight the benefits and advantages offered by PSM in comparison to conventional soil mapping methods.

The speakers and high-level messages of the talks were:

- Dr. Robert (Bob) MacMillian LandMapper Environmental Solutions Inc.
 - Provided a high-level overview of predictive soil mapping and how this mapping approach relates to conventional soil mapping approaches
- Dr. Markus Walsh Agriculture and Food Security Center, Earth Institute, Columbia University
 - Described the value created to farmers by predictively mapping soil properties across Africa
 - How proximal soil sensors are being leveraged to efficiently collect soil property data across Africa
 - How crowd-sourcing has been utilized to develop maps of landcover and land-use



- Dr. Angela Bedard-Haughn University of Saskatchewan
 - Overviewed the predictive mapping work being done in Saskatchewan and the factors driving this work
- Mr. Xiaoyuan Geng Canadian Soil Inventory System (CanSIS)/Agriculture and Agri-Food Canada
 - o Overviewed the current perspective on soil mapping at the national level
- Mr. Chuck Bulmer BC Forests, Lands and natural Resource Operations
 - Described how predictive mapping is being used in parts of BC
- Dr. Tom Hengl EnvirometriX / Open GeoHub
 - Provided a high-level overview on the state-of-the art practices for developing machine learning models to predict soil properties
 - Overviewed the costs of doing this kind of mapping
 - Described the opportunities available to Alberta as a result of all the high-resolution remote sensing data now available

CITATION

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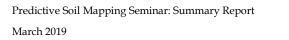




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ACKNOWLEDGEMENTS

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The authors thank Sarah Thacker, InnoTech Alberta, for taking notes during the sessions and monitoring the online input from the webinar participants. We would also like to thank all of the individuals who have contributed to this initiative thus far including the individuals who have served on our technical advisory committee (Len Leskiw, Bob MacMillian, Tony Brierley, Bruce Walker, Chris Powter, Lynette Esak, and Larry Nikiforuk) and the individuals from the environmental consulting companies (Golder Associates, Stantec, Paragon Soil and Environmental Consulting, and Matrix Solutions Inc.) who are interested in actively participating.



ACRONYMS USED IN THIS REPORT

AAFC	Agriculture and Agri-Food Canada
AfSIS	Africa Soil Information Service
AGRASID	Agricultural Region of Alberta Soil Inventory Database
AI	Artificial Intelligence
ALOS	Advanced Land Observing Satellite
API	Application Programming Interface
BMP	Best Management Practices
CanSIS	Canadian Soil Inventory System
CDEM	Canadian Digital Elevation Model
CLI	Canada Land Inventory
CLORPT	CLimate, Organisms (including humans), Relief, Parent material or geology, Time
CSM	Conventional Soil Map / Mapper / Mapping
DEM	Digital Elevation Model
DGG	Discrete Global Grid
DMP	Dry Matter Productivity
DSM	Digital Soil Map / Mapper / Mapping
DSS	Detailed Soil Survey
EGS	Ecological Goods and Services
EML	Ensemble Machine Learning
EthioSIS	Ethiopia Soil Information System
FORASIS	Forested Region of Alberta Soil Information System
FPAR	Fraction of Photosynthetically Active Radiation
FTIR	Fourier-transform Infrared (spectroscopy)
GDAL	Geospatial Data Abstraction Library
GIS	Geographic Information System
GSIF	Global Soil Information Facilities
HPC	High-power Computing
ISRIC	International Soil Reference and Information Centre
LHS	Latin Hypercube Sampling
LiDAR	Light Detection and Ranging



LWBSF	Lake Winnipeg Basin Stewardship Fund
MIR	Mid-infrared
MLA	Machine Learning Algorithm
MODIS	Moderate Resolution Imaging Spectroradiometer
MRVBF	Multiresolution Index of Valley Bottom Flatness
ND	No Data
NDVI	Normalized Difference Vegetation Index
O&M	Observation and Measurement
OK	Ordinary Kriging
PCA	Principal Component Analysis
PEM	Predictive Ecosystem Map / Mapper / Mapping
PPR	Prairie Pothole Region
PSM	Predictive Soil Map / Mapper / Mapping
REML	Residual Maximum Likelihood
RF	Random Forest
RFsp	Random Forest spatial
RK	Regression-kriging
RoI	Region of Interest
RPA	Remotely Piloted Aircraft
RS	Remote Sensing
RSA	Remote Sensing Application
RT	Regression Tree
SAR	Synthetic-aperture Radar
SCORPAN	Soil, Climate, Organisms, Relief, Parent material, Age, N (spatial or geographic position)
SKSIS	Saskatchewan Soil Information System
SLC	Soil Landscapes of Canada
SMAPVEX	Soil Moisture Active Passive Validation Experiment
SNMZ	Soil Nutrient Management Zone
SOC	Soil Organic Carbon
SRTM	Shuttle Radar Thirty Metres
SVAECP	Soil Variability Analysis to Enhance Crop Production
SVM	Support Vector Machines

UAV	Unmanned Aerial / Autonomous Vehicle
UK	Universal Kriging
WG-DSM	Working Group on Digital Soil Mapping
WLS	Weighted Least Squares
XRF	X-ray Fluorescence



PREDICTIVE SOIL MAPPING SEMINAR: Summary Report

BONNIE DROZDOWSKI, CRAIG AUMANN AND CHRIS POWTER

1.0 INTRODUCTION

Traditional soil mapping has been conducted in Alberta for decades and has provided valuable information to support industrial development plans and regulatory oversight. However, recent advances in remote sensing, modelling and data processing capabilities have produced opportunities to develop soil maps cheaper, faster, more effectively, and with greater reproducibility. Predictive Soil Mapping (PSM) is a suite of tools that can streamline the entire soil mapping workflow – from sample design, to efficiencies in field data collection, field sampling, identification and numbering of samples from initial site ID, through lab processing to database entry, and finally to map production.

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The long term goal is that FORASIS be used as resource tool that fills these gaps and thereby assists industry and government in making land management decisions at regional, local and/or operational scales.

A Predictive Soil Mapping Seminar was held at the InnoTech Alberta facility in Edmonton on March 6, 2019 and was also accessible through a webinar to invited participants. A total of 148 people had registered to participate in the Seminar (see Appendix A for the list of registrants).

1.1 WORKSHOP OBJECTIVES

The objective of the seminar was to develop a collective understanding of the benefits and opportunities of Predictive Soil Mapping (PSM) as they relate to Alberta. It was not intended to be a high level training session in PSM; rather, it was intended to be an introduction to highlight the benefits and advantages offered by PSM in comparison to conventional soil mapping methods. The key questions that the organizers wanted answered were seeking answer for include:

- At a high-level, how does PSM work?
- How good are PSM maps today? While "accuracy" has certainly improved with the new statistical techniques, are things "good enough" now, or are we still waiting for additional



technical developments so that things become "good enough"? That is, is PSM ready for commercial use to support the needs of government, industry and other end users?

- What are the risks of using predictive mapping systems in decision making?
- What opportunities do predictive maps open up that we couldn't do before?
- What does PSM cost generally?
- What are others around the world doing around predictive soil mapping? Are they having successes? And how are they defining "success"?
- What is the value proposition for potential funding agencies in any further work (cost, speed, regulatory acceptance), and what are the potential downsides to doing the work (e.g., a limited talent pool to carry out the work in a PSM world, etc.)?
- What will convince regulators to shift from status quo to a new way of doing things (accuracy, reproducibility, within the current range of natural variability they already accept, previously adopted in other fields they are familiar with, etc.)?
- What will the shift to PSM do to consulting business models, how can they defend the PSM results (to clients, regulators, and stakeholders), and what training / expertise will they need to hire?

1.2 SEMINAR AND REPORT STRUCTURE

The Seminar consisted of six presentations given by five invited speakers, with opportunities to ask questions (see Appendix B for the Agenda and Appendix C for the presentation materials). The speakers included:

- Dr. Angela Bedard-Haughn University of Saskatchewan (UofS)
 - Associate dean of research and graduate studies and professor at the U of S focusing on applied pedology. Angela is a key collaborator in the Saskatchewan Soil Information System (SKSIS) project. She provided an overview of the project and some lessons learned.
- Dr. Chuck Bulmer BC Forests, Lands and Natural Resource Operations
 - Soil scientist with 25 years of experience evaluating rehabilitation efforts on sites disturbed by forestry and oil and gas development. His work has led to improved methods for evaluating soil compaction status and implications for site productivity. Recent work has included high resolution air photos to support soil conservation and monitoring, as well as improving BC's digital soil inventories using GIS technology and modeling to enhance the use of digital soil datasets in resource planning and operations.
- Mr. Xiaoyuan Geng Canadian Soil Inventory System (CanSIS)/Agriculture and Agri-Food Canada
 - Scientist whom has been conducting R&D in the field of PSM for nearly a decade and is the lead on Soil Landscape Canada data development and renewal. He provided an update on national PSM activities.
- Dr. Tom Hengl EnvirometriX / Open GeoHub
 - Over 20 years of experience as an environmental modeler, predictive soil mapper, data scientist and spatial analyst. Tom has published more than 50 journal articles and several textbooks in the fields of geo-information science, PSM and spatial statistics.



He currently leads production of the Global Open Land Data System LandGIS (<u>https://landgis.opengeohub.org</u>), which includes soil properties and classes. Tom reviewed the status of technologies for PSM and suggested possible development directions in Alberta.

- Dr. Robert (Bob) MacMillan LandMapper Environmental Solutions Inc.
 - A retired environmental consultant with over 40 years of experience in creating, packaging, delivering and using environmental information on soils, ecosystems, landforms and hydrology. Bob spent 20 years working in public sector research and soil survey with Agriculture and Agri-Food Canada and the Alberta Research Council and then a second 20 years as a consultant offering services in predictive soil and ecological mapping. Since retiring, Bob has remained an active supporter, promoter, advocate, mentor and technical contributor to various projects to advance the science and technology of mapping soils and other ecosystem components.
- Dr. Markus Walsh Agriculture and Food Security Center, Earth Institute, Columbia University
 - Over 25 years of experience in ecosystems and landscape ecology research in Africa. For the last decade he has focused on developing operational tools for diagnosis, mapping and monitoring with an emphasis on the application of IT and data science. Markus provided insights into the lessons learned from initiating a soil inventory system in Africa and the importance of collecting new data appropriately and efficiently.

The following sections provide the highlights of each presentation and a summary of the questions posed by the participants.



2.0 PRESENTATIONS AND DISCUSSIONS

2.1 SHIFTING FROM TRADITIONAL TO PREDICTIVE SOIL MAPPING (PSM) – DR. ROBERT (BOB) MACMILLAN

The Universal Model of Spatial Variation (close things are similar and far things are different) underpins PSM. The Universal Model of Soil Spatial Variation has three parts:

- Deterministic can be captured by conceptual model (e.g., expert knowledge, or existing soil maps) or statistical models which are data-driven (e.g., elevation or other soil forming factors) and objective and provide a parameterization of these deterministic components.
- Stochastic has spatial structure; analyses effect of distance by creating a variogram and interpolating via kriging (traditional mappers do this manually by drawing lines around similar soils or values)
- Error (noise unstructured so can't interpolate or predict it).

Predictive models range from linear regressions (simplest), non-linear regression, trees and random forest or other machine learning models (most complex). The output from machine learning models represents the mean of many models (ensemble).

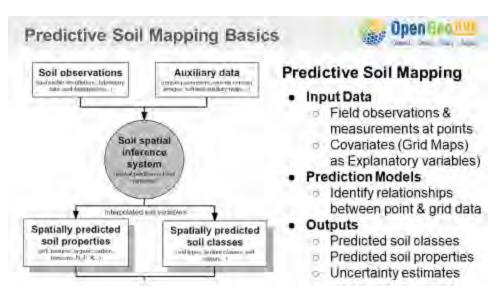
It is important to remember that different environmental properties operate at different scales and therefore require data at different scales; these data must be brought to a common scale to be used in the models. There are different methods of scaling covariates, each with their own advantages and disadvantages.

Predictive soil mapping involves three components: inputs data, prediction models, and outputs. The key differences between conventional maps and predictive maps are shown in Table 1.

Conventional Map	Predictive Map
Based on expert judgement	Data driven
Subjective	Objective
No two alike	Reproducible
Static maps	Minimize error
Very difficult to map	Best fit to available data
changes	Multiple runs
Can't update easily	Easily updated
One and done	Get new data
Have to return to field and	Rerun models
redo to update	Get new maps

Table 1.Difference between conventional and predictive maps.





Question Period

Q: How do kriging maps work with cross validation, etc.?

A: Better in terms of spatial detail. One camp wants model-based interpretation and insight, while the other is only interested in the accuracy of the predictions. Machine learning can accomplish spatial kriging, so you don't need the regression kriging per se. Relatively easy to do cross validation with machine learning.

Q: Expand on Gaussian pyramid, what does it mean?

A: Take variables that operate across different spatial scales (e.g., climate, digital elevation model, coarse and fine satellite imagery) and resample these variables to the finest resolution. Machine learning models can determine which variables at which resolution work the best for the predictions one is trying to make.

2.2 LESSONS LEARNED: WHAT'S BEEN TRIED; PROBLEMS AND SOLUTIONS FOR UTILIZING PREDICTIVE SOIL MAPPING – DR. MARKUS WALSH

A workflow overview of the African Soil Information System (i_4^A Information for Agriculture) was provided along with an overview of the need for predictive mapping systems, lessons learned regarding methods, and processes implemented to increase efficiencies and reduce costs. Dr. Walsh provided the context for where they are currently monitoring various parameters within the photosynthetically active "region of interest" (RoI) in Africa to develop a process-level understanding about agricultural nutrient cycles at national and continental scales.

The AfSIS Information for Agriculture (i_{4}^{A}) workflow (which is a process for PSM) consists of the following steps:

1. Determining what information products end-users actually need. Revisit this step frequently!



- 2. Rapidly assess agricultural system distributions in a region of interest (RoI) with GeoSurvey. [GeoSurvey is a tool provided online at <u>https://geosurvey.qed.ai/about/</u>]
- 3. Apply spatially and temporally balanced sampling to identify field survey and experimental locations
- 4. Use MobileSurvey (which operates on hand-held phones) to log field observations, experiments and the associated physical samples. This creates a universal unique ID which allows sampling tracking throughout the entire process
- 5. Analyze all rock, soil, plant and livestock biomarker samples with high throughput lab methods. There are currently 17 spectral labs across Africa
- 6. Predict and monitor system state variables with machine learning and geostatistical models

Steps 1 to 5 apply to new data being collected while steps 1 and 6 apply to all samples (legacy data and new data). Several examples of applications were provided as well as links to access data and additional information. One excellent example of the above process is the Soil Nutrient Management Zones which provide fertilizer recommendations based on the maps generated. This information was then combined with nutrients measured from plant tissue and a comparison was made for nutrients in soils to nutrients in plants to assess variability in nutrient uptake based on the soil variability.

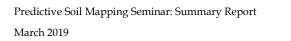
Strengths of the i_4^A system include: field data recorders (phone, tablet) for simple data entry; single QR coded samples that can be tracked from field to lab to database to map; simple tool to select regions of interest for sampling based on presence/absence information gleaned from remote sensing images; use of mid-IR and XRF spectrometers (measuring elemental profile of sodium to uranium on periodic table) – so they can obtain nutrients and soil pollutants, heavy metals, and soil geochemistry quickly and cheaply (a few dollars per sample). Hand-held devices used in the field can obtain similar information and are calibrated based lab-analyzed data. All data is publicly accessible.

Challenges in monitoring and producing maps for large, remote areas such as many areas in Africa include: site accessibility, field expenses, power sources for labs, variation among reference laboratories in analytical methods and quality control, consistency of measurement methods over several years to decades, and geo-referencing for repeat sampling.

The products produced are not static maps, but really a monitoring system tool that allows them to generate predictions about the ecosystems they work over time as more data is collected, and forecast where changes are likely to happen.

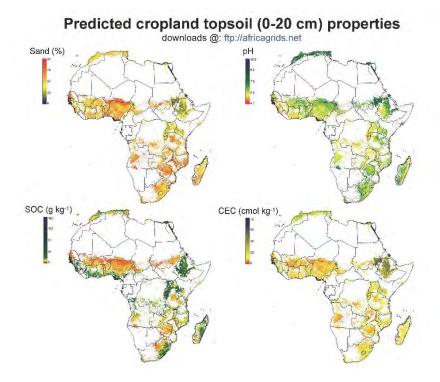
Some key messages:

- It is important to collect new data to continue to input into the models so can monitor changes with time.
- Unique sample ID's assigned to samples right in the field decrease error substantially.
- Laboratory analysis methods and QA/QC need to be consistent. Costs can be reduced substantially be eliminating the need for wet chemistry analysis (or reducing the quantity of samples requiring it).





• Publicly funded data collection should mean that this data is publicly available (point observations, grids and models).



Question Period

Q: When using mobile field data collection, do you collect anything on paper? Ever lose data? If I want to do it, how can I avoid pitfalls?

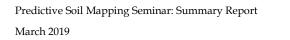
A: Yes, can lose data. But, it is critical to collect data electronically. Like to be in and out of a site in <10 minutes to collect 20 cm deep soil sample; this would make paper collection difficult.

Q: How sensitive and how practical is handheld equipment? Concerns with colour, drying, homogenization – does that happen as well in the field?

A: Maybe not for all areas, but very promising. People working on calibrations to adjust for moisture content, homogenization issues, etc. MIR is the really promising technology.

Q: Things change quickly in Africa. In 5-10 years, cropland use could have changed (i.e., due to development). How do you capture these changes and prepare for these unpredicted changes?

A: We cannot remap all of a country or the entire continent every year. Need new GeoSurvey data and updated high resolution satellite information to investigate where land cover changes are happening most rapidly. Working with a group called Radiant Earth (specialize in providing scientists with high res, high quality, time stamped, satellite info) to try to answer these questions.





Q: Focus is monitoring crops, predict yields, crop nutrients. We use spectroscopy now. We could just use soil spectroscopy to predict yields and skip all the soil science. Thoughts?

A: Things should proceed in parallel. We want to understand soils, but also make the best crop predictions possible. We need both.

2.3 SASKATCHEWAN SOIL INFORMATION SYSTEM (SKSIS) – DR. ANGELA BEDARD-HAUGHN

Predictive soil mapping has tremendous potential for enhancing the quality of soil information everywhere, however, there is a need to identify methods that allow mappers to work with (and integrate) the strengths of legacy soil data, overcome the challenges of large spaces/coarse datasets, and create opportunities for soil maps to enhance land management. Saskatchewan Soil Information System (SKSIS) is the platform to make the data available (similar to Alberta's AGRASID).

Challenges have been identified with converting legacy data into raster format for current applications due to issues around format and scale. Predictive soil mapping provides the opportunity to utilize the data using disaggregation and machine learning techniques to remap soils at higher resolutions. Some key considerations in PSM is the quality and quantity of the input data. In general, the more data that goes into the model, the better the information that comes out in terms of the uncertainty associated with the prediction. Predictive soil mapping builds on the key soil forming factors described by Jenny (1994) and Ellis (1938 Soils of Manitoba). S = f(cl, o, r, p, t, h, gw). Due to the inclusion of the influence of ground water, Dr. Bedard-Haughn prefers to refer to Joe Ellis' soil forming factors which determine soil type as:

- 1. The climate, or the temperature and moisture within the soil;
- 2. The vegetation, which determines the type of organic matter added to the soil;
- 3. The parent material, or the geological deposits which determine the minerals on which the soil is formed, and in turn affect the texture, the water retention capacity, and the mineral reserve;
- 4. The position in which the soil is found in relationship to the topography;
- 5. The presence or absence of ground water within the soil profile;
- 6. The age or length of time the soil has been under the influence of its environment;
- 7. In the case of cultivated soils the modifying effects of culture or the work of humans.

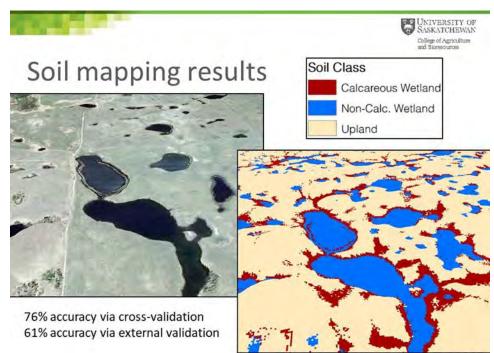
Conventional soil mapping was knowledge driven which requires one to understand the landscape and the conditions within which a soil has formed. To quantitatively predict soils with a data driven approach (as is the case with predictive soil models) it is essential to have high quality digital elevation models and input layers. It is important to recognize that just because a variable can be included doesn't automatically mean it should – focus on the covariates/predictor variables that are really necessary to interpret the output. It is also very important to know the limitations of the dataset.

Despite there being more soil information collected and precisely georeferenced via GPS than at any other point in history, predictive mappers struggle to have enough point data to carry out large-scale mapping efforts; still need to do a fair bit of field work to train the computer, so critics ask what the PSM advantage actually is. Need to be ready to address this question.



Key Messages

- Their approach to PSM is to build on the strengths, overcome the challenges, and take advantage of opportunities:
 - o Strengths: Legacy data, conceptual model, computing power and creativity
 - o Challenges: Spatial data resolution, obstacles to data sharing
 - Opportunities: Use emerging technologies and data sharing to enhance legacy data
- Errors within the DEM or co-variate data can cause compounded errors within predictive soil maps, thus QA/QC is essential
- More [quality] data that can be used in the model, the better the outputs
- Essential to identify WHY and WHAT. What is the desired outcome and why do you need/want to create predictive soil maps



Jeremy Kiss MSc thesis, Fall 2018

Question Period

Q: Challenges with data sharing – any ideas for working with private entities sitting on a lot of soils data?

A: Having conversations with soil testing and agronomy companies currently. People fear how data might be used, trust issues. Soil testing folks most open to census based approach, where data shared more broadly in an aggregated form (i.e., in SKSIS), but primary, individual data would not be available to everyone. It's about providing the security people want before they will share the data. Agronomy people: variability in peoples' willingness to share. Comes down to the purpose of the data.



Comment: Data shared in aggregate could work in Alberta, through an AGRASID-type platform. Contaminants probably can't be shared or would only be available to certain users.

Comment: Issue of not having fine scale data. There is an opportunity in not having fine scale data. We all talk about bottom up mapping (start at fine scale and move up), but why not top down (i.e., from coarse to finer scales)? There are advantages in top down. And it gives context (upland ponds versus lowland ponds). Don't be overly committed to idea that best data is finest data.

A: Yes, in landscapes where our conceptual models are not very refined or we don't know a lot about the land. Agricultural regions: scale focused on the users that want the info and coarser info is not what they want/need. From top down, finer features can get missed. Should consider: why are you doing soil mapping and what is the desired outcome? That determines what data you are putting in. As their work is with Ag people, focus more on fine scale because that better meets end-use needs of clients.

2.4 PREDICTIVE SOIL MAPPING – NATIONAL PERSPECTIVE – MR. XIOYUAN GENG

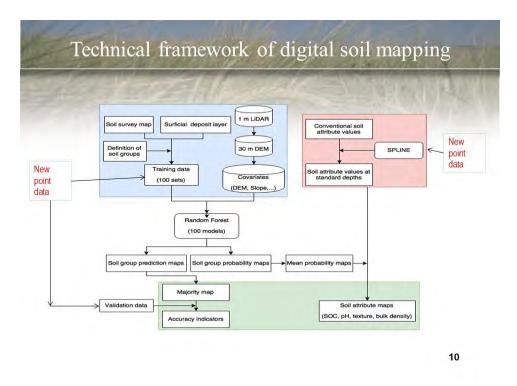
There are international, national and regional drivers for federal involvement in PSM. Soil and landscape data can be useful for a number of activities, including: Infrastructure, environment and watershed management, soil management, risk management; best management practices research, development and evaluation; precision agriculture, biodiversity etc.; and environmental goods and services measurement and assessment. Soil changes and information renewal is critical.

From Agriculture and Agri-Food Canada (AAFC)'s perspective, digital soil mapping is a costeffective way to develop soil data, particularly at a higher resolution. AAFC is working towards a global and national database to develop higher resolution regional digital soil maps for a variety of applications, examples of which were provided. Particularly useful for land management decisions. Primarily focused on the agricultural regions of Canada with the intention of linking to precision agriculture, phenomics, resiliency metrics and soil microbiome initiatives. They will be advancing the national soil database structure by adding business driven attributes including soil total phosphorus and soil metagenomics.

Key Messages

- Data structure at different scales and resolutions causes different challenges in terms of its use in large national inventories
- Legacy soil data may need to be re-grouped to be classified by "drainage, slope, catena, etc." rather than "names"
- Need to be clear about what the desired outcome is
- There is an optimal number of samples required for the outcomes you are looking for
- We need to maximize the use of legacy soil data (by disaggregating, for example ecodistrict by eco-district, into vector based data)



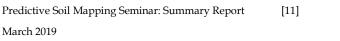


2.5 PREDICTIVE MAPPING IN BEAUTIFUL BRITISH COLUMBIA - DR. CHUCK BULMER

The BC Soil Information Finder Tool (SIFT) provides access to soil survey data, reports and maps, predominantly from the agricultural regions of the province. "Hectares BC" provides access to digital mapping data layers (raster data) for the province, including: soil landscapes, soil parent materials, land use/cover, and topography. A variety of predictive mapping exercises at various scales have been undertaken in various regions. A 250 m resolution map of soil classes has been developed (article in preparation) which is being used as an input for carbon mapping.

Successes and challenges include:

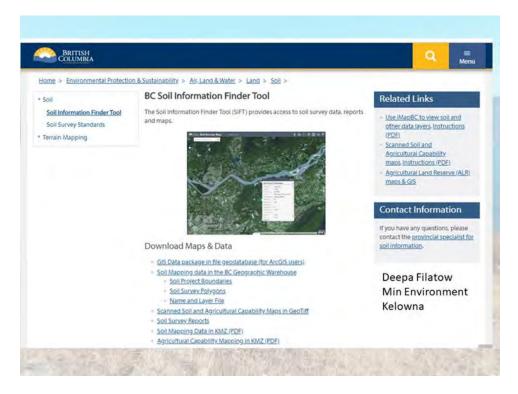
- ٠ Vector soil datasets are readily available for large parts of the province (SIFT)
- Need to define and organize existing data according to common rules and naming conventions for data and maps (e.g., is it colluvium or till)
- We've had some early success, and now trying to improve predictive maps
- Possible to represent common soil attributes directly without soil classes / names? ٠
- BC has rugged topography
 - lots of variation in relief factor of soil formation 0
 - but parent material and vegetation and other factors often vary in 'unpredictable' Ο ways
 - sometimes finer resolution maps are no better than coarse resolution 0
- LiDAR has great potential (about 10 20 percent of BC has LiDAR)
- We're getting better and building capacity •
- DSM is here to stay





Key Messages

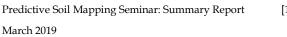
- Combination of very specific and/or general attributes easier to model and combine into complex interpretations (i.e., don't necessarily need soil names specifically it is important to be clear about what soil attributes you need)
- Parent materials are easier to map than "great groups" however when you combine the two you are very close to a soil map even in the absence of other soil attributes



2.6 ENSEMBLE MACHINE LEARNING AS A FRAMEWORK FOR PSM – DR. TOM HENGL

The objective of the presentation was to provide an introduction to machine learning for soil mapping (soil properties, classes, class probabilities, etc.) and to discuss the new developments and benefits associated with Ensemble Machine Learning (which include: maximizing accuracy/data processing automation; modelling of non-linear complex relationships; combining geography/feature space patterns without too many strict statistical assumptions). Dr. Hengl decided to structure his talk based on the list of questions from Dr. Craig Aumann and included:

- 1. At a high level, how does PSM work?
- 2. How good are PSM maps today?
- 3. Is PSM ready for commercial use to support the needs of government and others?
- 4. What are the risks of using predictive maps in decision making?
- 5. What opportunities do predictive maps open up that we couldn't do before?
- 6. What does this generally cost?
- 7. What are others around the world doing around PSM? Are they having successes? And how are they defining success?





Hengl and MacMillan (2019) is a good reference for introductory and advanced information.

Digital soil mapping and predictive soil mapping are different (see presentation for links to good resources such as the USDA Natural Resources Conservation Service Soils website):

Digital: "The creation and the population of a geographically referenced soil database generated at a given resolution by using field and laboratory observation methods coupled with environmental data through quantitative relationships."

Predictive: "The development of a numerical or statistical model of the relationship among environmental variables and soil properties, which is then applied to a geographic data base to create a predictive map."

Theoretically, PSM is largely based on CLORPT (Jenny, 1994). A conventional soil mapper (CSMer) knows how to draw polygon maps. The difference between a CSMer and a digital soil mapper (DSMer) is that a DSMer knows how to use GIS. The difference between a DSMer and PSMer is that a PSMer knows how to code (R, Python, Julia, etc.)! Modern PSM is largely based on using RS / proximal soil sensing / LiDAR and state-of-the-art Machine and Statistical Learning software (here focused on Open Source tools).

The objective of PSM is to produce optimal unbiased predictions of a mean value at some new location along with the uncertainty associated with the prediction, at the finest possible resolution. From the application point of view, the main application objective of soil mapping is to accurately predict response of a soil(-plant) ecosystem to various soil management strategies.

There are three main types of PSM projects:

- PSM projects in new, previously unmapped, areas no point observations or samples currently exist.
- PSM projects using legacy points sufficient point data to support PSM exist and are available, but no previous PSM modelling has been implemented for this area.
- PSM projects aimed at optimizing predictions and usability previous PSM models have already been completed but previous results can still be improved / optimized.

The costs for the various types of PSM projects have been estimated based on a variety of factors. The costs are typically a function of the size of the area (spatial resolution), the total number of samples/points, the total number of variables and the distance that needs to be crossed to visit all points. Other projects can be developed with a different cost structure based on the intended outcomes. Another way of classifying PSM projects is by purpose:

- PSM projects for the purpose of mapping static (stable) spatial patterns only.
- PSM projects for the purpose of one-time change detection (e.g. two time intervals).
- PSM projects for the purpose of monitoring soil conditions / status (continuous updates at regular intervals).

A good resource to evaluate the costs associated with PSM is Hengl et al. (2013).

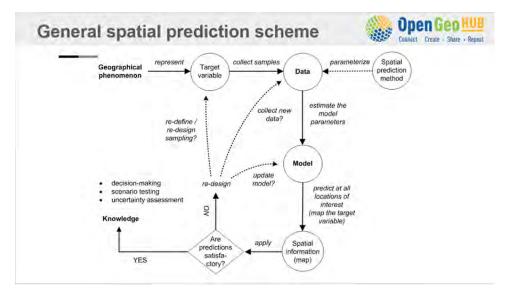
One attractive framework to generate spatial predictions is the Ensemble Machine Learning (see e.g., SuperLearner, caret, mlr, h20 modeling frameworks for the R statistical language). By including geographical distance in the Machine Learning model, we can "elegantly" replace traditional geostatistics (kriging). Overall, it is scary how much we could automate generation of

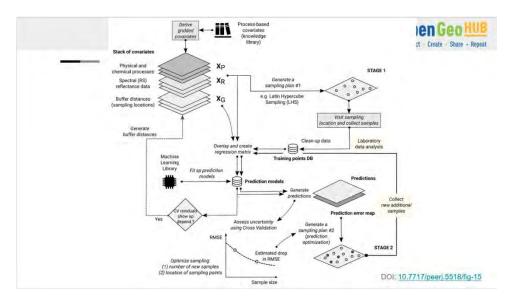


soil maps today, but that does NOT mean that: (a) we should stop sampling, (b) we do not need to learn/understand stats or soil science any more, or (c) that we need to stop coding.

Predictive soil mapping at a high level consists of two steps (which may be done iteratively in a second phase):

- Step 1: Observations coming in need to be verified with expert data and linked to covariates.
- Step 2: The model needs to be calibrated (generally better if multiple models are being applied as is done with Ensemble Machine Learning). If the model and predictions are satisfactory, you can stop and use the information for the intended purposes. If the model is not providing satisfactory predictions you repeat these steps in what becomes Phase 2. These steps can continue with additional data, a different/updated model, and/or new/different covariates until satisfactory outcomes can be developed (see slides below).







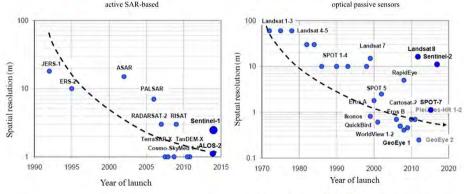
2.7 TECHNOLOGICAL AND METHODOLOGICAL ADVANCES IN SOIL MAPPING AND MONITORING AND OPPORTUNITIES FOR ALBERTA/CANADA – DR. TOM HENGL

The presentation focused on advancing technologies, lessons learned from previous efforts, and which new application areas could benefit Alberta the most. The intent was to initiate discussion around how to leverage the current "big data" paradigm and how best to produce decision- and analyst-ready insight. Information was provided on the state-of-the-art remote sensing technologies and advancements in data resolution and availability. The impact of "free and open" data was highlighted. Examples were also provided where predictive data models did not accurately predict and the intended outcome could not be reached. Explanations for the unsuccessful examples included: high noise in the data, model parameters inaccurate, and cloud cover. A suite of advancements in new global data releases, "active"-type sensing and technologies for measuring soil properties were provided (Table 2).

Monitoring	Processing
Public-access, high-res Space Sentinels, ALOS, Landsat 8, TANDEM	Online geospatial data workflows R-spatial (plumber), GeoTrellis DB, Cloud Optimized GeoTIFF
Commercial "NewSpace" Very fast system design/launch Data- or Intelligence-as-a-Service	Permanent data storage Digital data instantly accessible, unalterable, uncensorable
UAV fleets With LiDAR + radar + hyperspectral Data- or Intelligence-as-a-Service	Scalable computing infrastructure Diverse data storage/processing solutions as- a-Service
Integrated sensor networks (meteo, soil, acoustic)	

Table 2.Promising technologies summary.



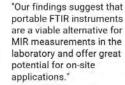


source: https://doi.org/10.1016/j.asr.2015.10.038



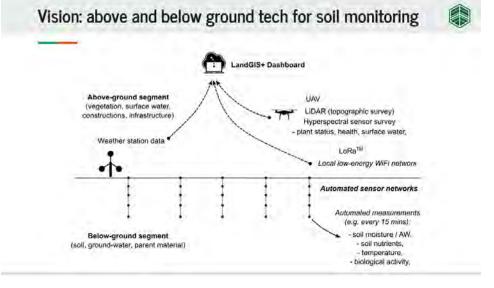
Soil spectroscopy

Figure 2. MIR spectrometers used in this study: (a) Bruker Tensor 27 bench-top instrument with EasyDiff diffuse reflectance accessory (back, in the sample compartment) and Ulbricht sphere (front); (b) Agilent 4300





Handheld FTIR measurement with custom sample cup.



The following key conclusions were provided:

- More data available, but that does NOT mean easier mapping procedures (in fact we're in danger of being overwhelmed)
- Very promising new technologies for soil science: "IoT" sensor nets, LiDAR, Sentinel-1,2,5, ALOS
- Single sensor → multi-sensor fusion;
 Single mission → multidisciplinary projects;
 Single model → Ensemble models;
- Machine Learning is increasingly available! Use it!

The following opportunities for Alberta (Canada) were noted:

• Large areas = leveraging RS is crucial (UAVs maybe not the best option for now?)

- Set-up automated sensor networks (weather, micro-weather, soil moisture, soil pollution...)
- On-demand web services: warning, spatial planning, scenario testing systems
- Next standard: hyper-resolution mapping 1–5 m
- Cloud / HPC solutions for geospatial processing GIS data (start with Open Source!)

Question Period

Q: My sense is there is a lot of noise in remote sensing. Can you suggest some of the ways you have dealt with that?

A: Take a time series, average that data for each month over 10 years (for example). So now you have a long term data set.



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3.0 COMMON THEMES IN PRESENTATIONS

The following common themes were identified during the presentations:

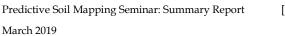
- 1. Ask what your users want (information and scale), and ask frequently PSM is about the user not the mapper!
- 2. As a visible end-product, the maps are important but the workflow, models and data underpinning the maps are the key to success.
- 3. To the extent possible, data and models should be public.
- 4. Once the first map is generated it creates opportunities for people to ask "what if …" and "could we …" questions that will spur new products and innovations.
- 5. Residual error maps allow for targeted sampling campaigns to focus on areas where there is high variability and/or missing data.
- 6. More data is better, but the right data in the right places is even better use data that are relevant to the question being asked.
- 7. Legacy data still have value incorporate them wherever possible.
- 8. Incorporating remote sensing tools and products will be the next big step in producing PSM.
- 9. Dynamic maps, showing trends over time, are the next big advance in PSM products.
- 10. PSM models are not black boxes they are based on long-accepted soil-landscape principles going back to the 1940s.
- 11. Current technology offers opportunities to harness citizen science to vastly increase sampling capabilities.



4.0 APPLYING THE LEARNINGS TO FORASIS

After the presentations participants were given the chance to provide advice and comments relative to application of Predictive Soil Mapping in Alberta's Green Area (i.e., the FORASIS project). The majority of the discussion was centered on data availability and sharing. The following points were raised.

- Soils gets some money for research in BC, but ecology gets more (likely because of relationship to forestry). Potentially consider forest inventory work and forest fire planning in the green zone and forestry companies as end users.
- Soil moisture is a key issue.
- Question is, is it a lack of quality data or a lack of availability of data? Wonder how much info is sitting on consultant's desks. Industry could cut down on amount of sampling to save cost would be a benefit of FORASIS, open data.
- Point field observations where do they end up? Do they die after report submitted to regulatory body? Lab data must have been in a digital format anyway. We collect the data for private companies, but then it is THEIR data. We don't own the data. So don't look at consultants for data.
- Needs to be a central data home for soil point data.
- So who has opportunity and ability to make it available? It would be good enough to know which companies how much data, in what area, etc. Maybe don't need all the data. Maybe then someone can offer to pay to see the actual data?
- Industry wants to reduce sampling cost. Having a standard in place for how data is reported would make it easy to access and use, potentially. Brings together private sector and public sector entity managing and maintaining that data.
- Could a soil mapping system look like the AB Wetland Inventory for mapping wetlands? Could that framework be applied to soils? Should be shared management approach.
- Environmental Site Assessment Repository (Alberta Environment and Parks) has reports that public can access, and would have soils info. Again, client, decides if that info goes into the repository. Landowners may also need to authorize accessing info from reports on their land. Site assessment data may not always be typical soil survey data.
- Seems like a failure to communicate. We should collect all point data. If government makes a regulation saying all data must be collected, then everyone has to do it. Doesn't all have to be made publicly available. But then that data could be used for things such as a predictive soil map. There is a new directive for renewable energy projects that gives AEP room to do this. If industry wants to reduce sampling cost, then it would mean moving in the direction of making more data available. Make data more accessible at a cost.
- Someone could just go out and start taking points. Show the way, show an example of the value of this PSM. This could trigger response to share data.





- I would like to return to original question. Who is the user of FORASIS? Could inform who will put in info, etc. It's not AGRASID extended into the Green Area. It can be used for pre-disturbance assessment, etc. useful for consultants and such who need this sort of info for the Green Area.
- What would the disclaimer to the dataset look like? People want to be skeptical about predictive maps. But the same scrutiny is not applied to conventional maps. Conventional maps certainly have data errors, but there is a general sentiment that "my map is the best map" which prevents people from embracing new methods.
- What you put into the model may not have had QA/QC done. This is accounted for in the prediction error. Can do repeated sampling, nested sampling to reduce error. Can't report higher precision than what you can actually achieve.



5.0 ADDITIONAL RESOURCES

5.1 DOCUMENTS

Aumann, C., 2017. Predictive Soil Mapping Pilot in NE Alberta. Prepared for Alberta Biodiversity Monitoring Institute, Edmonton, Alberta. 37 pp. plus appendices. <u>https://ftp-public.abmi.ca/home/publications/documents/535_Aumann_2017_PredictiveSoilMapping_A</u>BMI.pdf

Fawcett, M.D., W.L. Nikiforuk, R.L. McNeil and R.A. MacMillan, 1993. An Evaluation of the Extrapolatory Method of Soil Mapping. Environmental Research and Engineering Department, Alberta Research Council, Edmonton, Alberta. Alberta Research Council Open File Report 1993-09. 69 pp. <u>https://ags.aer.ca/document/OFR/OFR_1993_09.pdf</u>

Hengl , T., J. Mendes de Jesus, G.B.M. Heuvelink, M.R. Gonzalez, M. Kilibarda, A. Blagotić,
W. Shangguan, M.N. Wright, X. Geng, B. Bauer-Marschallinger, M.A. Guevara, R. Vargas,
R.A. MacMillan, N.H. Batjes, J.G.B. Leenaars, E. Ribeiro, I. Wheeler, S. Mantel and B. Kempen,
2017. SoilGrids250m: Global Gridded Soil Information Based on Machine Learning. PLoS ONE
12(2): e0169748. <u>https://journals.plos.org/plosone/article?id=10.1371/journal.pone.0169748</u>

Hengl, T. and R.A. MacMillan, 2019. Predictive Soil Mapping with R. OpenGeoHub Foundation, Wageningen, The Netherlands. 370 pp. ISBN: 978-0-359-30635-0. https://envirometrix.github.io/PredictiveSoilMapping/index.html

Hengl, T., M. Nikolić and R.A. MacMillan, 2013. Mapping Efficiency and Information Content. International Journal of Applied Earth Observation and Geoinformation 22: 127-138.

Heung, B., 2017. Regional-Scale Digital Soil Mapping in British Columbia using Legacy Soil Survey Data and Machine-Learning Techniques. Ph.D. Thesis. Department of Geography, Simon Fraser University, Burnaby, British Columbia. 164 pp. http://summit.sfu.ca/system/files/iritems1/17377/etd10172_BHeung.pdf

Nadeau, L.B., C. Li and H. Hans, 2004. Ecosystem Mapping in the Lower Foothills Subregion of Alberta: Application of Fuzzy Logic. The Forestry Chronicle 80(3): 359-365. <u>http://pubs.cif-ifc.org/doi/pdf/10.5558/tfc80359-3</u>

5.2 WEBSITES

AfSIS Database - <u>https://qed.ai/afsisdb/</u>

Agricultural Region of Alberta Soil Inventory Database (AGRASID) – <u>https://www1.agric.gov.ab.ca/\$department/deptdocs.nsf/all/sag10372</u>

Alberta Data Partnerships (ADP) – <u>http://abdatapartnerships.ca/</u>

BC Soil Information Finder Tool (SIFT) -

https://www2.gov.bc.ca/gov/content/environment/air-land-water/land/soil/soilinformation-finder

Canadian Soil Information Service (CanSIS) – <u>http://sis.agr.gc.ca/cansis/</u>

Environmental Site Assessment Repository (ESAR) – <u>http://www.esar.alberta.ca/esarmain.aspx</u>



European Soil Data Centre (ESDAC) – DSM: Digital Soil Mapping – <u>https://esdac.jrc.ec.europa.eu/projects/dsm-digital-soil-mapping</u>

GeoDiscover Alberta – <u>https://geodiscover.alberta.ca/geoportal/catalog/main/home.page</u>

GeoSurvey - <u>https://geosurvey.qed.ai/about/</u>

GlobalSoilMap.org - <u>https://www.globalsoilmap.net/</u>

Hectares BC - <u>https://www.hectaresbc.org/app/habc/HaBC.html</u>

International Soil Reference and Information Centre (ISRIC) – <u>https://www.isric.org/</u>

OpenGeoHub - <u>http://opengeohub.org/</u>

Radiant Earth Foundation – <u>https://www.radiant.earth/</u>

Saskatchewan Soil Information System (SKSIS) – <u>https://sksis.usask.ca/#/map</u>

Soil_x – <u>http://www.soilx.ca/</u>

US Department of Agriculture – Digital Soil Mapping – <u>https://www.nrcs.usda.gov/wps/portal/nrcs/detail/soils/survey/geo/?cid=stelprdb1254424</u>

US Geological Survey – Digital Soil Mapping: High Resolution Maps for Modern Land Management Decisions – <u>https://www.usgs.gov/centers/sbsc/science/digital-soil-mapping-high-resolution-maps-modern-land-management-decisions?qt-science_center_objects=0#qt-science_center_objects</u>



APPENDIX A: LIST OF SEMINAR REGISTRANTS

The following people attended the March 6, 2019 Seminar at the InnoTech Alberta facility in Edmonton.

Name	Organization
Jaime Aguilar	
Murray Anderson	M.L. Anderson Advisory Services
Laurence Andriashek	Alberta Energy Regulator
Craig Aumann	InnoTech Alberta
David Bergstrom	Alberta Energy Regulator
Michael Bock	Government of Alberta
Scott Boorman	Paragon Soil and Environmental Consulting Inc.
Eldon Borgen	Paragon Soil and Environmental Consulting Inc.
Tony Brierley	
Christiane Brouwer	Golder
David Campbell	Forestry Corp
Chi Chen	Alberta Environment and Parks
Kimberly Cornish	Pachaterrae
Diana Dabrowa	Paragon Soil and Environmental Consulting Inc.
Kara Dallaire	Paragon Soil and Environmental Consulting Inc.
Sebastian Dietrich	University of Alberta
Konstantin Dlusskiy	Paragon Soil and Environmental Consulting Inc.
Becky Doherty	Forestry Corp
Lynette Esak	Esak Consulting Ltd.
Lane Feschuk	Paragon Soil and Environmental Consulting Inc.
Ted Furler	Stantec
Becca Gilroyed	Paragon Soil and Environmental Consulting Inc.
Claudia Gomez	Matrix Solutions
Reid Graham	Tree Time
Sanjay Gupta	



Name	Organization
Stephanie Hannem	Klohn Crippen Berger Ltd.
Jason House	Stantec
Javed Iqbal	Government of Alberta
Kyle Jones	Alberta Environment and Parks
Jahan Kariyeva	University of Alberta
Brian Lambert	Alberta Environment and Parks
Len Leskiw	Paragon Soil and Environmental Consulting Inc.
Barb Logan	Paragon Soil and Environmental Consulting Inc.
Derek Lonergan	
Ben Manshanden	Government of Alberta
Leon Marciak	Precedent Environmental Management Inc.
Jackie Maxwell	
Susan McGillivray	Alberta Environment and Parks
Larry Nikiforuk	SOIL-INFO LTD
Lekan Olatuyi	Alberta Environment and Parks
Claudia Palylyk	
Rashmi Pathak	ALS Global
Shane Patterson	Alberta Environment and Parks
Steven Pawley	Alberta Energy Regulator
Robbie Price	NorthWind Land Resources Inc.
Robert Proudfoot	
Jeff Reading	Pachaterrae
Steve Reed	SilvaComm
Thomas Romanowski	Sherritt
Jilene Sauve	Matrix Solutions
Ron Sawatzky	InnoTech Alberta
Colleen Shabada	SWAT Consulting Inc.
Preston Sorenson	Maapera Analytics Inc.
David Spiess	Alberta Agriculture and Forestry
Marcin Stanislawski	Golder



Name	Organization
Angela Taylor	Stantec
Sarah Thacker	InnoTech Alberta
Bruce Walker	
Don Watson	Alberta Environment and Parks
Marian Weber	InnoTech Alberta
Takele Zleke	Advisian

The following people registered to participate in the Seminar through a webinar broadcast.

Name	Organization ¹
Vaishalie Anand	Alberta Environment and Parks
Koreen Anderson	Alberta Health Services
Les Anderson	CCS Energy Services
Jose Armando Gomez	
Andrew Arnold	Summit Earth
Carlos Arregoces	Ecoventure Inc.
Christopher Bater	Government of Alberta
Kathryn Bessie	Tetra Tech Canada
Christopher Blackford	University of Toronto
Marla Bohm	Paragon Soil and Environmental Consulting Inc.
Atty Bressler	Wood PLC
Maxine Butler	
Luke Bye	Terex Environmental
Gayle Caltagirone	Tetra Tech Canada
Jennifer Canham	Weston Foundation
Christopher Chagumaira	
Nikki Chartrand	Secure Energy
Jeff Christisansen	Golder
Jill Clarke	
Helen Lynn Connally	



Name	Organization ¹
Burton Cosgrove	Integrated Environments (2006) Ltd.
Alexandra Dalton	
Michelle Dias	City of Calgary
Catrina Duffy	Solstice Canada Corp.
Leanne Erickson	Alberta Energy Regulator
Kahlie Forster	Stantec Consulting
William Gardin	
Yohannes Getachew	
Adam Gillespie	University of Guelph
Denise Gordon	Yukon Government
Travis Grant	
Tony Gregov	
Claire Gunoud	
Sarah Hall	
Sheldon Hann	
Lauren Harding	Matrix Solutions Inc.
Emily Herdman	Government of Alberta
Guillermo Hernandez Ramirez	University of Alberta
Brandon Heung	
Mitch Heynen	Yukon Government
Kirsten Horne	Terracon Geotechnique Ltd.
Tahmid Huq Easher	University of Guelph
Carolyn Inglis	
Stephanie Jaffray	
Ed Karpuk	Government of Alberta
Babak Kasraei	Simon Fraser University
Jaylene Kemp	
Karen Klimek	Agland Corp
Danny Lajoie	North Shore Environmental Consultants Inc.
Michael Lau	Volker Stevin



Name	Organization ¹
Dana Lee	McElhanney
Sarah Lepp	University of Guelph
Eduardo Loos	Vertex
Andrew Marcil	Jacobs
Hillard MacDonald	Core Geomatics
Joe Meaney	Suncor Energy
Tom Messier	
Symon Mezbahuddin	Government of Alberta
Brenda Nachtegaele	Strathcona County
Chris Newton	Ecoventure Inc.
Lindsay Oiffer	Matrix Solutions
Olusegun Oyewole	
Robert Palmer	
Karen Patz	
Colin Peters	Alberta Energy Regulator
Tyler Phillips	Teck
Carmella Pierce	Esker Consulting
Donald Poisson	
Matt Porter	Trent University
Clara Qualizza	
Fabrizio Re	SNC-Lavalin Environment Inc.
Mary Sarodub	
Daniel Saurette	Government of Ontario
Margaret Schmidt	Simon Fraser University
Kara Schwaebe	
Haylee Smysniuk	University of Saskatchewan
Karen Stals	Alberta Energy Regulator
Marcin Stanislawski	Golder
Taralee Stephenson	
Karen Trenholm-Boyle	

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Name	Organization ¹
Deanna Van Muyen	Reclaimit
Stephanie Vickers	
Tara Wang	Alberta Energy Regulator
Troy Wawrinchuk	Keneco Environmental Services (2000) Inc.
Ryleigh-Raye Wolfe	MacKenzie County
Ian Young	SLR Consulting
Jin Zhang	Simon Fraser University

¹ In most cases, organization was interpreted by e-mail address.



APPENDIX B: WORKSHOP AGENDA

Time	Topic	Speaker	
8:30-8:45 am	Registration and coffee		
8:45 – 8:55 am	Welcome, Introductions, and FORASIS Context	Bonnie Drozdowski	
8:55 — 9:15 am	Shifting from traditional to predictive soil mapping (PSM)	Robert (Bob) MacMillian	
9:15–10:30 am	Lessons Learned: what's been tried; problems and solutions for utilizing PSM	Markus Walsh	
10:30—10:45 am	Break		
10:45 – 11:30 pm	Saskatchewan Soil Information System (SKSIS)	Angela Bedard-Haughn	
11:30 – 12:00 pm	Predictive Soil Mapping – National Perspective	Xiaoyuan Geng	
12:00– 12:15 pm	Predictive Mapping in Beautiful British Columbia	Chuck Bulmer	
12:15 – 1:00 pm	Lunch (will be provided)		
1:00 - 2:15	Ensemble Machine Learning as a framework for PSM [the basics]	Tom Hengl	
2:15 - 3:30	Technological and methodological advances in soil mapping and monitoring and opportunities for Alberta / Canada	Tom Hengl	
3:30- 4:30	Closing Remarks, Questions, and Working Session	Craig Aumann and Chris Powter	



APPENDIX C: PRESENTATIONS

The following sections contain the presentation materials provided by the speakers.

Shifting from traditional to predictive soil mapping (PSM) - Bob MacMillan

<u>Lessons Learned: What's been Tried; Problems and Solutions for Utilizing PSM</u> – Markus Walsh

Saskatchewan Soil Information System (SKSIS) - Angela Bedard-Haughn

Predictive Soil Mapping - National Perspective - Xiaoyuan Geng

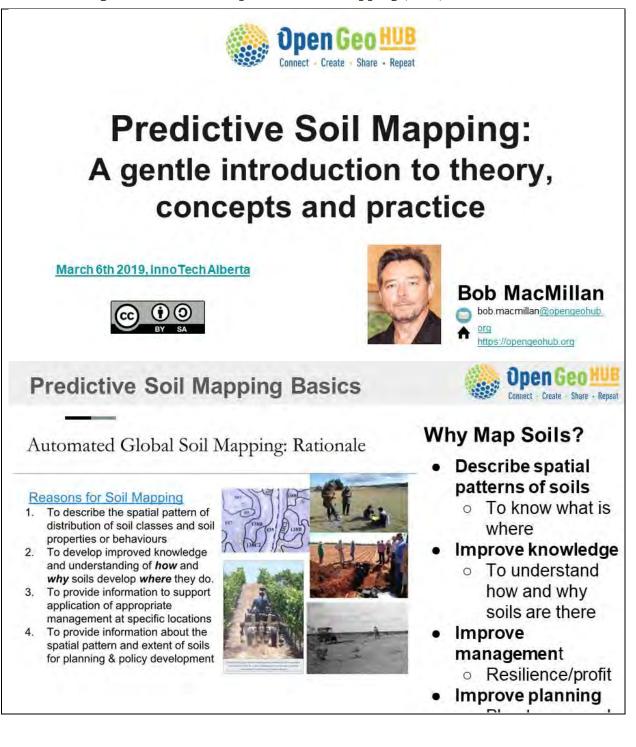
Predictive Mapping in Beautiful British Columbia - Chuck Bulmer

Ensemble Machine Learning as a Framework for PSM – Tom Hengl

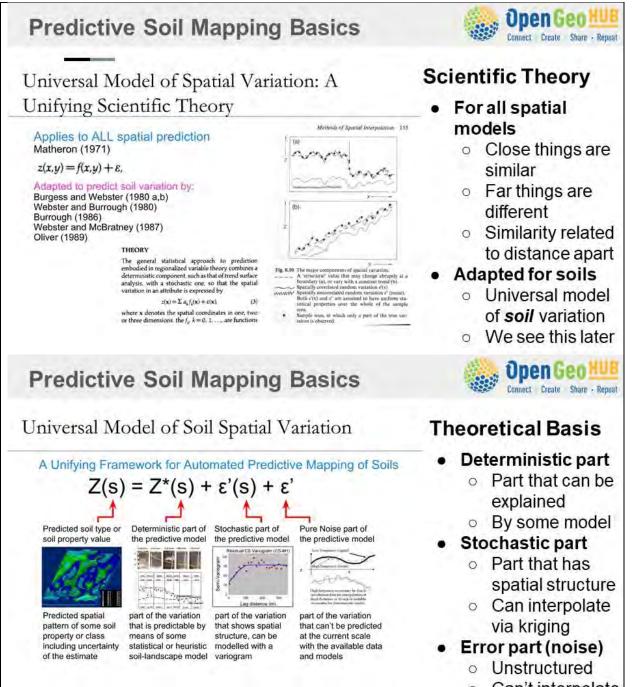
Technological and Methodological Advances in Soil Sapping and Monitoring and Opportunities for Alberta / Canada – Tom Hengl



Shifting from traditional to predictive soil mapping (PSM) – Bob MacMillan







Can't interpolate



Predictive Soil Mapping Basics

Deterministic Part of Prediction Model: Z*(s)



KLM S **DYD** Series **Conceptual Models** Basis for manual soil mapping Based on conceptual soil-landscape models Empirical models developed by soil surveyors Produce area-class polygon maps Statistical Models Basis for automated predictive soil mapping CLORPT: relates soils/soil properties to observed environmental covariates Explains spatial distribution of soils in terms of statistical relationships of soils to known soil forming factors as represented by covariates

Theoretical Basis

- **Deterministic part**
 - Part that can be explained
- **Conceptual models**
 - Expert knowledge
 - Soil-landscape 0
 - Polygon maps

Statistical models

- Data driven 0
- Objective 0
- Soil-landscape too 0
- Continuous maps 0

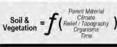


Predictive Soil Mapping Basics

Theoretical Basis for Current Manual or "Conventional" Soil or Ecological Mapping

Jenny (1941)

CLORP Climate, Organisms, Relief, PM, Time (No space)

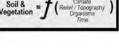


Simonson (1959) Soil genesis conceptual process model Additions, removals, translocations, transformations

Ruhe (1975) Geomorphic process models Erosional -Depositional surfaces, open/closed basins

Dalrymple et al., (1968) Hillslope (geomorphic) model Nine unit hill slope model

Milne (1936a, 1936b) Soil-landscape conceptual model Catena concept, toposequences



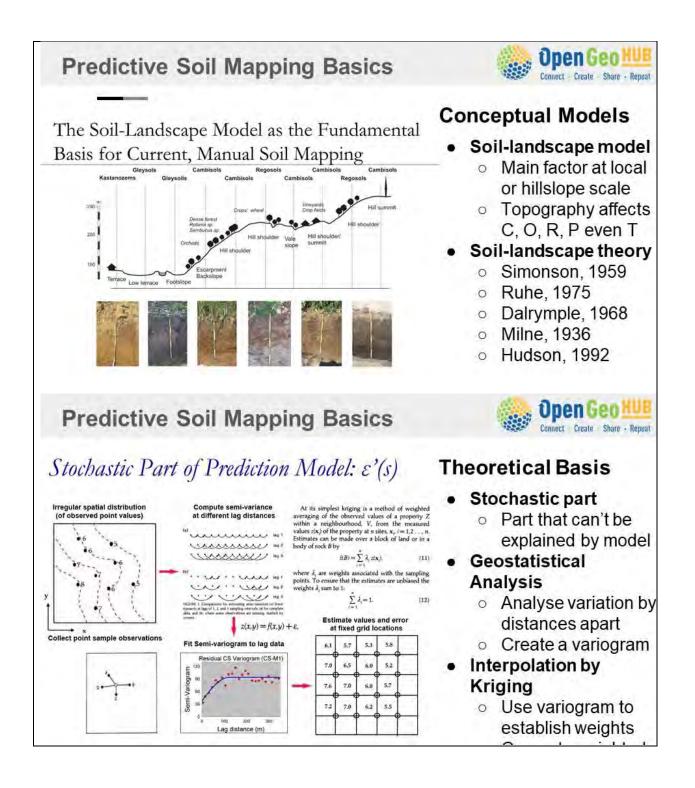




Conceptual Models

- For soil mapping
 - CLORPT (Jenny, 1941)
 - SCORPAN (McBratney, 2003)
- Additional theory
 - Simonson, 1959 0
 - Ruhe, 1975 0
 - Dalrymple, 1968 0
 - Milne, 1936 0
 - Hudson, 1992







Upen Geo **Predictive Soil Mapping Basics** Create Share - Reneat Geostatistics & Kriging Stochastic Part of Prediction Model: e'(s) Kriging/spatial prediction Optimal Interpolation by Kriging Estimate value at point 0 Geostatistical Estimation Weighted average of all Predict soil properties Point or block kriging surrounding values Predict soil cla Indicator kriging (0/1) Soil class likelihood values Weight is computed Predict error of estimate according to variogram Correct Deterministic Part Manual Mappers Error in deterministic part is computed Compute residuals Interpolate manually 0 If structure exists in error residuals Then krige error & subtract from predictions "Dig it out" 0 Draw boundaries 0 around similar soils or values UpenGeo Predictive Soil Mapping Basics Connect Create Share - Repeat Theoretical Basis Pure Noise Part of Prediction Model: 2' Pure Noise part Part that can't be Low Frequ ency (signal) explained/predicted Some variation is just not predictable Have to be honest about this High May be deterministic Quantify it and report it (pure noise) But data or models Deterministic prediction be du can't capture it Mental and statistical models Not perfect –often lack suitable covariates to data for interpolation ces or to lack of suitab May have structure predict target variable, or not at proper resolution for deterministic model But structure is **Geostatistical Prediction** Semi Varianc shorter than spatial Insufficient point input data Can't predict at less than the smallest spacing of Nugge input point data resolution of data dı d4 Don't have points



close enough

Predictive Soil Mapping Basics

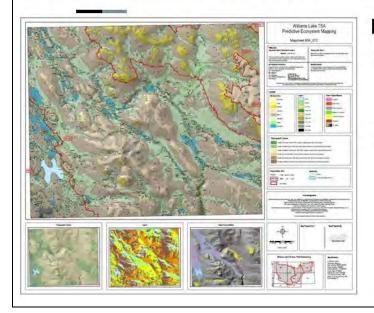




J.S. Rowe (1996)

- All fundamental variations in landscape ecosystems can initially (in primary succession) be attributed to variations in landforms as they modify climate
 - Boundaries between potential ecosystems can be mapped to coincide with changes in those landform characteristics known to regulate the reception and retention of energy and wator

What I learned: 2003-2008



Knowledge Based PEM

- Landform based
 - J. S. Rowe, 1996
 - **Based on observation** Landforms modify
 - their environment
 - Vegetation
 - Climate
 - Parent material
 - Hydrology
- **Boundaries occur**
 - Where landforms 0



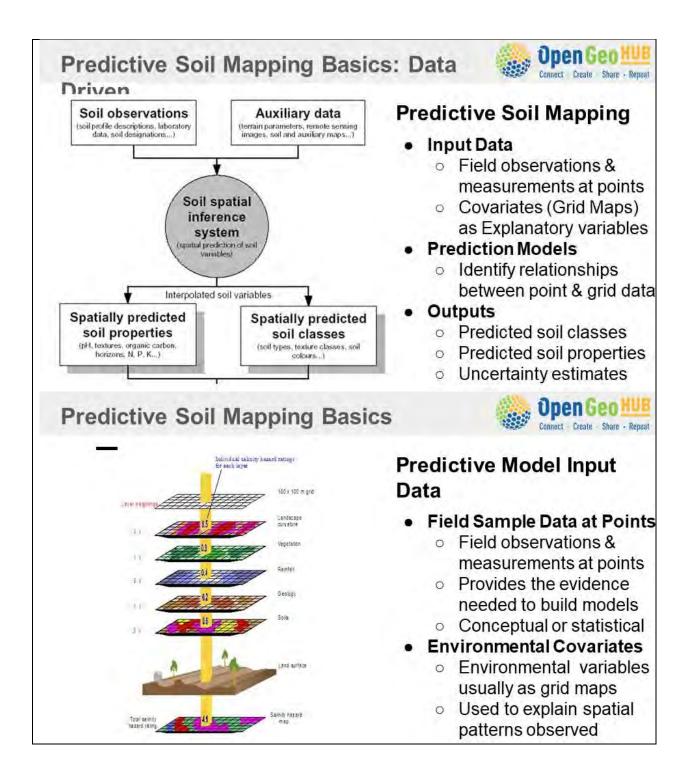
Expert Based PEM in BC

- Knowledge Based Systems
 - Can produce decent maps 0
 - As good as conventional
 - At a cost of 10 cents/ha

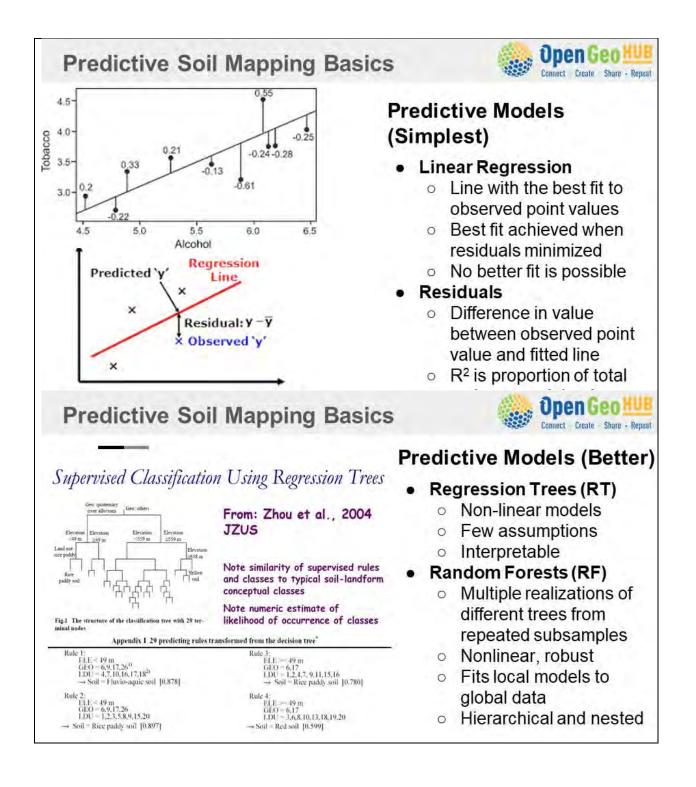
Methodology Used

- Faster than conventional
- But production limited by time to build & test rules
- Really need a local expert to achieve needed quality
- Spatial accuracy still poor
- Better to fully automate

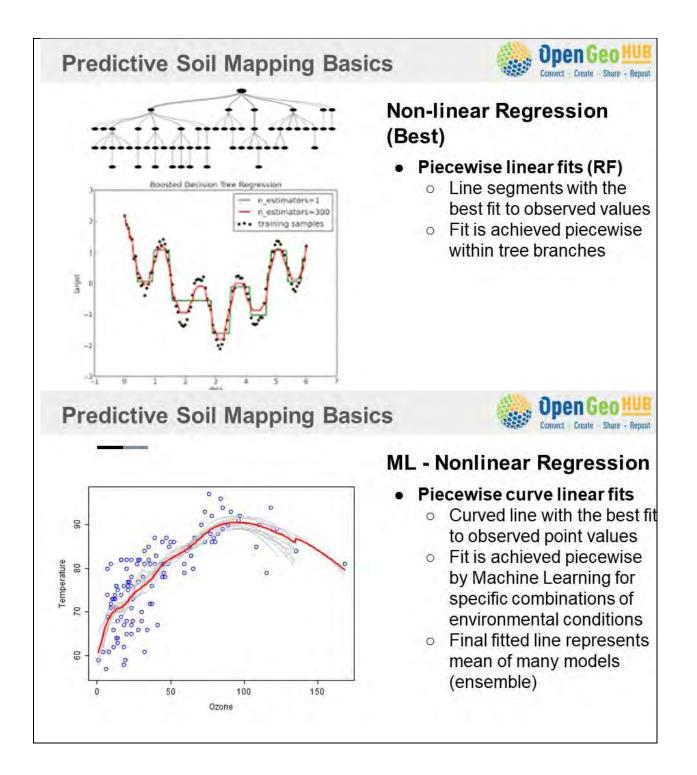




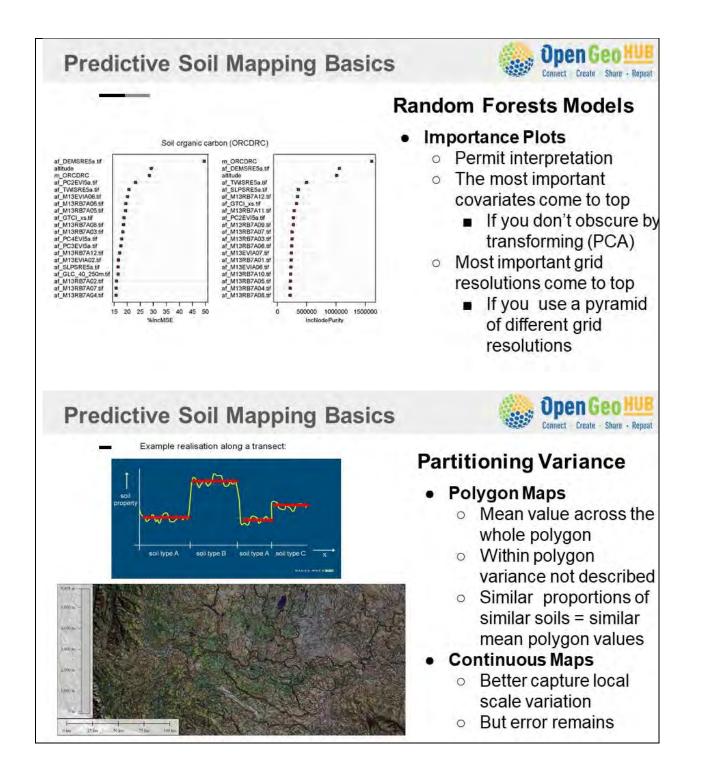




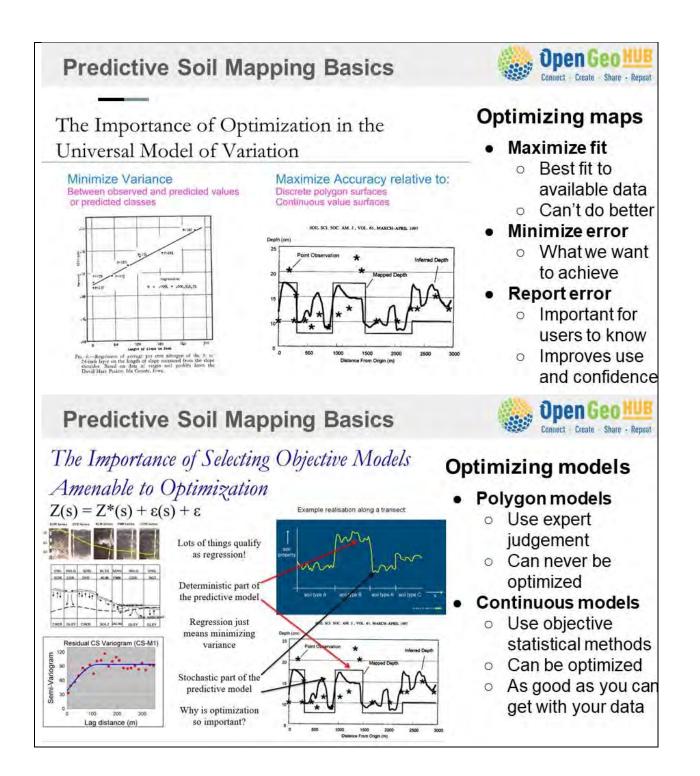




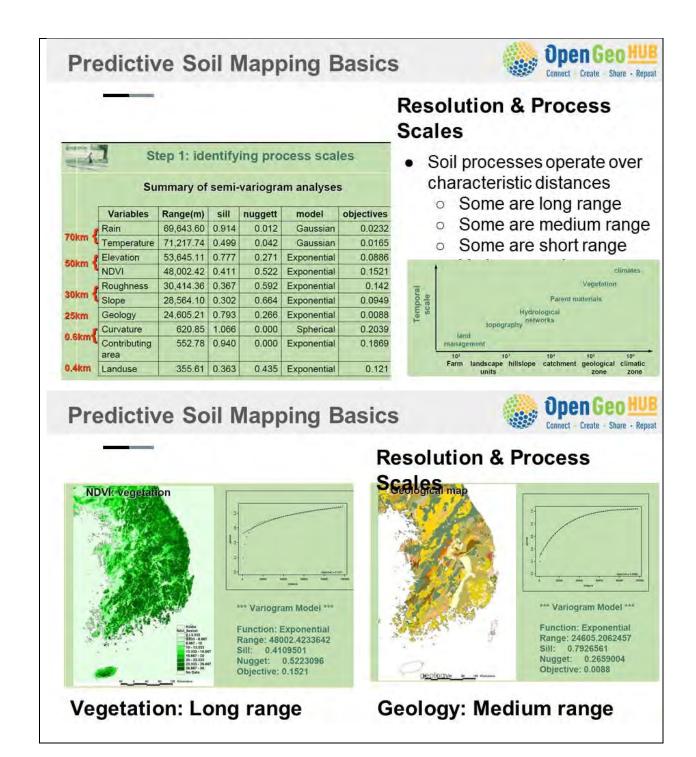








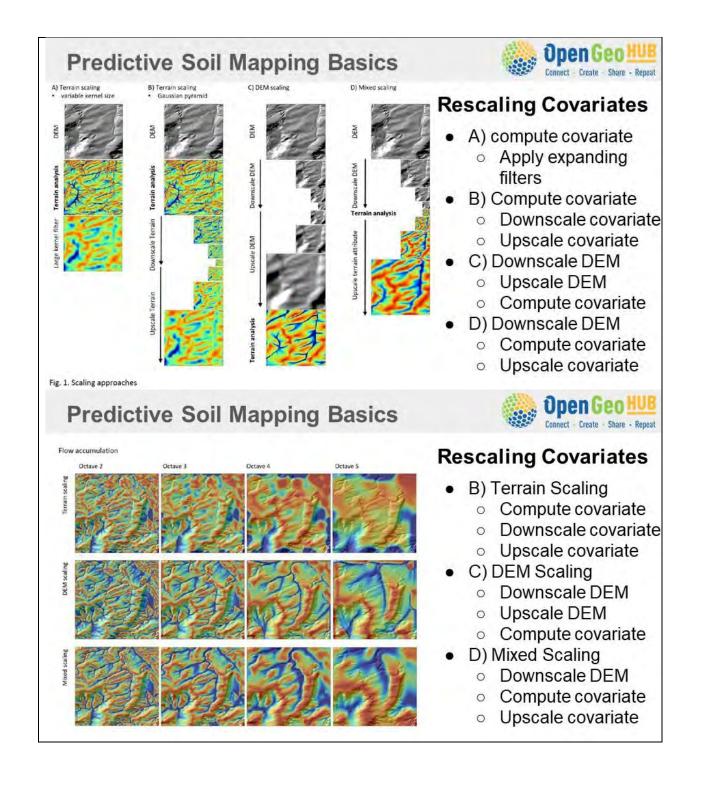




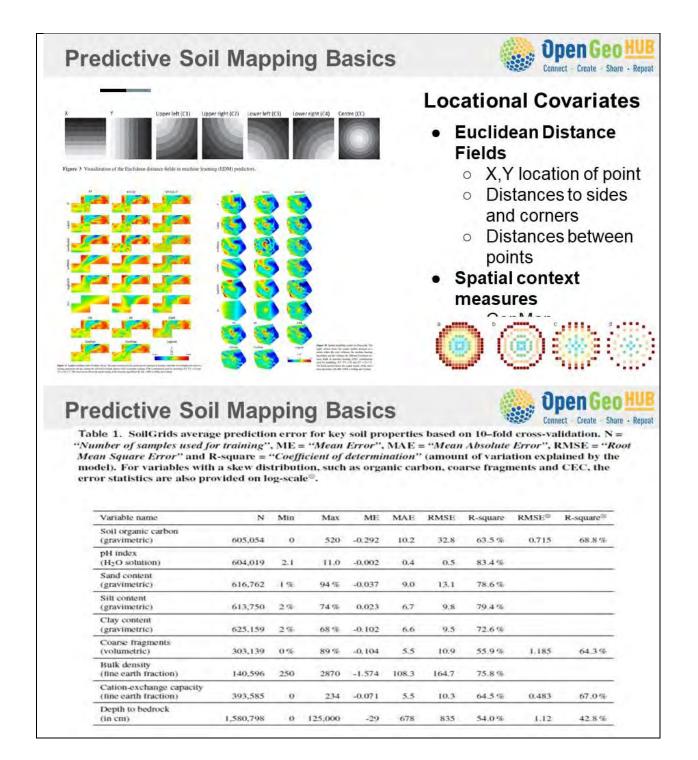


Pred	ictive S	Soil Ma	apping	Basi	cs	Connect Create Share - Repeat
-	-			_	Reso	olution & Process
Contraction of the second seco	ntributing area	+++ Var Functi Range Sill: 0 Nugge Object	ogram Model *** ogram Model *** 552.7831244 9399081 ±: 0.0000000 ve: 0.1869			The second secon
range	Step 1: id	Soil Ma		Basi	cs	• Form a hierarchy and so need different resolution covariates
range	Step 1: id Summary of	Soil Ma entifying p	apping process sca	Basic les	cs	Different Process Scales Form a hierarchy and so need different resolution covariates Best way is to produce a
range Pred	Step 1: id Summary of	Soil Ma entifying p f semi-vario sill nugg	apping process sca gram analyse ett model	Basi	cs	 Open Geo Hue Connect Create Share - Repeat Different Process Scales Form a hierarchy and so need different resolution covariates Best way is to produce a Gaussian Pyramid of
range Pred	Step 1: id Summary of 69,643.60	semi-vario	apping process sca gram analyse ett model 12 Gaussian	Basic les s objectives 0.0232	cs	 Different Process Scales Form a hierarchy and so need different resolution covariates Best way is to produce a Gaussian Pyramid of
Variat Rain Temper Elevatio	Step 1: id Summary of 69,643.60 ature 71,217.74 53,645.11	Soil Ma entifying p semi-vario sill nugg 0.914 0.0 0.499 0.0 0.777 0.2	apping process sca gram analyse ett model 12 Gaussian 42 Gaussian 71 Exponential	Basic les s objectives 0.0232 0.0165	cs	 Different Process Scales Form a hierarchy and so need different resolution covariates Best way is to produce a Gaussian Pyramid of
Variat Rain Temper	Step 1: id Summary of 69,643.60 ature 71,217.74	Soil Ma entifying p semi-vario sill nugg 0.914 0.0 0.499 0.0 0.777 0.2	apping process sca gram analyse ett model 12 Gaussian 42 Gaussian	Basic Ies s objectives 0.0232 0.0165 0.0886	cs D	 Different Process Scales Form a hierarchy and so need different resolution covariates Best way is to produce a Gaussian Pyramid of covariate grids of different
Variate Rain Temper Km (Rain Temper Elevatio NDVI Roughn	Step 1: id Summary of 69,643.60 ature 71,217.74 53,645.11 48,002.42	Soil Ma entifying p semi-vario sill nugg 0.914 0.0 0.499 0.0 0.777 0.2	apping process sca gram analyse ett model 12 Gaussian 12 Gaussian 11 Exponential 22 Exponential	Basic les s objectives 0.0232 0.0165 0.0886 0.1521	cs D	 Form a hierarchy and so need different resolution covariates Best way is to produce a Gaussian Pyramid of covariate grids of different
Variate Rain Temper Km Elevation NDVI Roughn	Step 1: id Summary of 69,643.60 ature 71,217.74 53,645.11 48,002.42	Soil Ma entifying p semi-vario sill nugg 0.914 0.0 0.499 0.0 0.777 0.2 0.411 0.5	apping rocess sca gram analyse ett model 12 Gaussian 12 Gaussian 12 Exponential 22 Exponential 22 Exponential	Basic les s objectives 0.0232 0.0165 0.0886 0.1521 0.142	cs D	 Different Process Scales Form a hierarchy and so need different resolution covariates Best way is to produce a Gaussian Pyramid of covariate grids of different
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Variat Rain Temper Km (Rain Temper Levatio NDVI Roughn Slope	E ictive S Step 1: id Summary of 69,643.60 ature 71,217.74 n 53,645.11 48,002.42 ess 30,414.36 28,564.10 48,002.41 re 620.85	Soil Ma entifying p semi-vario sill nugg 0.914 0.0 0.419 0.0 0.367 0.5 0.302 0.6	apping rocess sca gram analyse ett model 12 Gaussian 42 Gaussian 71 Exponential 22 Exponential 92 Exponential 64 Exponential 66 Exponential 60 Spherical	Basic Ies s objectives 0.0232 0.0165 0.0886 0.1521 0.142 0.0949 0.0088 0.2039	cs D	 Come Come Come Come Come Come Come Come

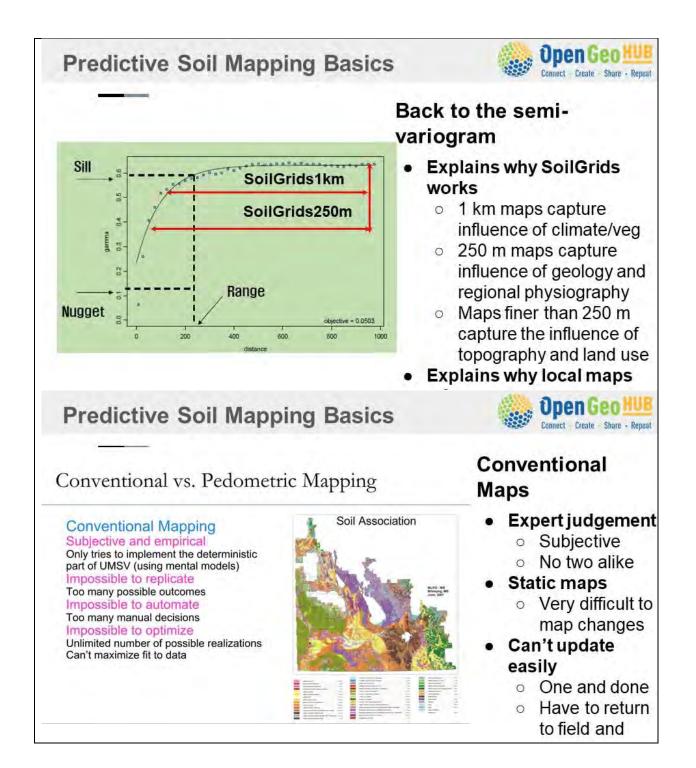




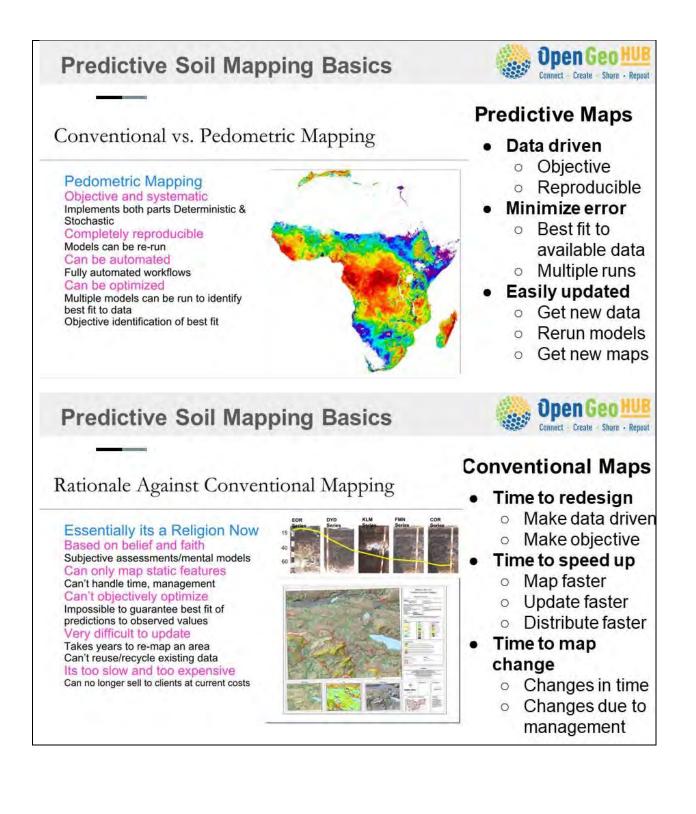




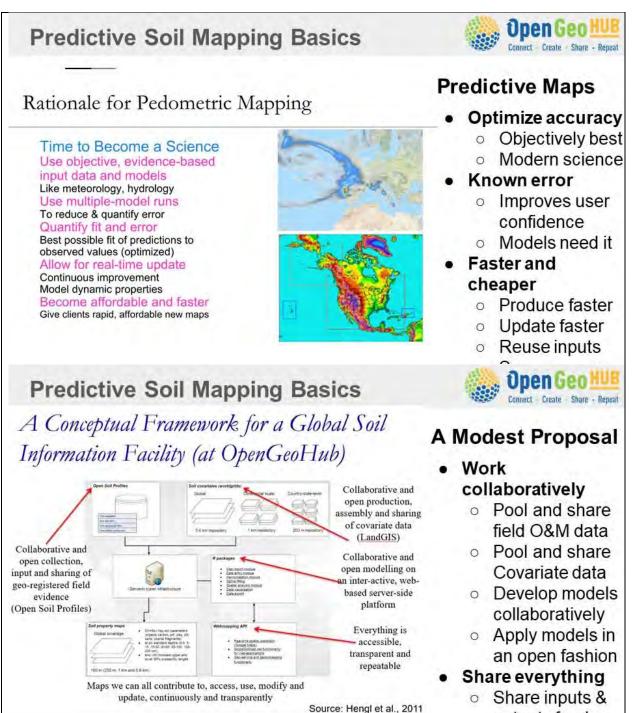




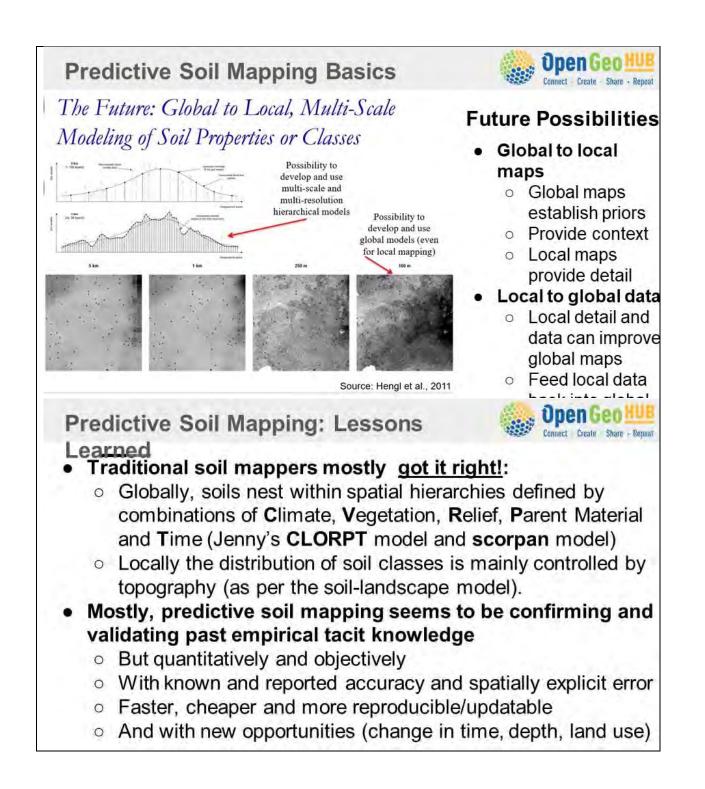




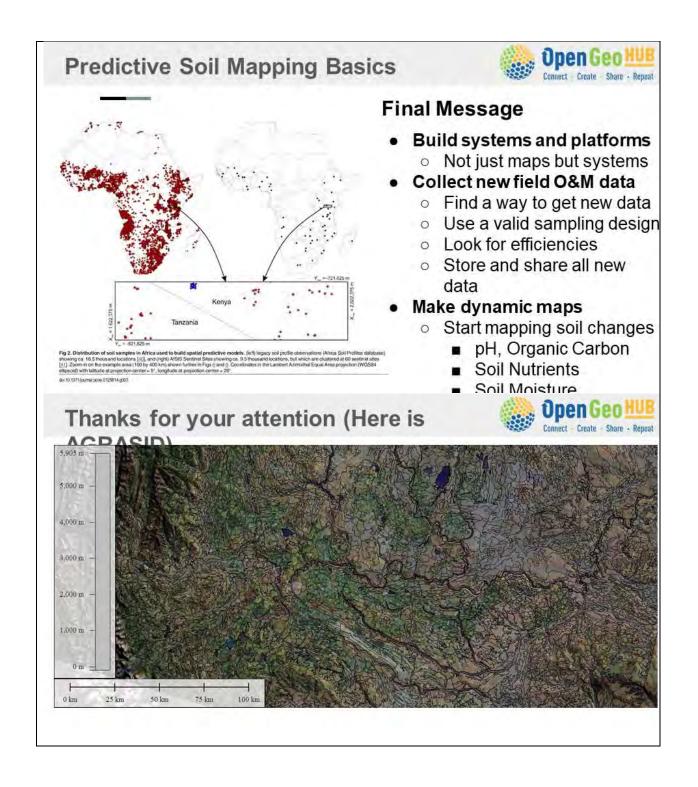




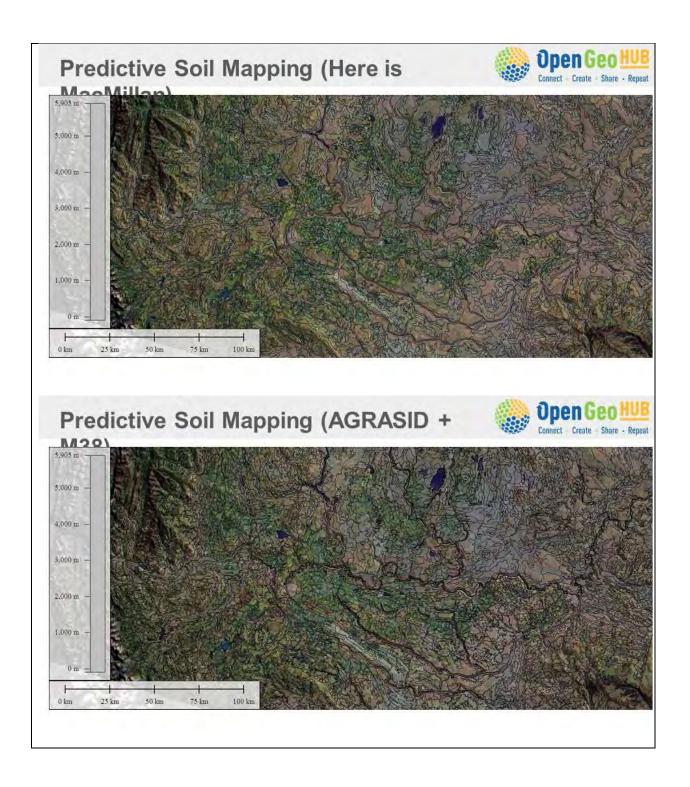














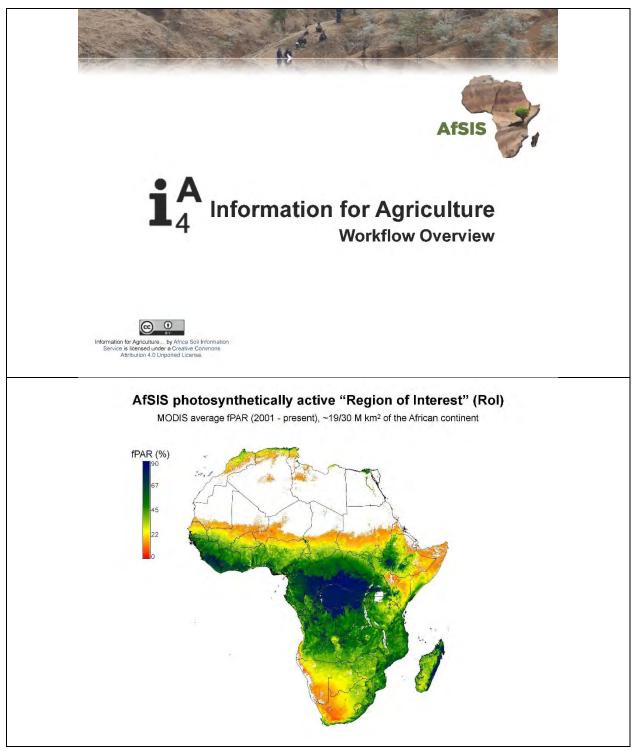
Predictive Soil Mapping Basics



Thank you

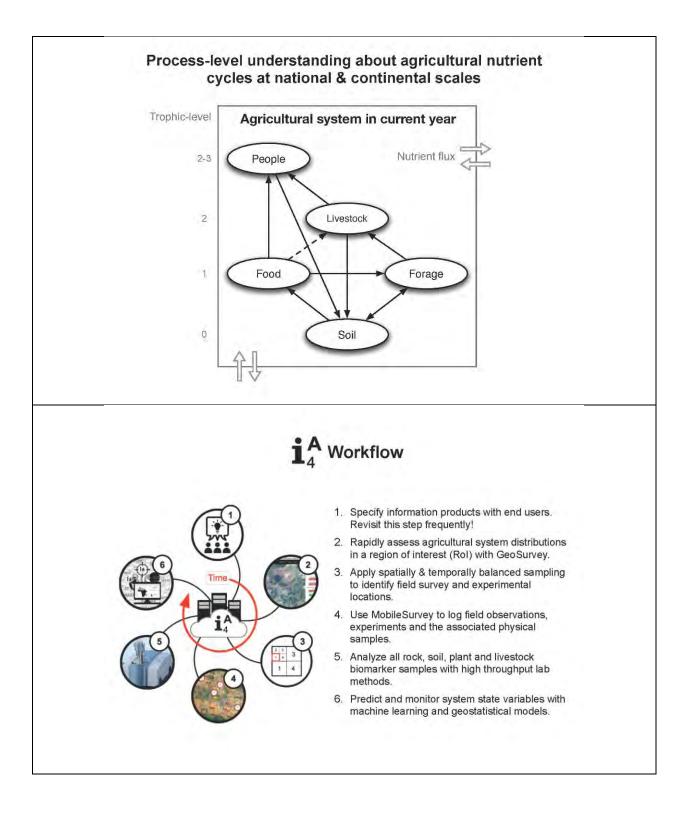
Try Predictive Soil Mapping Yourself

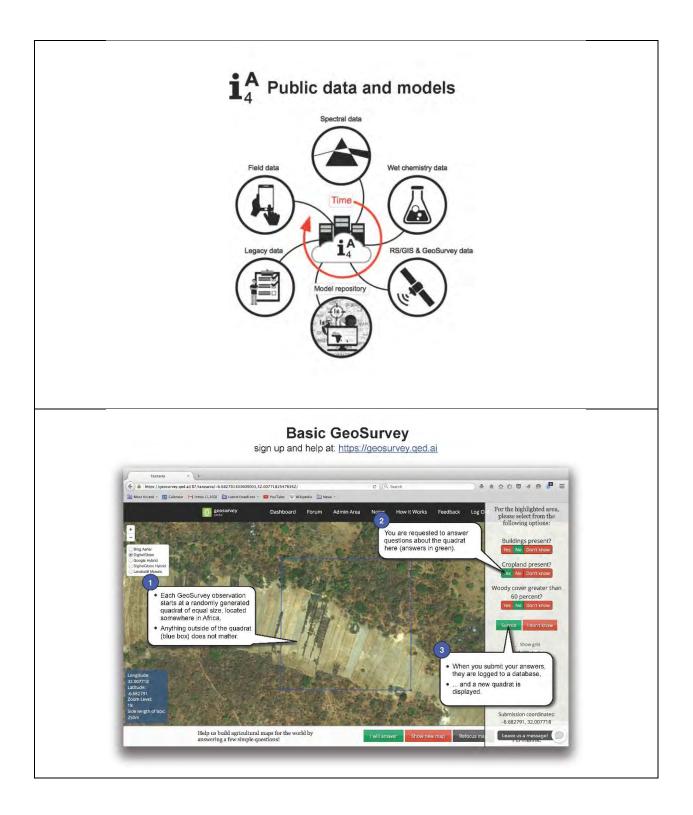




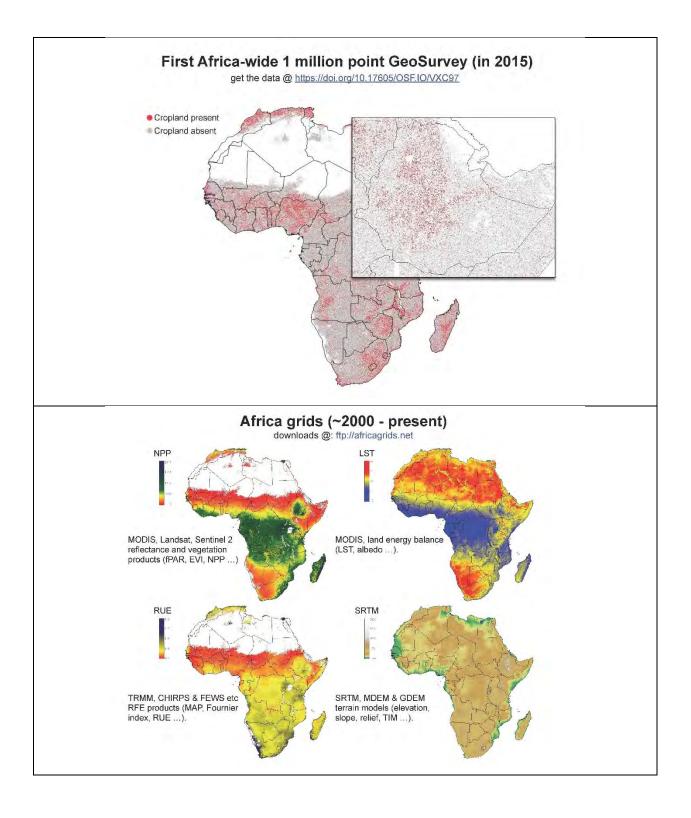
Lessons Learned: What's been tried; Problems and Solutions for Utilizing PSM – Markus Walsh



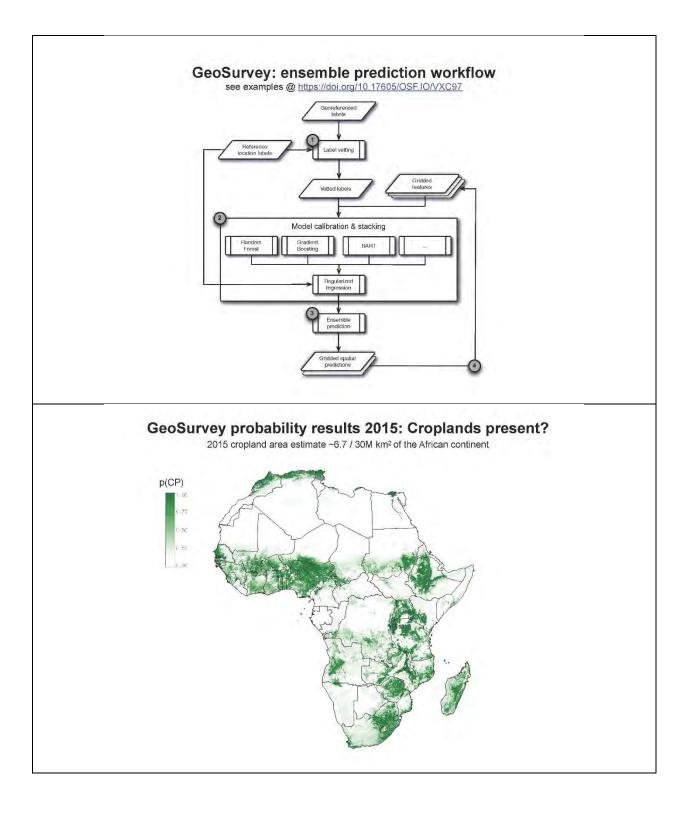




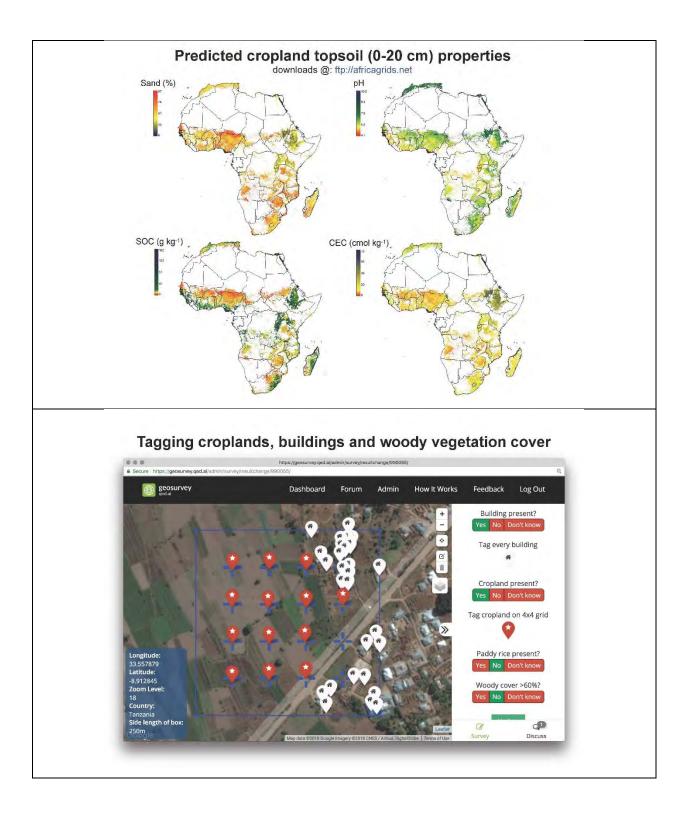




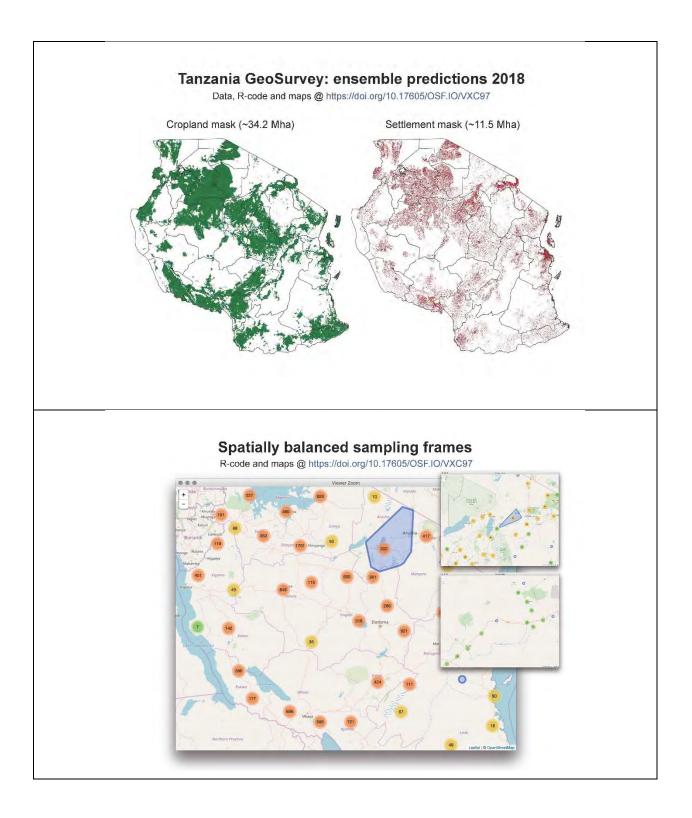




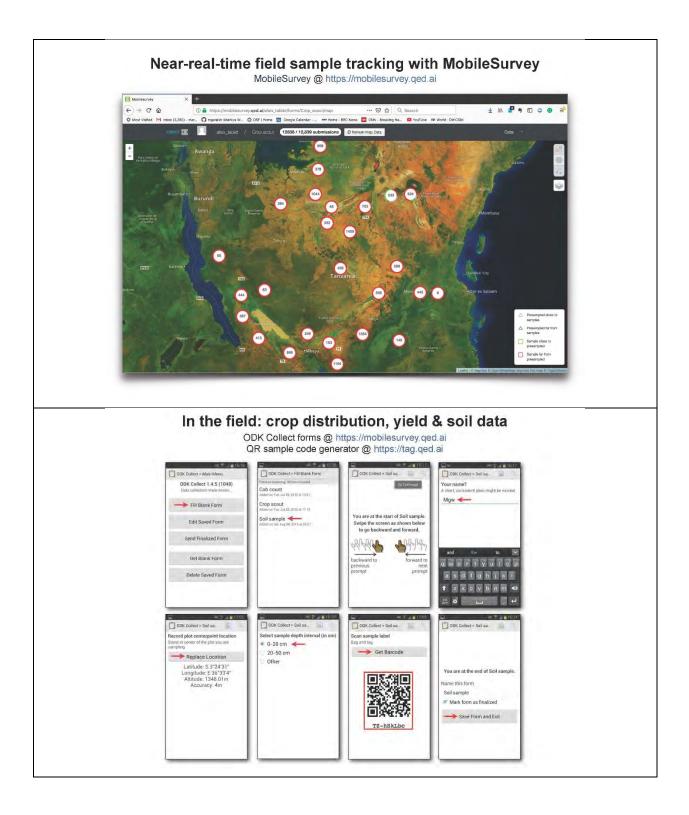




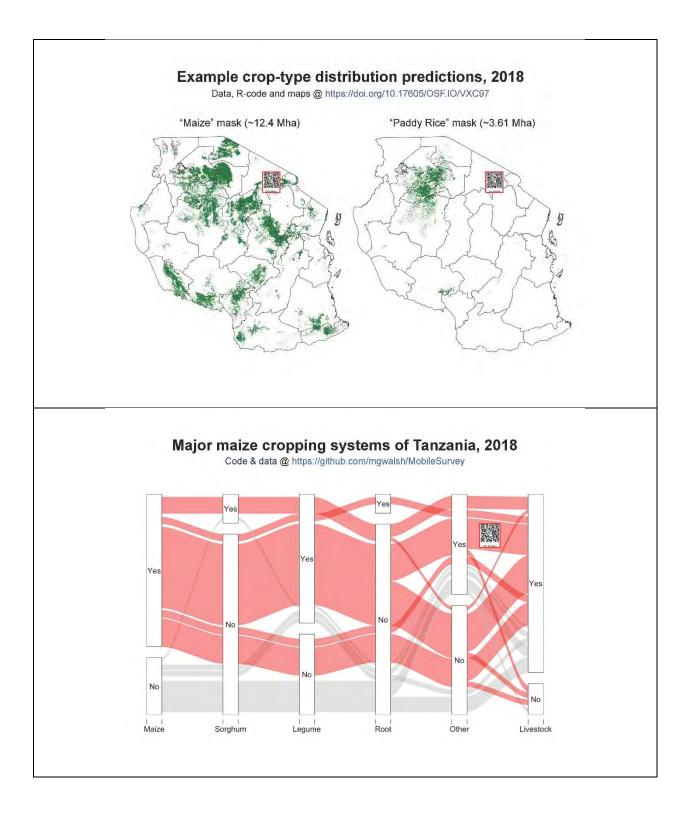




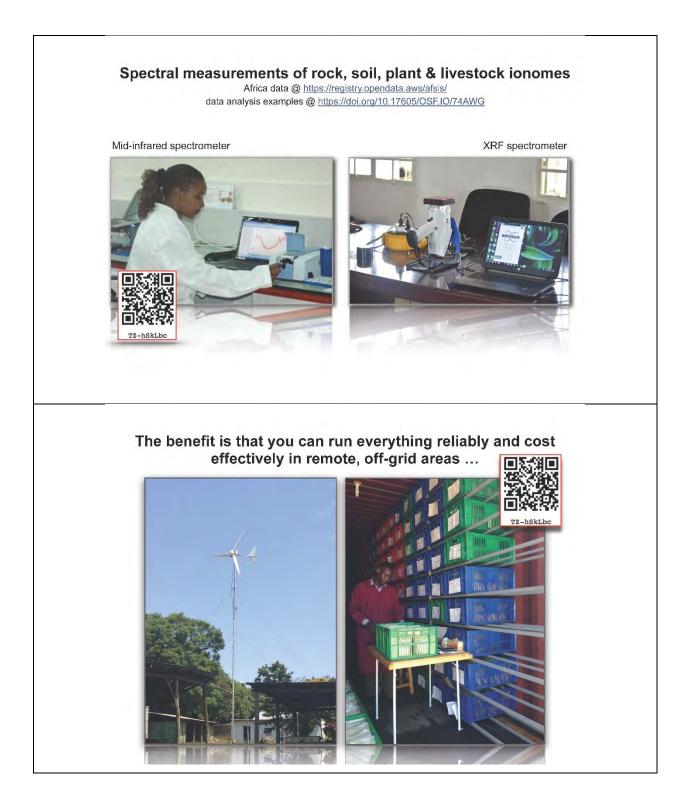




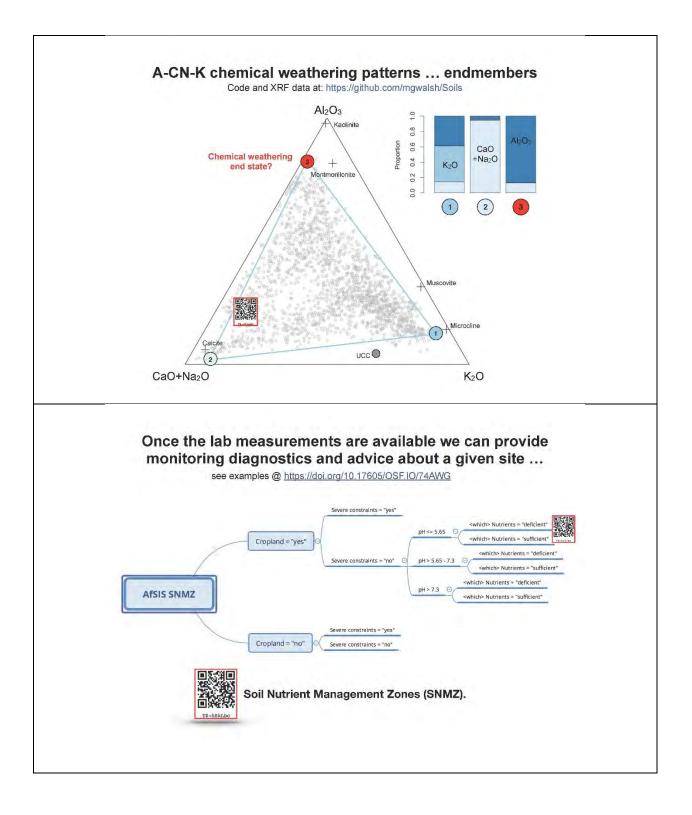




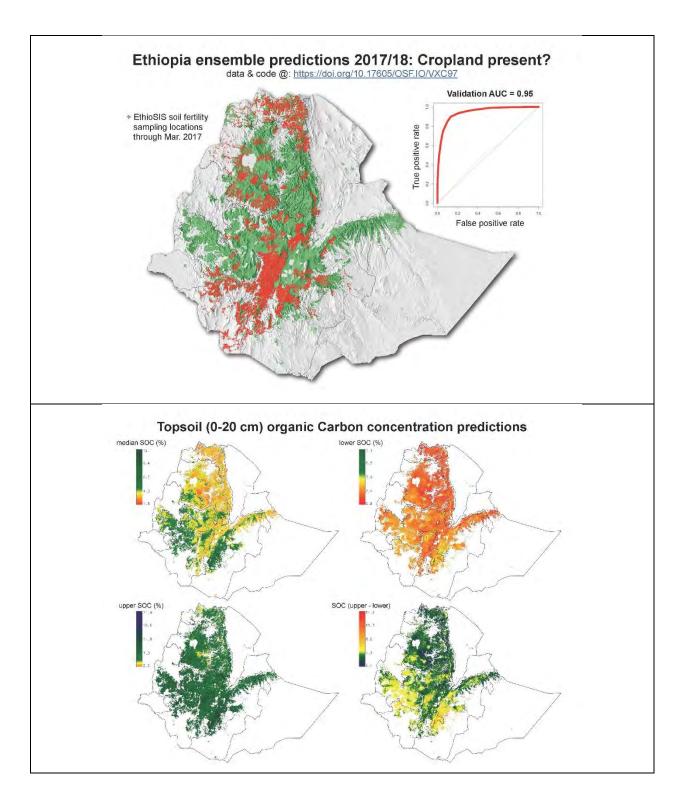




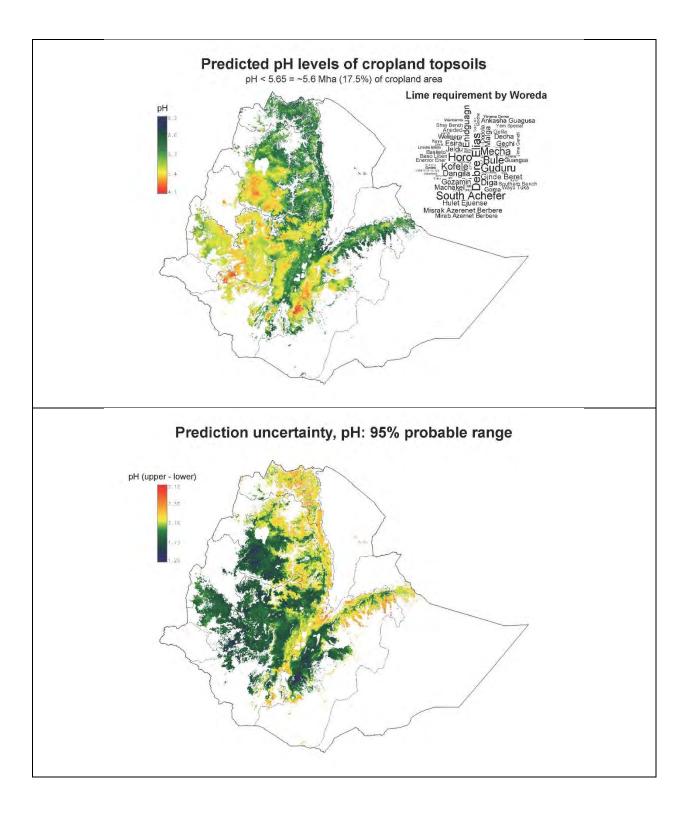




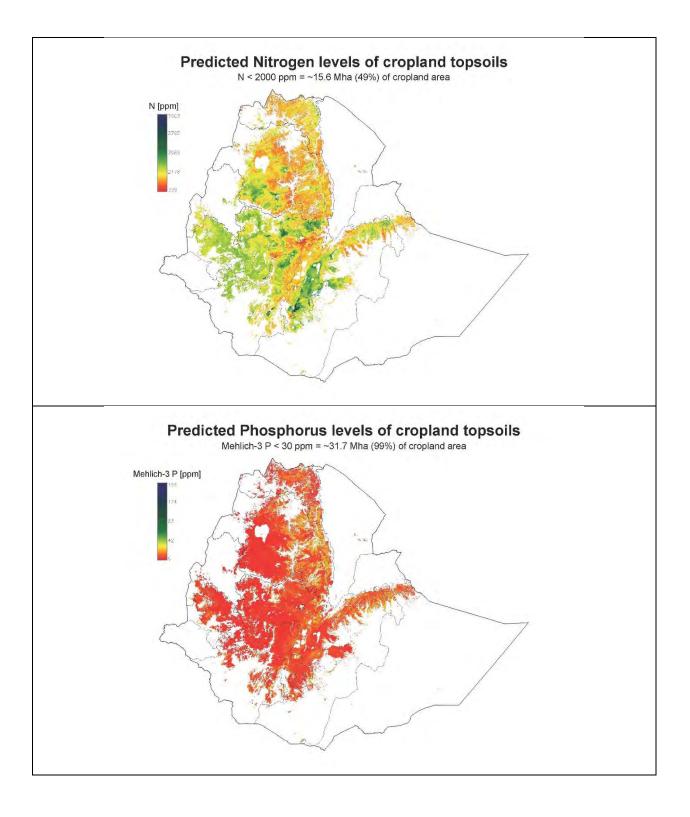




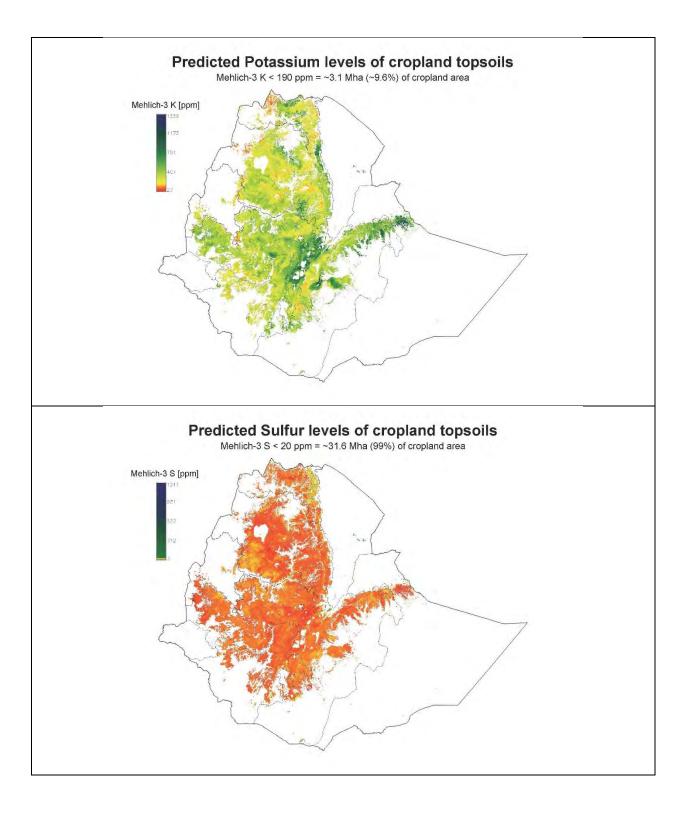




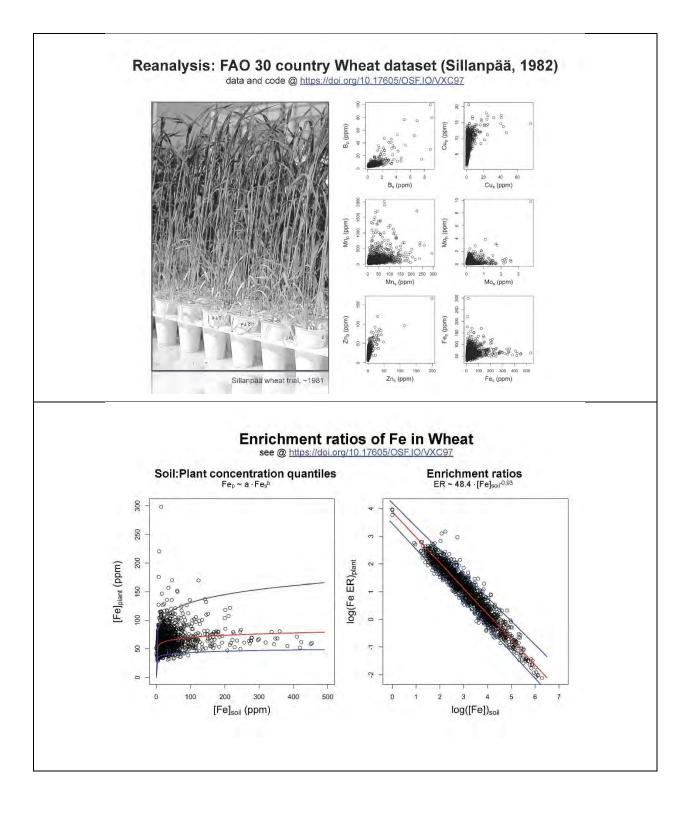




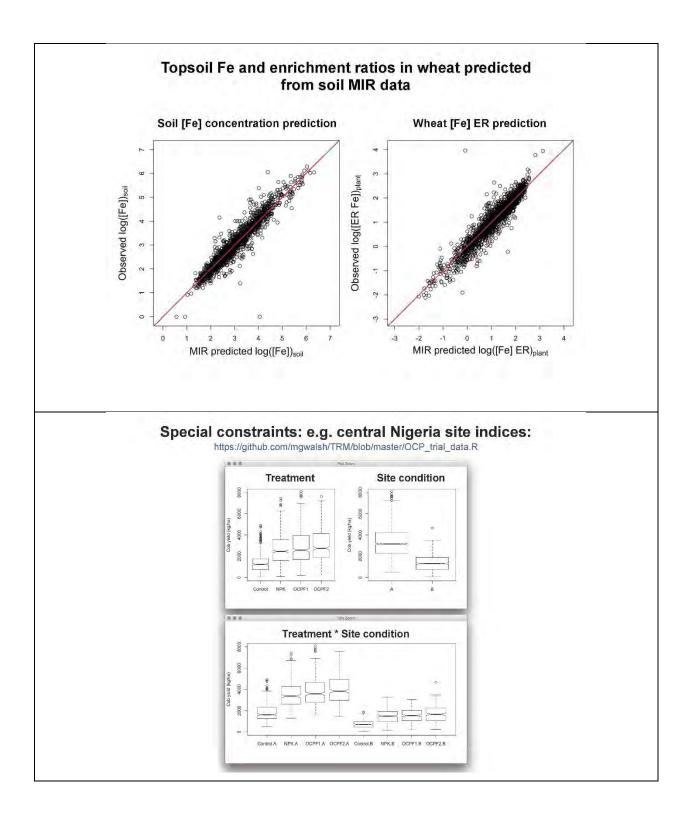




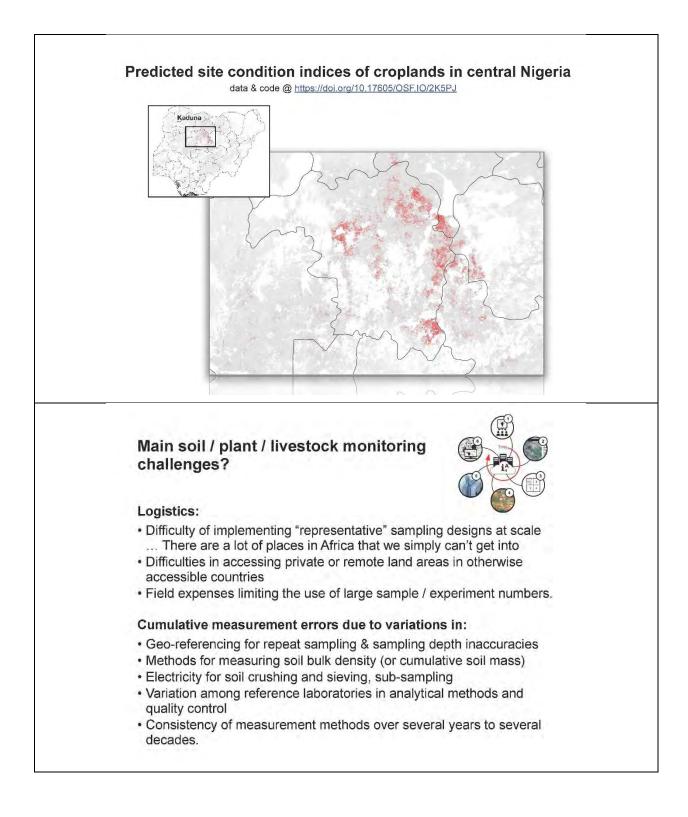




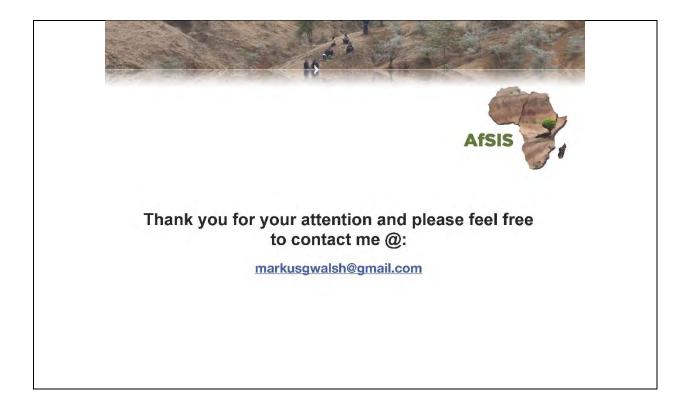






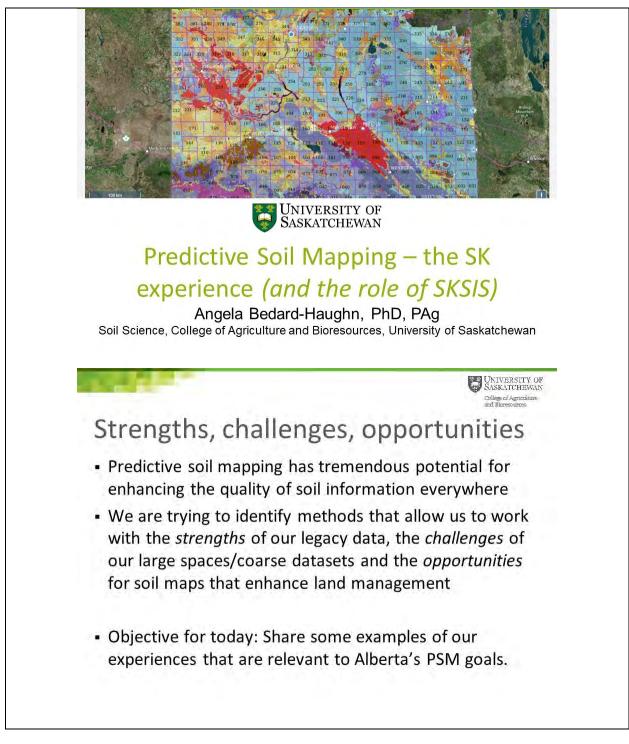








Saskatchewan Soil Information System (SKSIS) - Angela Bedard-Haughn





College of Agriculture

STRENGTH: Legacy Survey Data

- What?
 - Map soil and vegetation zones
 - The original **big soils data**
- Why?
 - Determine agriculture and forest capability, irrigation potential, agri-environmental rating, GHG
- How?
 - Canadian system started in 1945
 - Glory years: 1950-95





STRENGTH: The Data Legacy

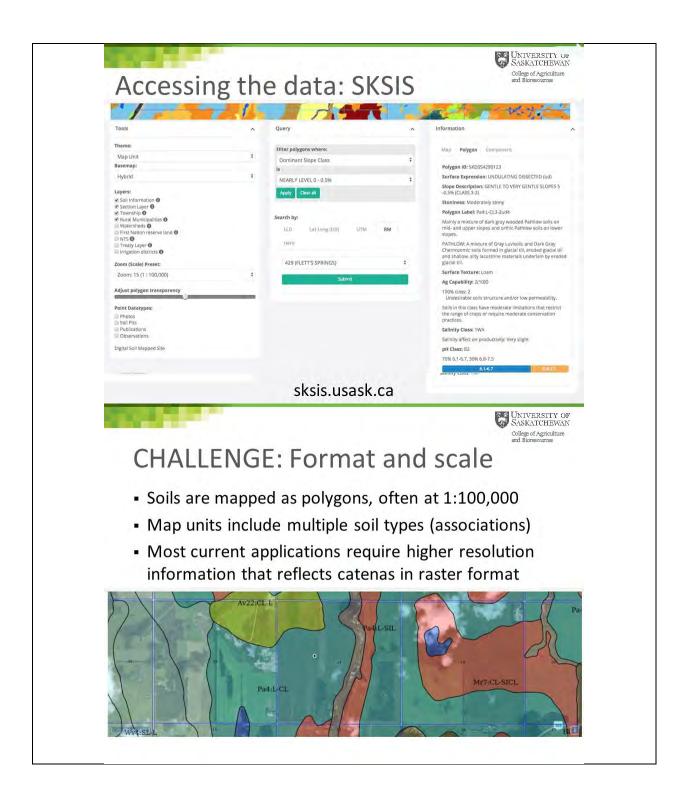


PDFs: sis.agr.gc.ca/cansis/publications/surveys/ index.html

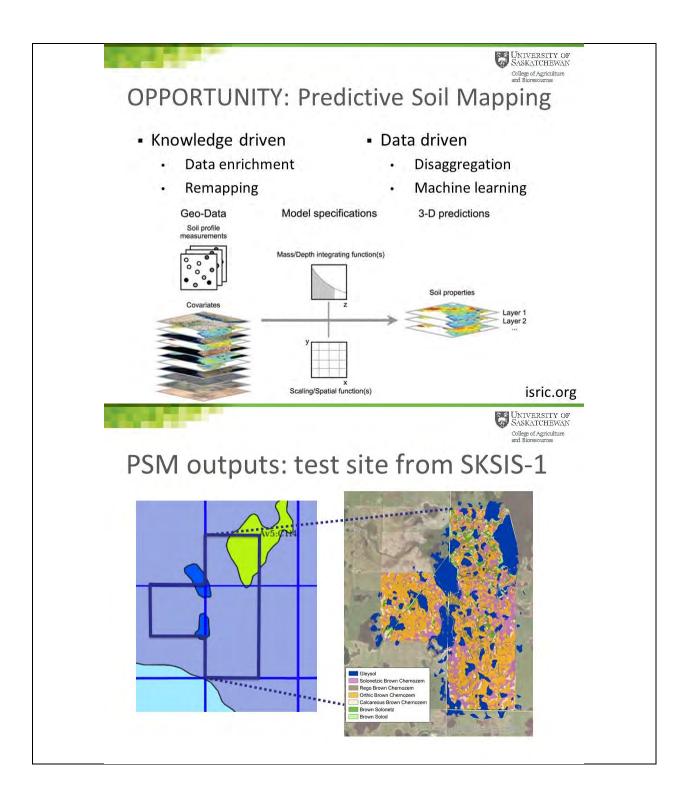
GIS: sis.agr.gc.ca/cansis/nsdb/index.html



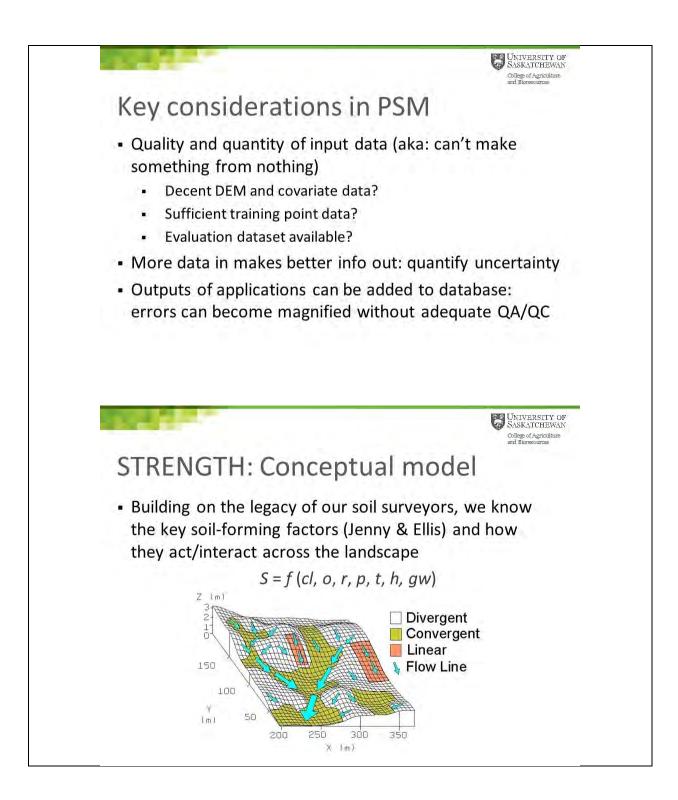




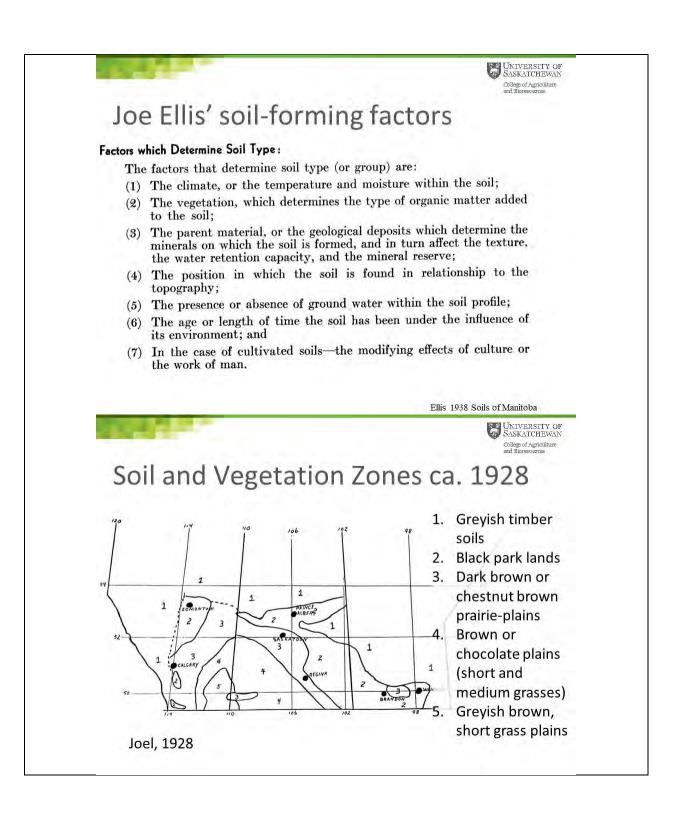




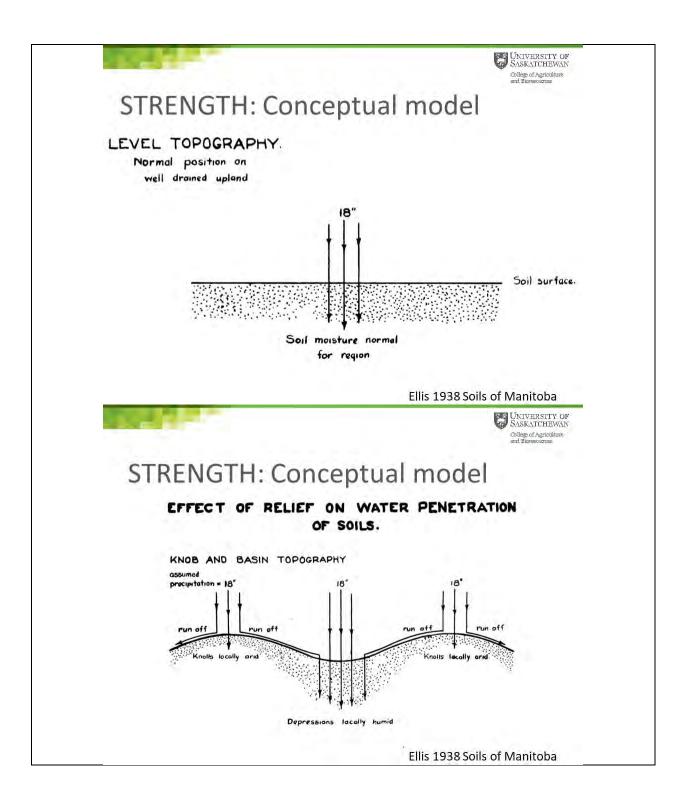




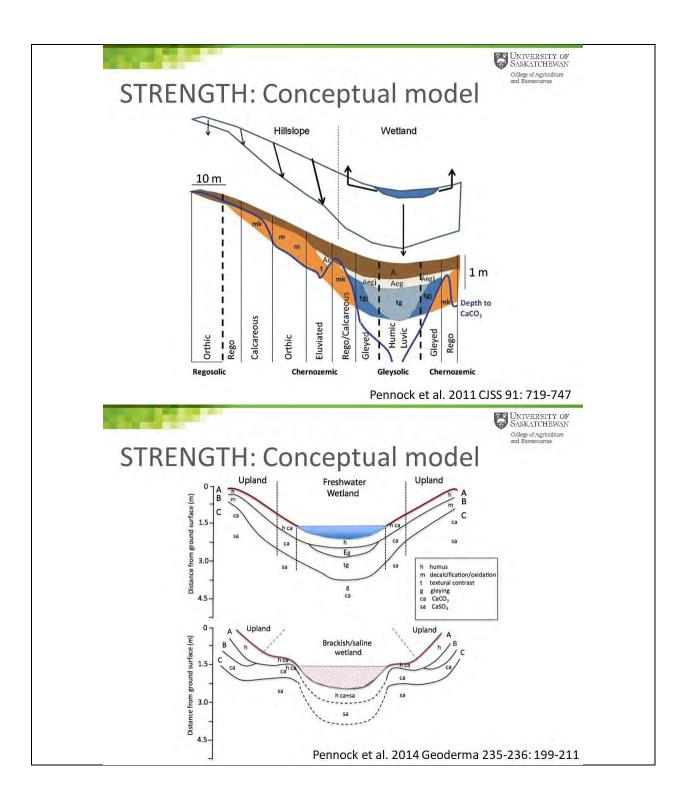




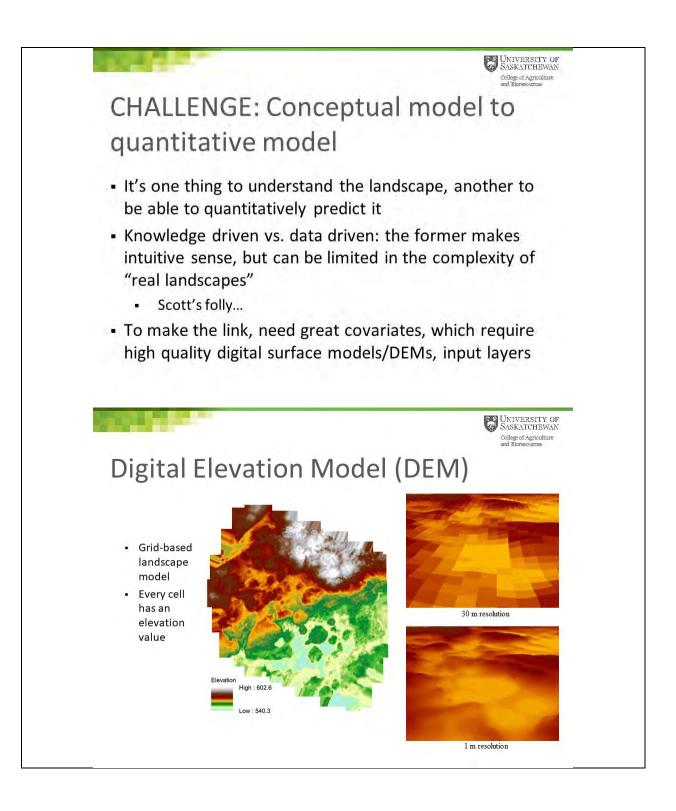




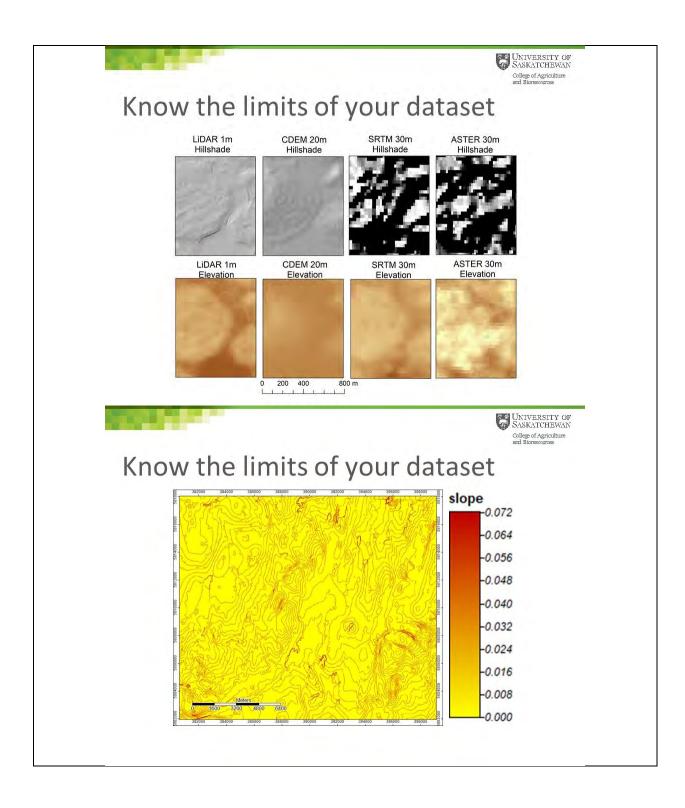




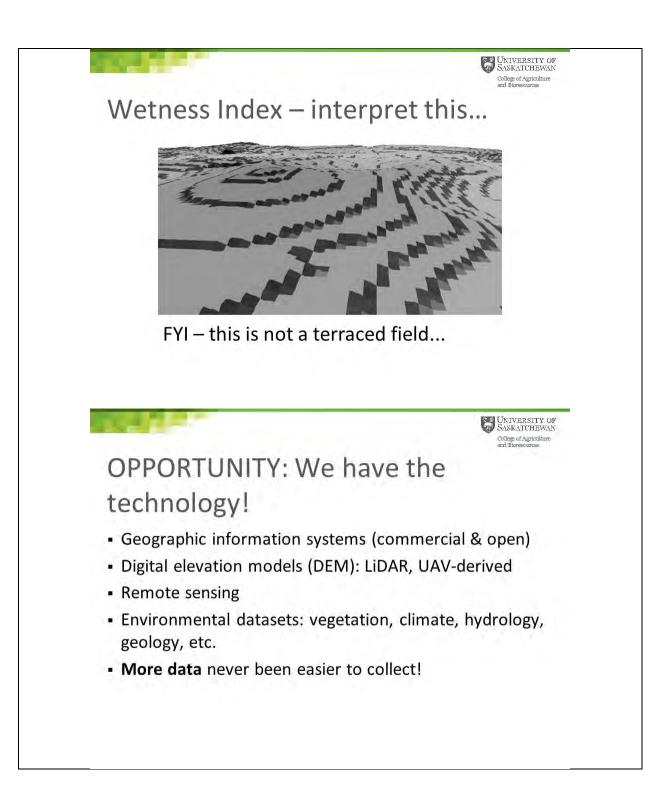




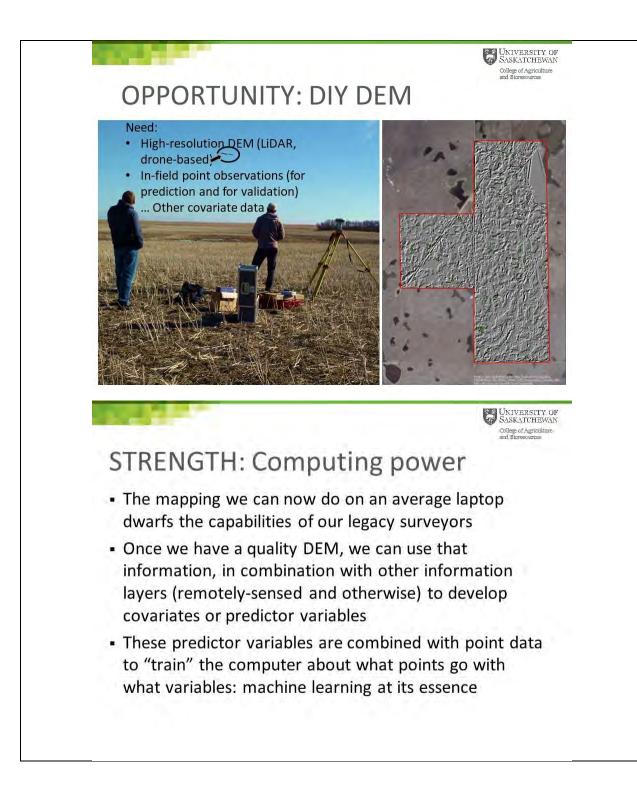




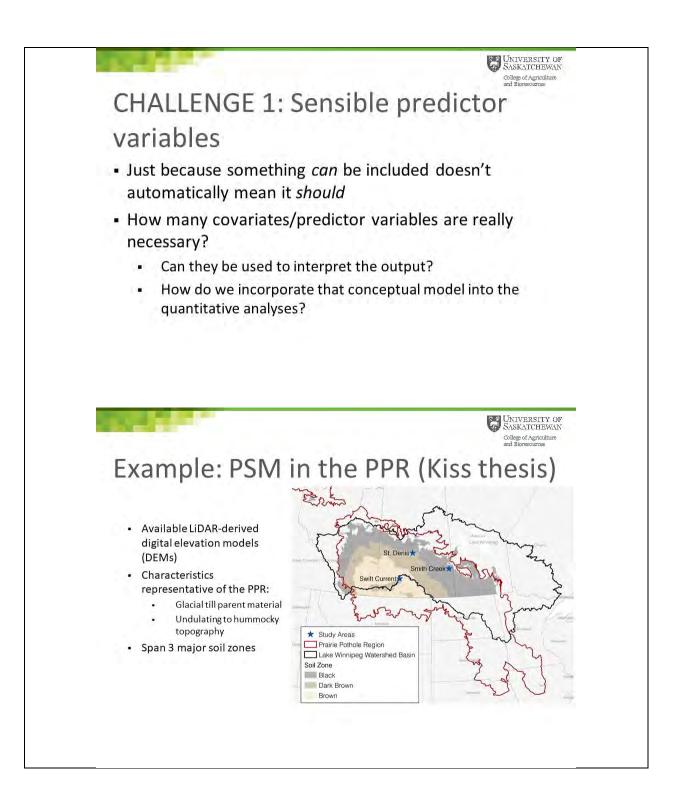




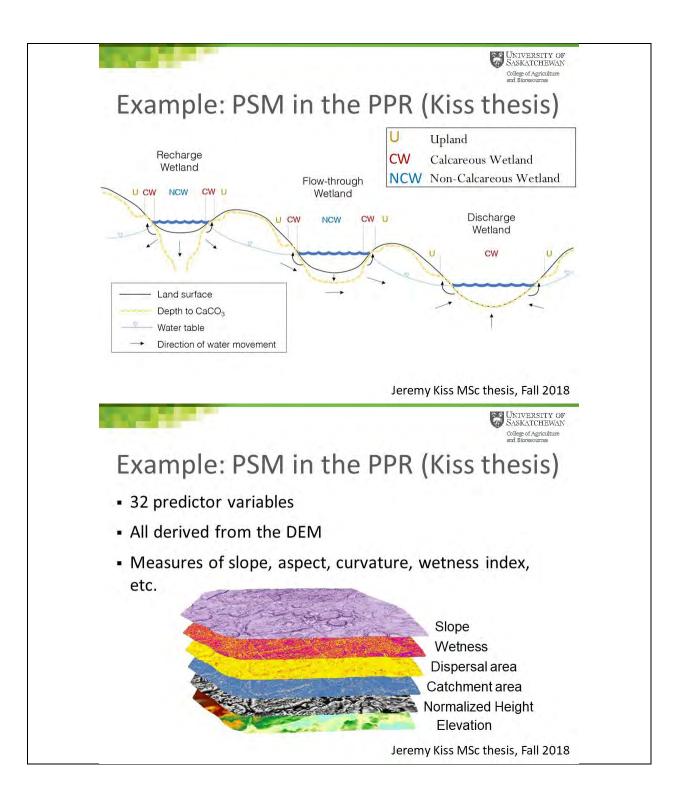




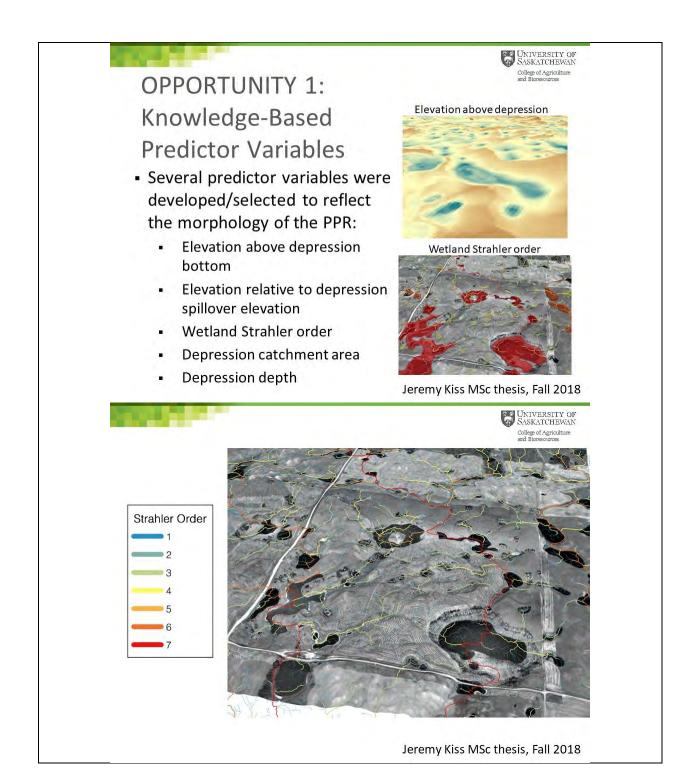




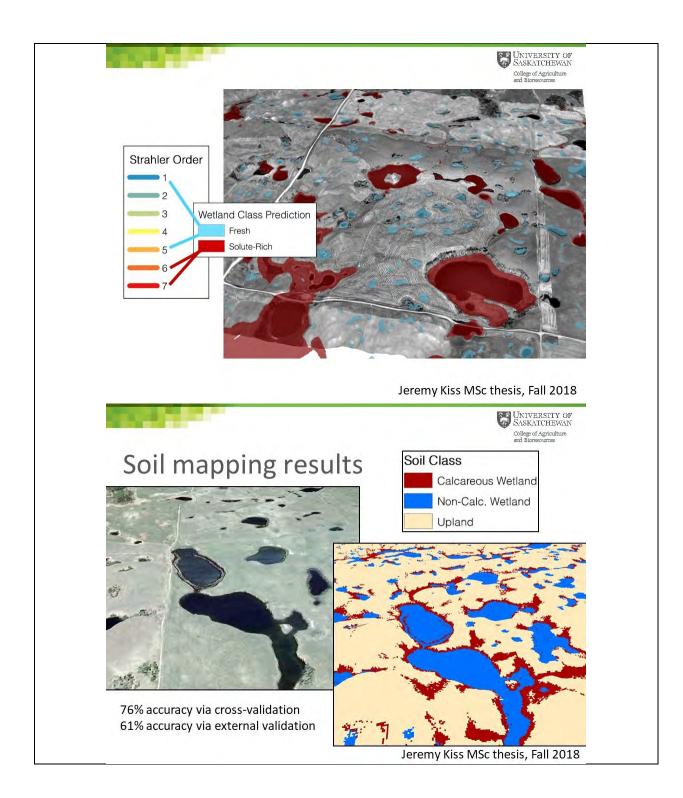




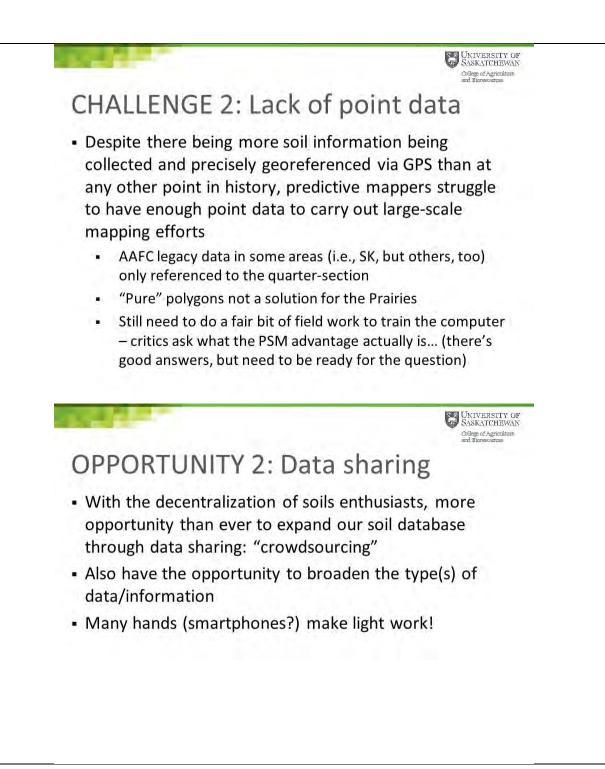




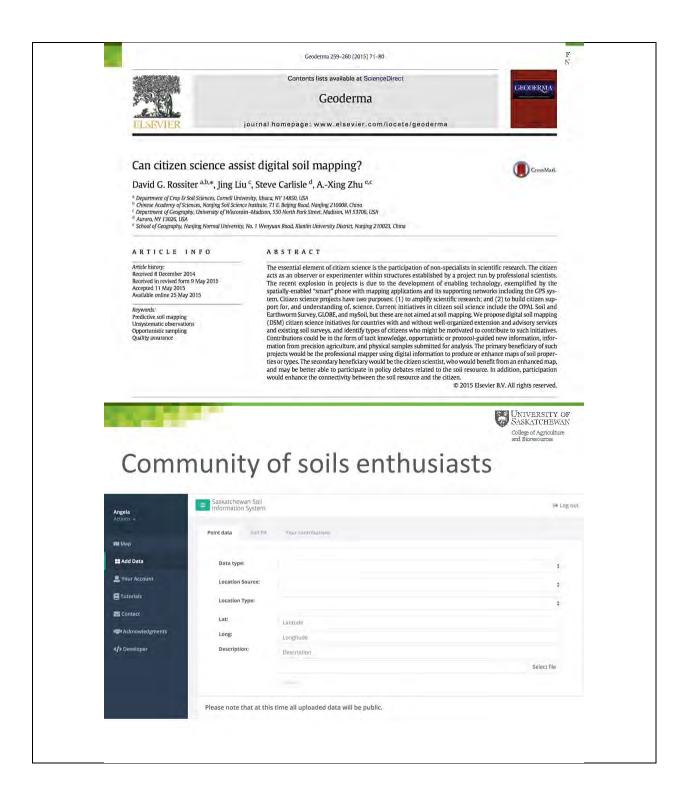




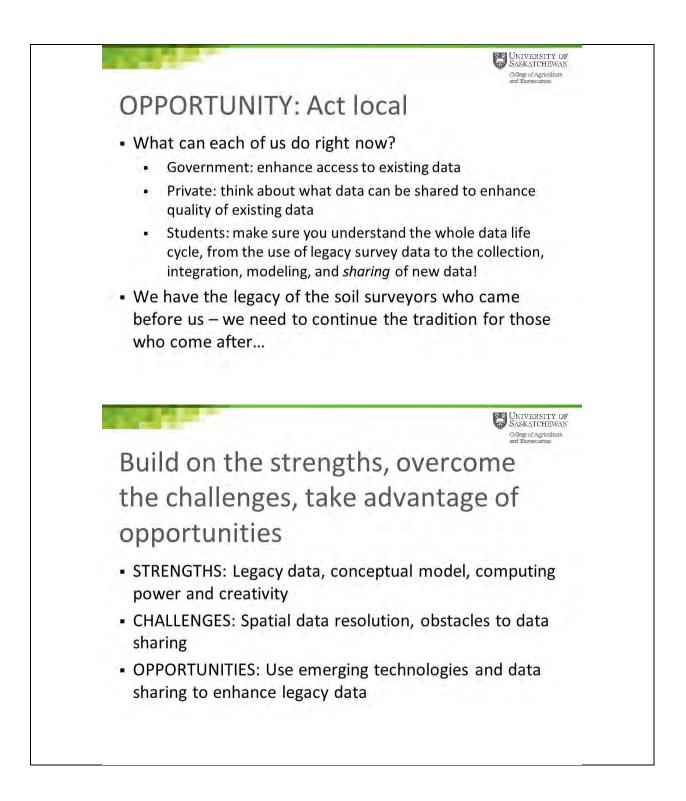








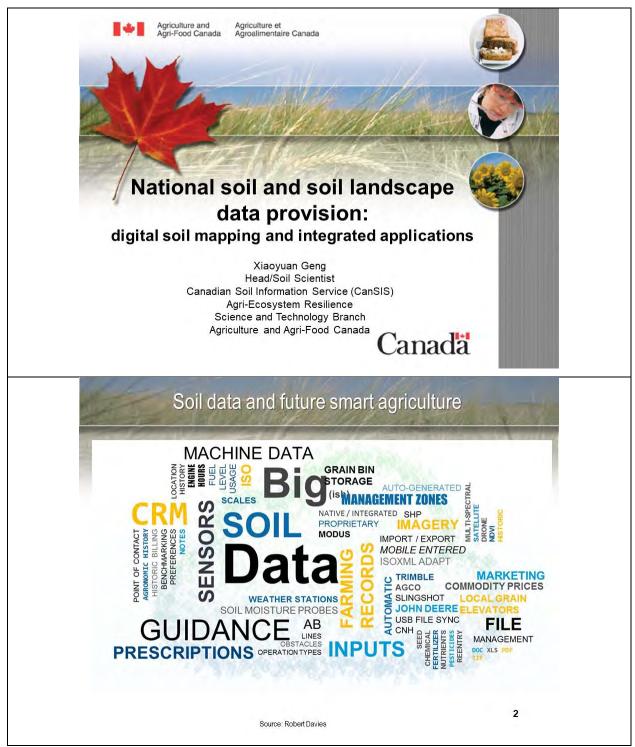






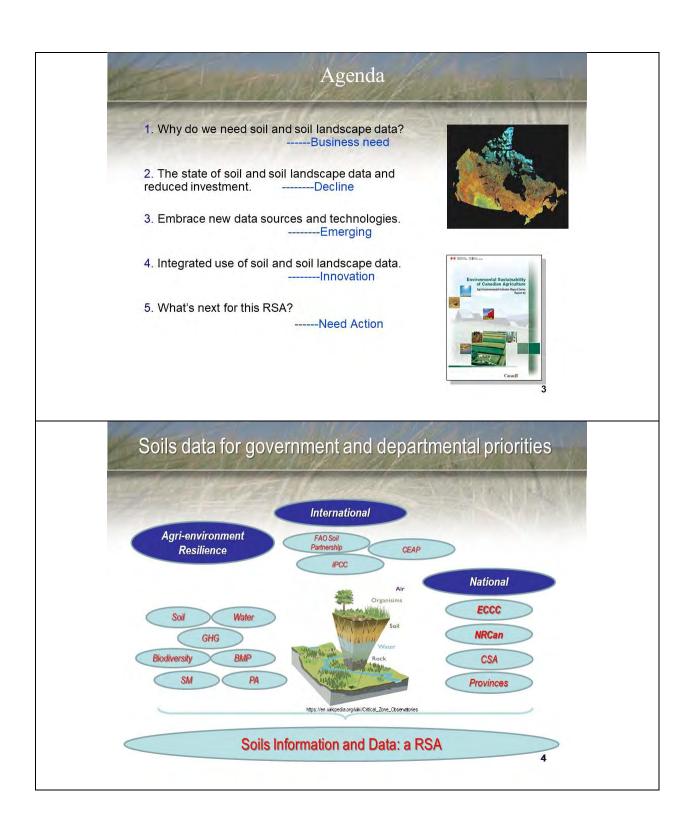




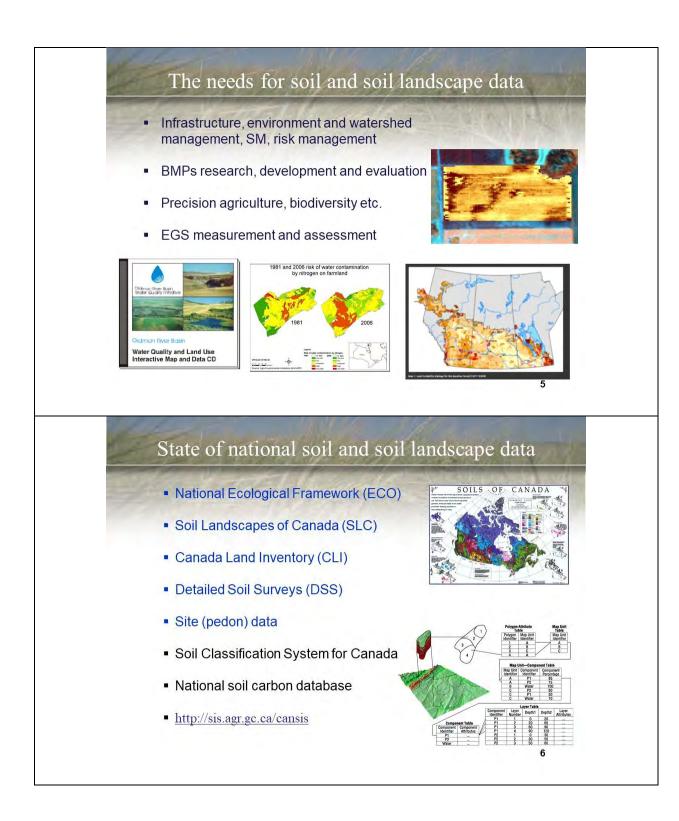


Predictive Soil Mapping – National Perspective – Xiaoyuan Geng

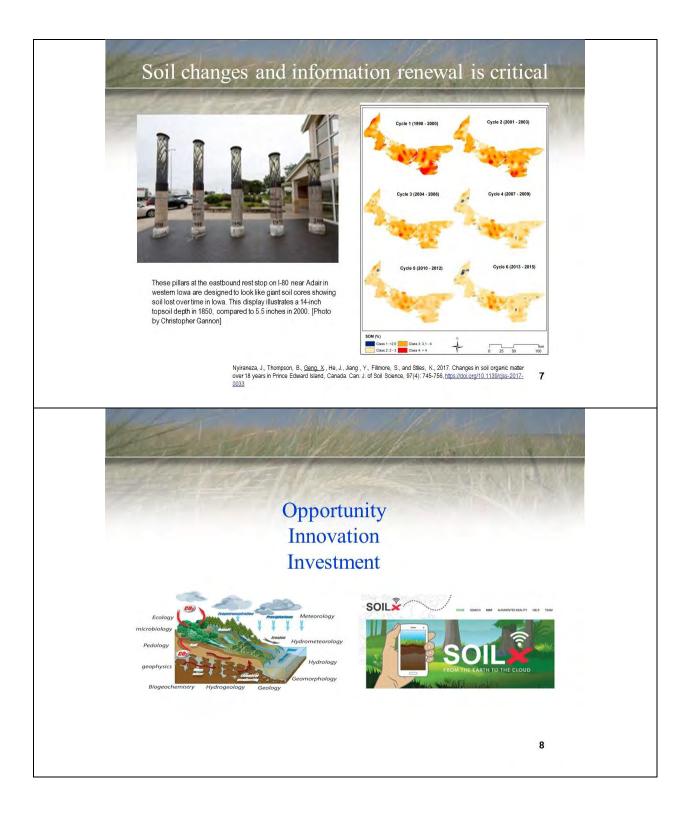




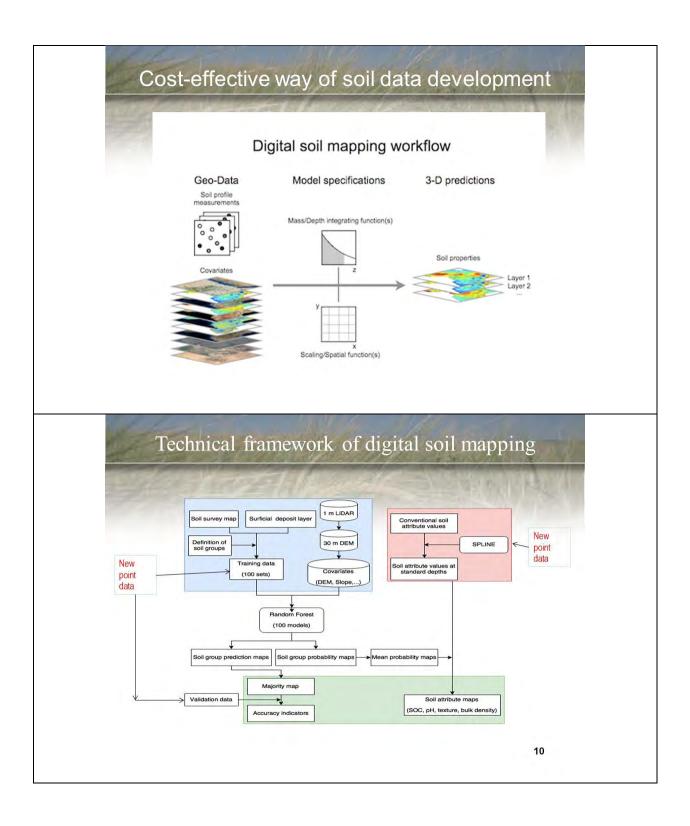




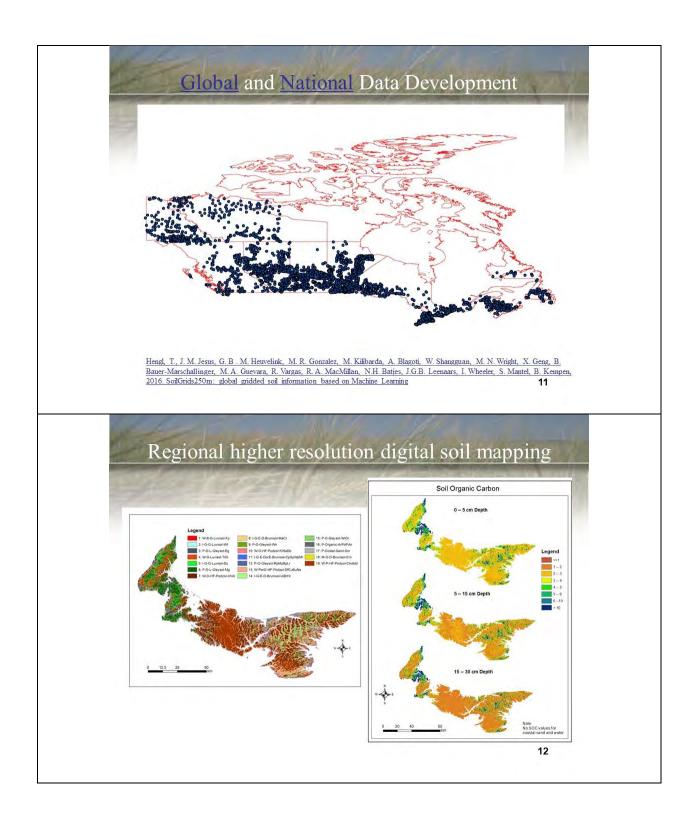






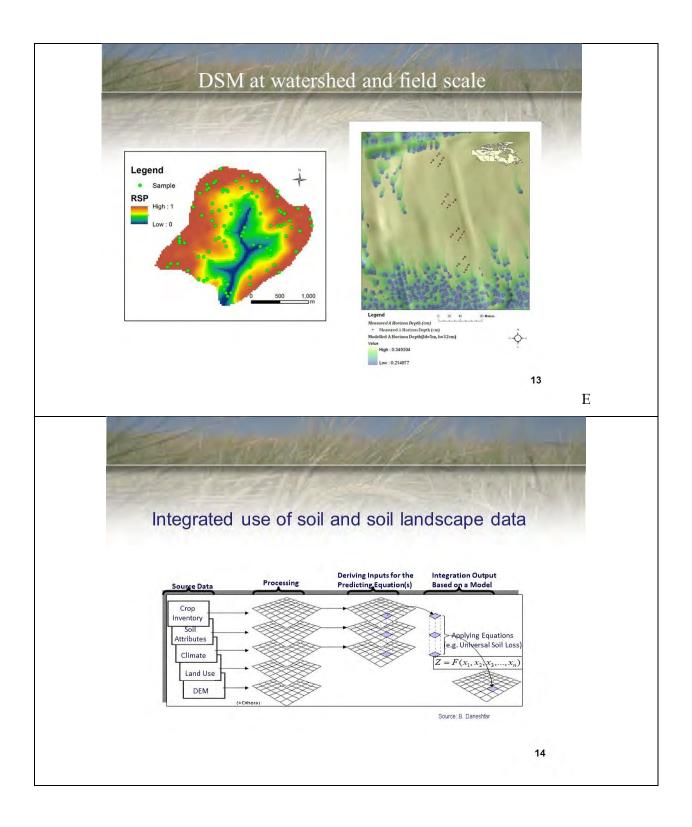




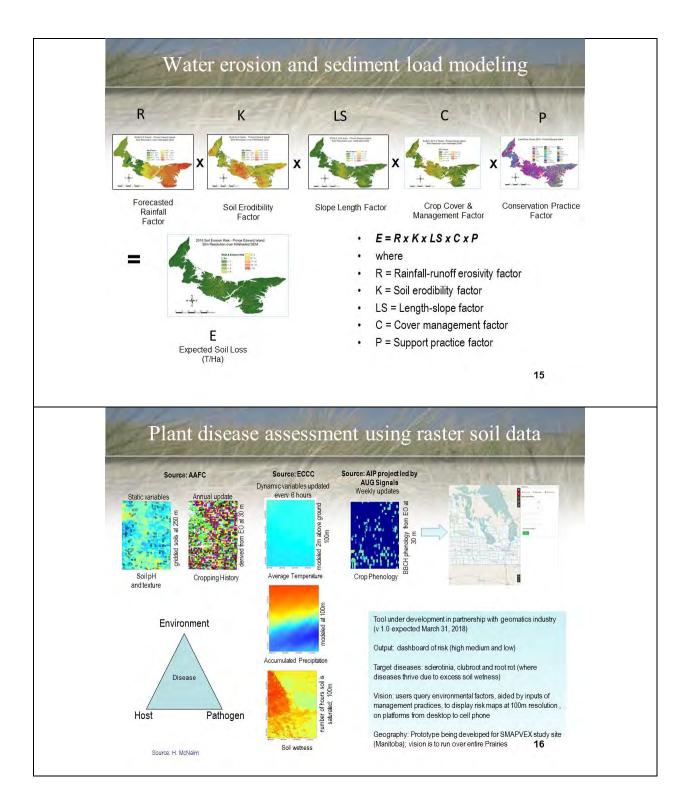


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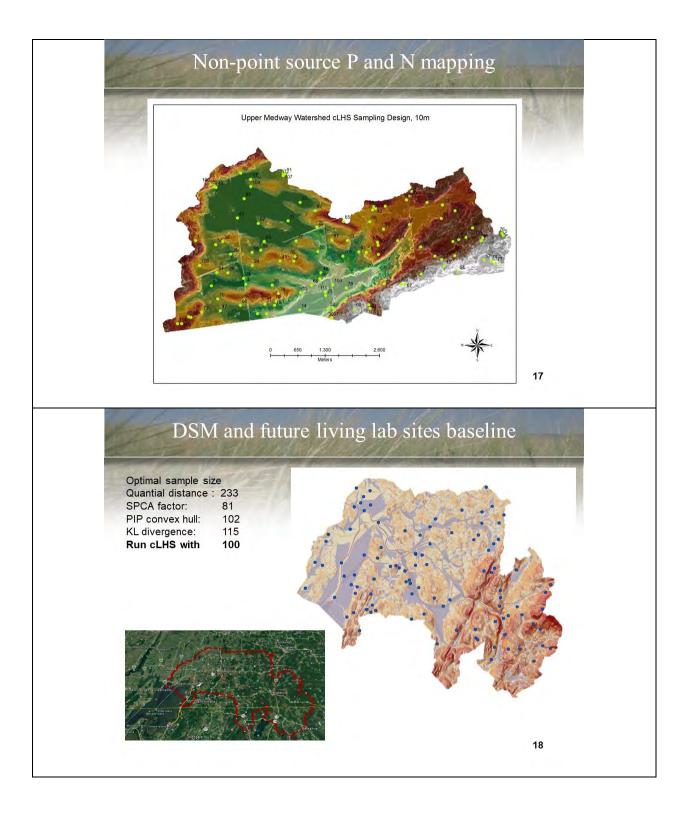




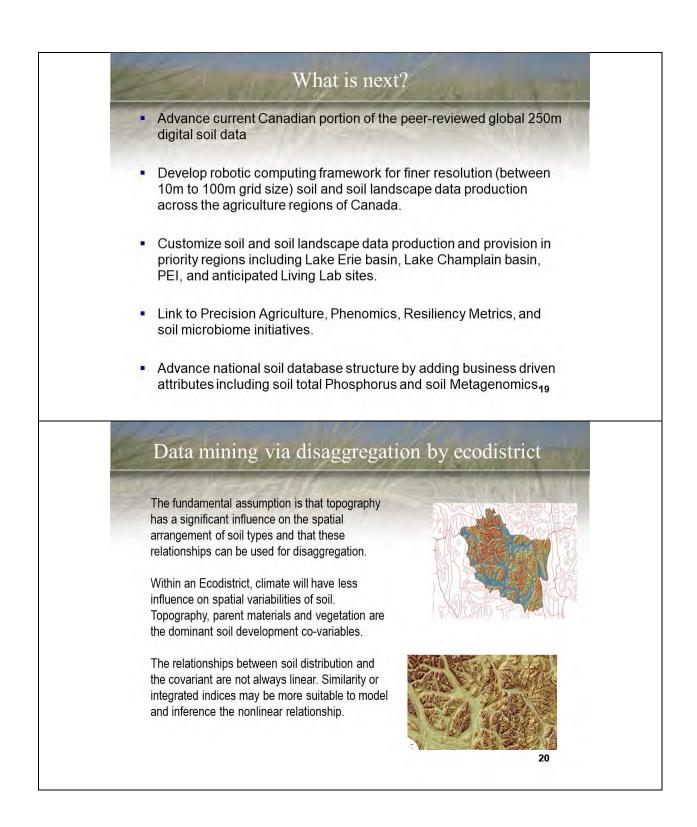




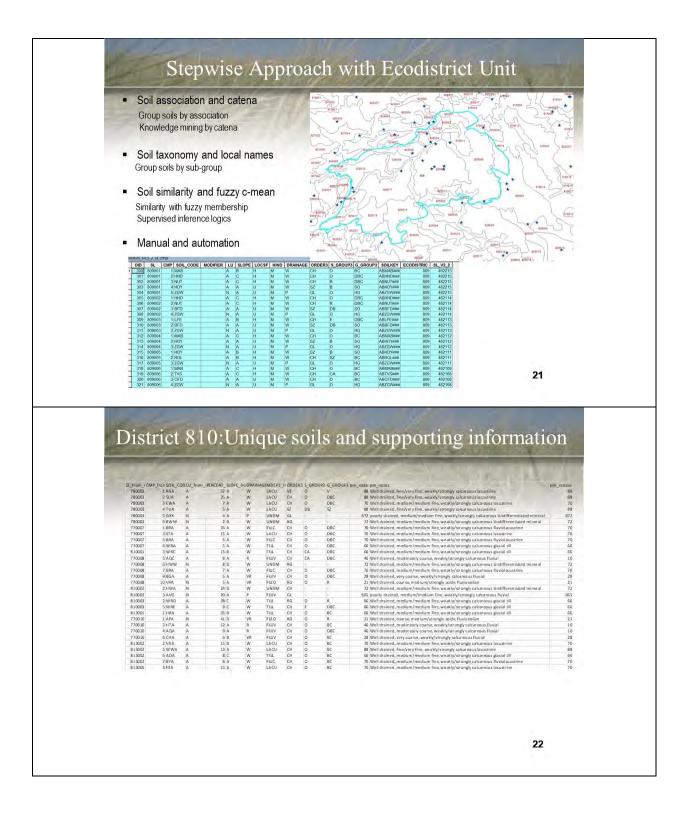








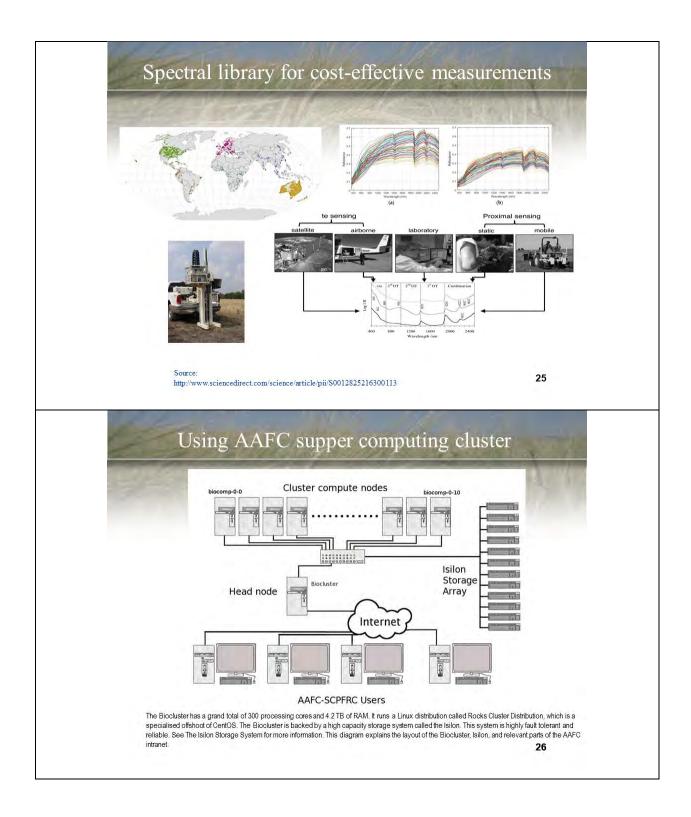




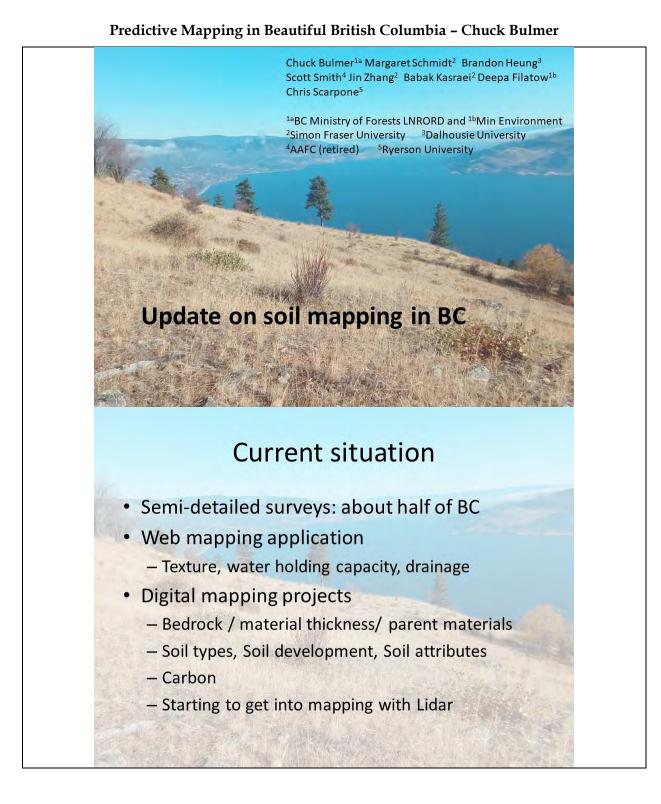




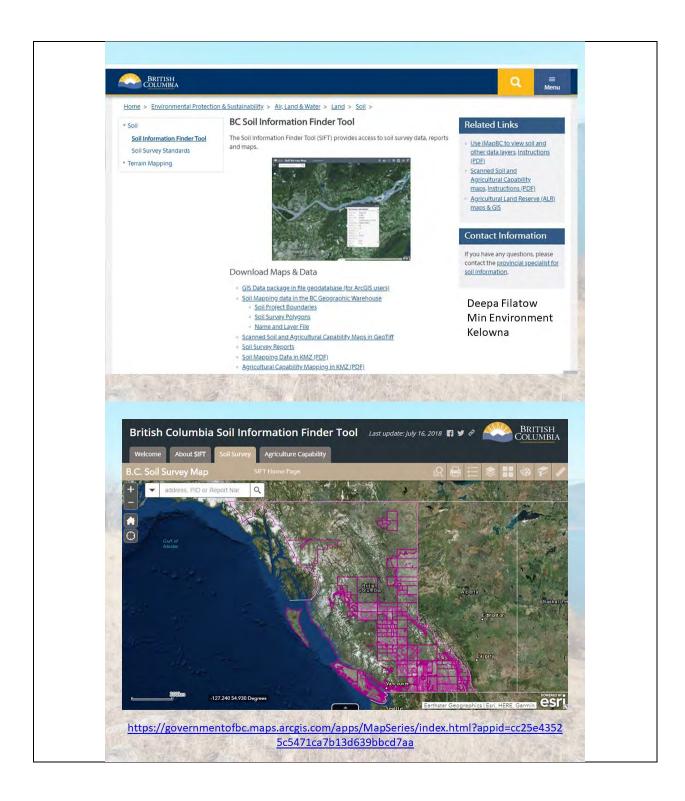




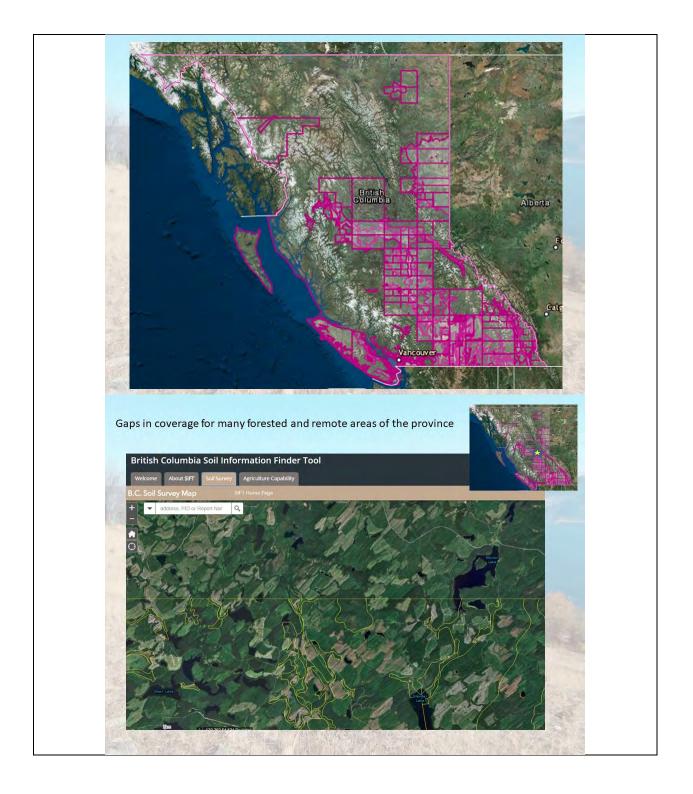




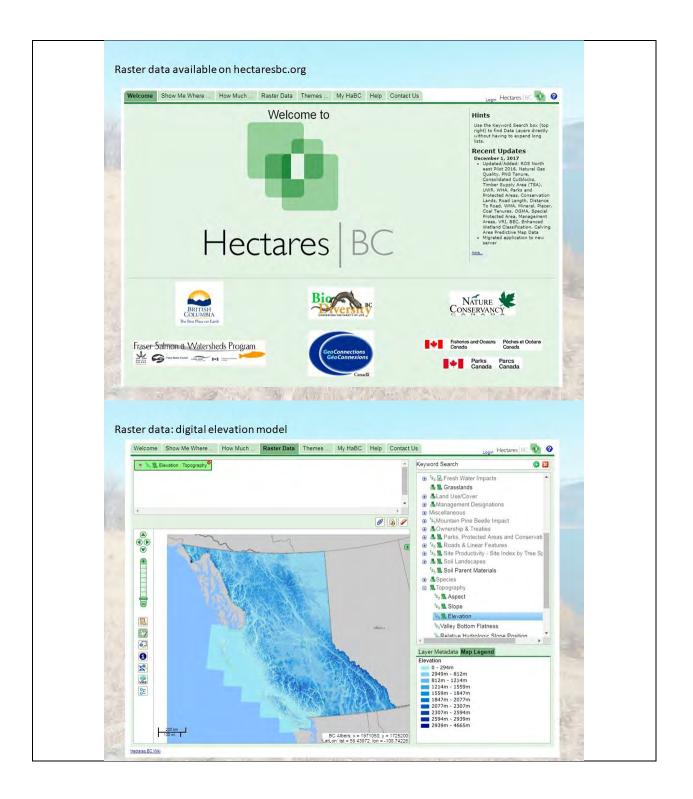




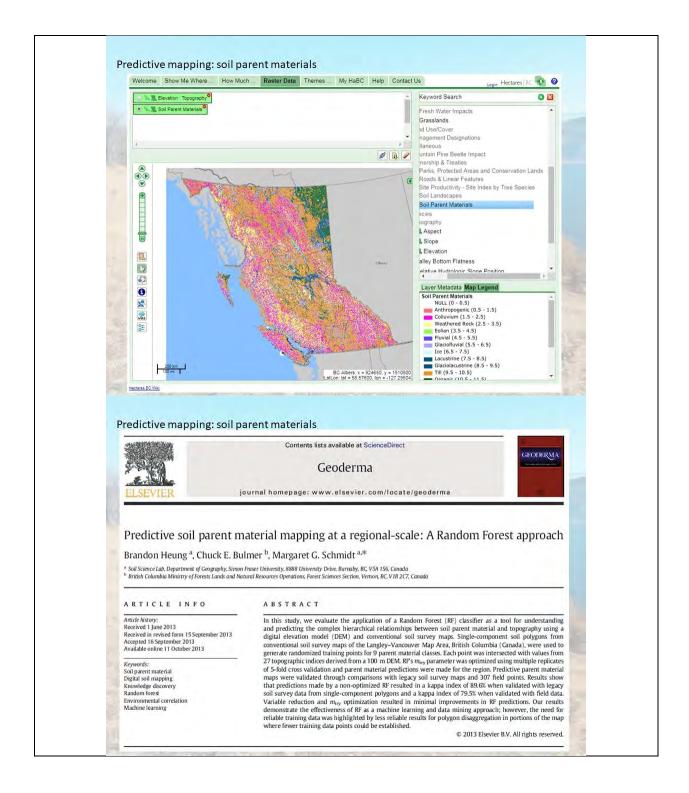




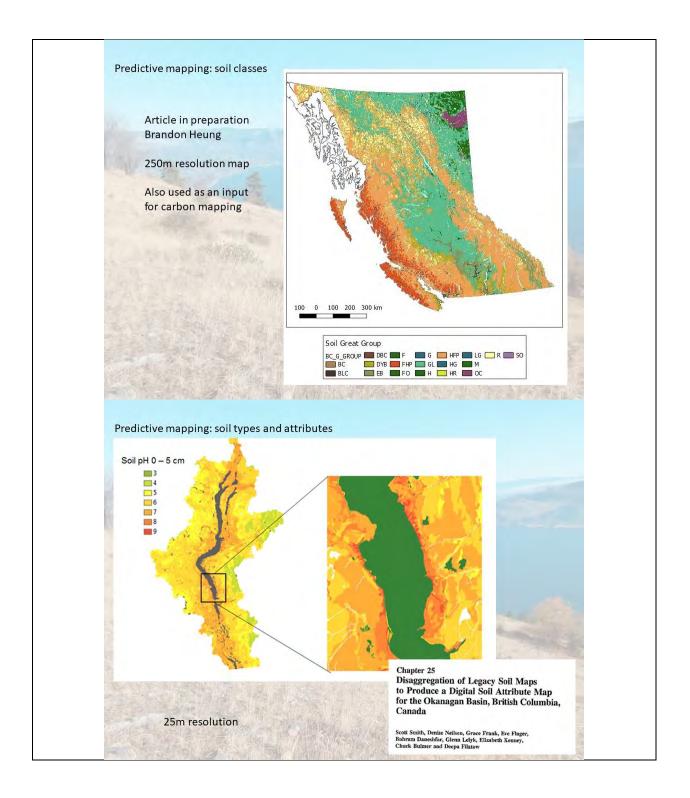




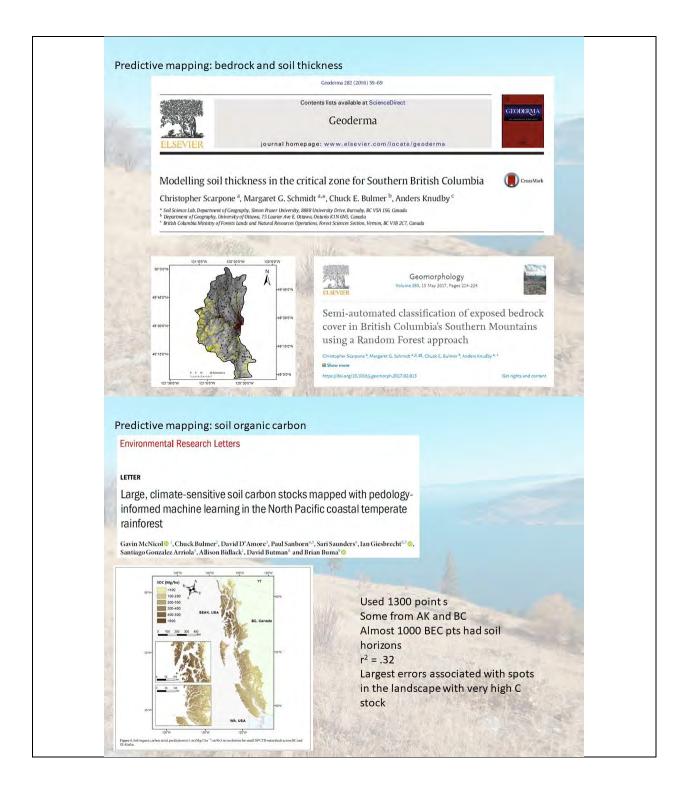




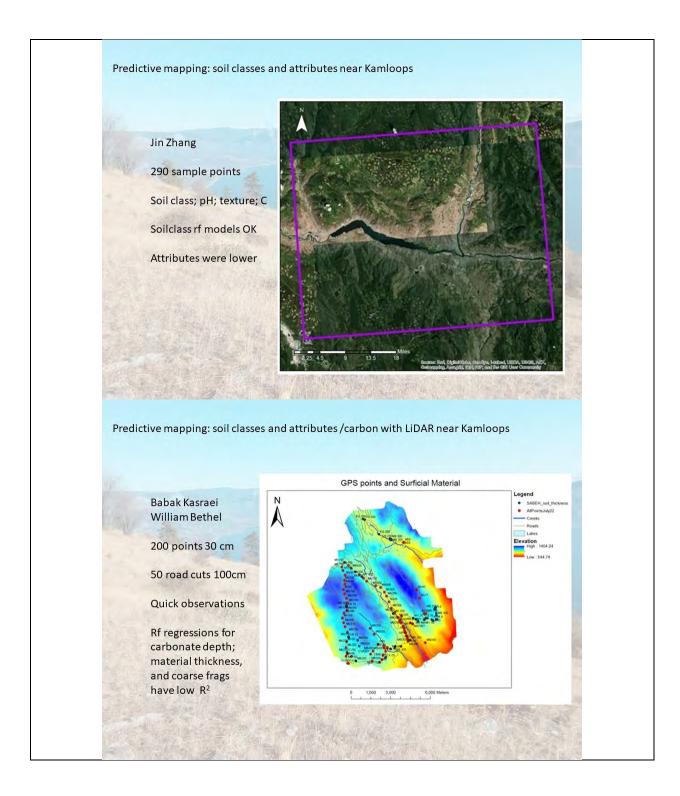




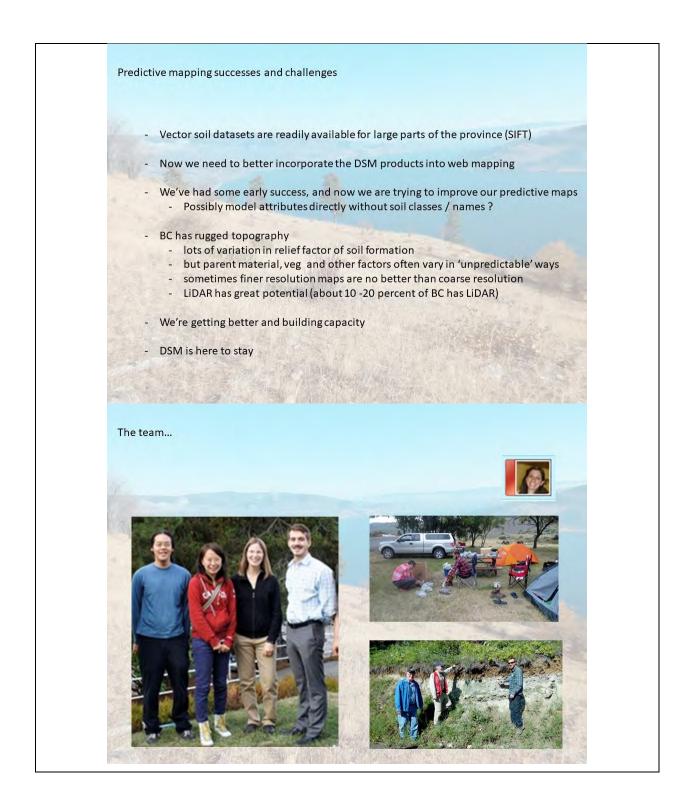














Ensemble Machine Learning as a Framework for PSM – Tom Hengl

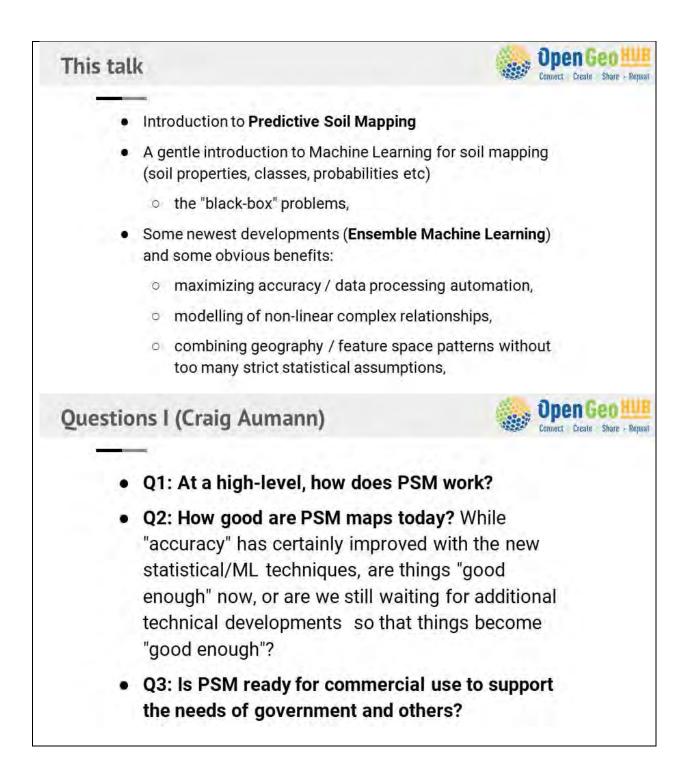
These slides are periodically updated at the following link – <u>https://urldefense.proofpoint.com/v2/url?u=https-</u> <u>3A_docs.google.com_presentation_d_1QstVEF4pVKrntGCmRd9OWIRUSgO0SZfRXgkWoyjfP94_edit-</u> <u>3Fusp-3Dsharing&d=DwID-</u> <u>g&c=Nx4cNT2ND5PKJMUw1Yiqvt5PYVXmyHyY3_zNPmJl6pU&r=Eh0WZEy_sZ0Bli5Pzh7zGn81ISx1CpSbaY</u> WJwZLAAGXAm2j72_VH5SiSG3Ku4GWQ&m=QXDQubowTMU4-pnSyOb5aqFK9N8zii4DXay-

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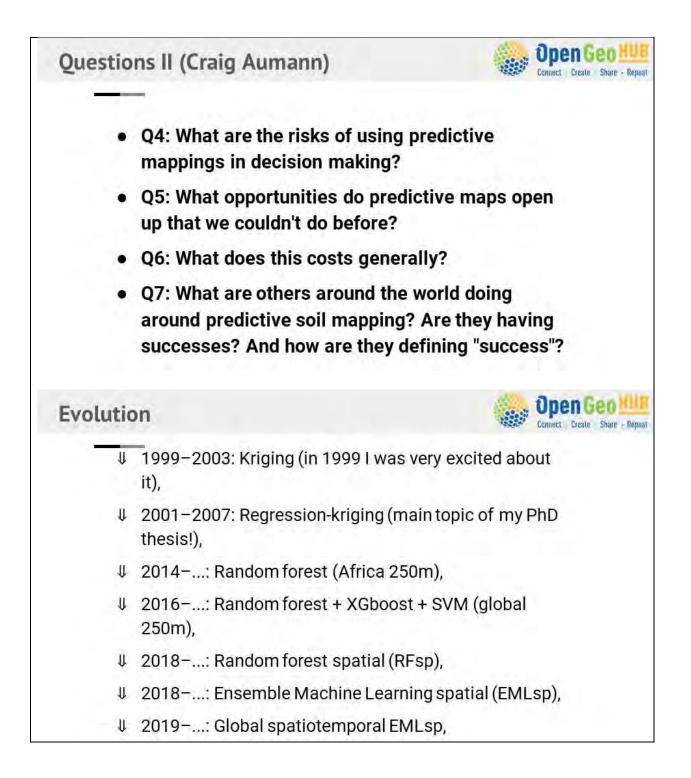








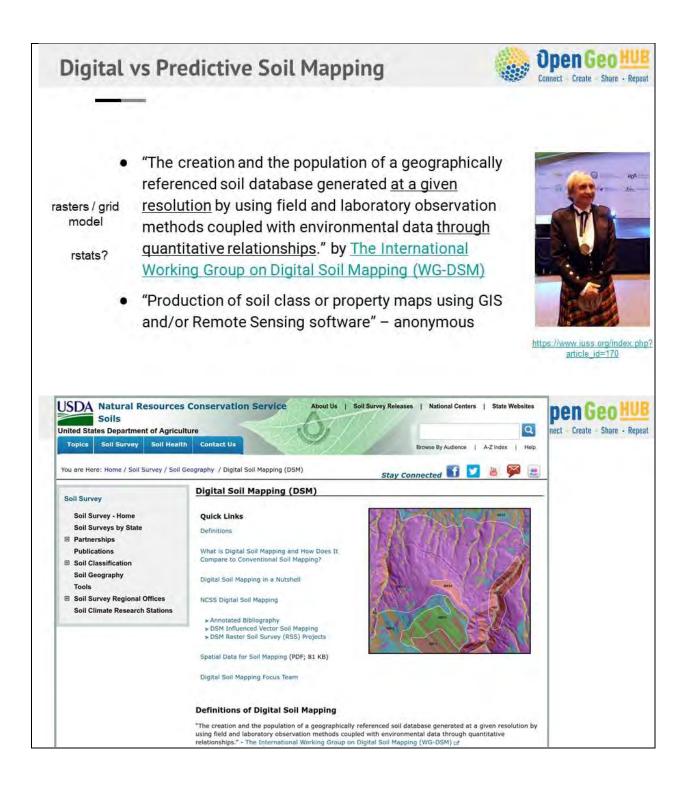




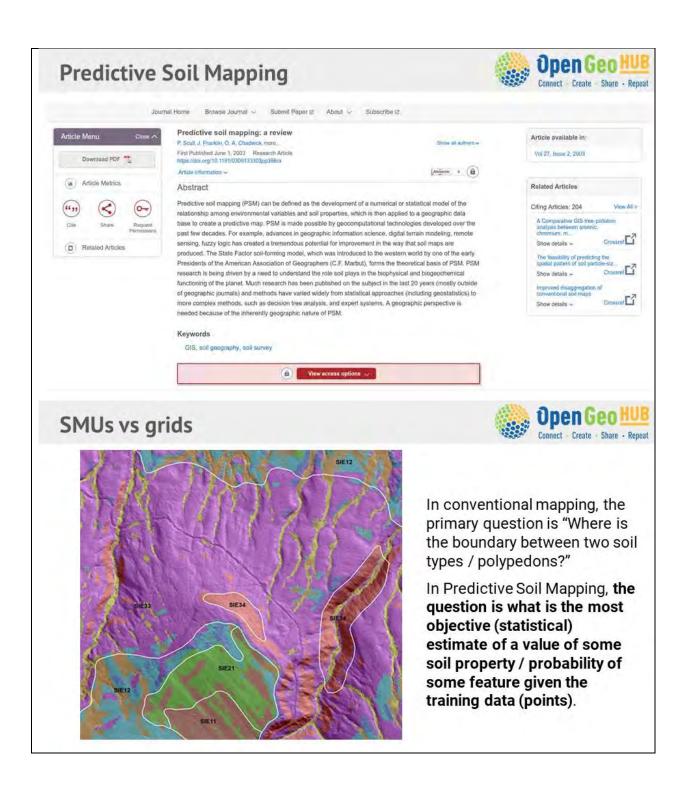


	Predictive Soil Mapping with R by T. (Tom) Hengl and R.A. (Bob) MacMillan Image: Ima	ect Create Share Repeat
	Hengi, T., MacMillan, R.A., (2019). Predictive Soll Mapping with R. OpenGeoHub foundation, Wageningen, the Netherlands, 370 pages, www.sollmapper.org, ISBN: 978-0-359-30635-0. Hard copies of this book can be ordered from www.lulu.comBy purchasing a hard copy of this book from Lulu you donate to the OpenGeoHub foundation. Copyright: © 2019 Authors.	\$12
Predictive Soll Mapping with R		3-(3
Predictive Soll Mapping for advanced R Preface 1 Soil resource inventories and soll maps 2 Software installation and first sleps 3 Soil observations and variables 4 Preparations of soil povariates for soil 5 Statistical theory for predictive soil m 6 Machine Learning Algorithms for soil 6.1 Spatial prediction of soil propert) 6.2 A generic framework for spatial 6.3 Summary points 7 Spatial prediction and assessment of 8 Practical tips for organizing Predictive 9 The future of predictive soil mapping References 7. (Tom) Hengl and R.A. (Bob) MacMillan	6 Machine Learning Algorithms for soil mapping Edited by: T. Heng! 6.1 Spatial prediction of soil properties and classes un MLA's This chapter reviews some common Machine learning algorithms (MLA's) that have demons potential for soil mapping projects i.e. for generating spatial predictions (Brungard et al. 2019) al. 2016; Thorsten Behrens et al. 2018). In this tutorial we especially focus on using tree-bas such as random forest, gradient boosting and Cubist. For a more in-depth overview of mach algorithms used in statistics refer to the CRAN Task View on Machine Learning & Statistical Some other examples of how MLA's can be used to fit Pedo-Transfer-Functions can be foun (J). 6.1.1 Loading the packages and data We start by loading all required packages. 1.116regr(platcH2) (= plator(), for 2010 (0, 5.47) (2010 -0.47)) (= plator(), for 2010 (0, 5.47) (2010 -0.47)) (= plator(), for 2010 (0, 5.47) (2010 -0.47)) (= plator(), for 2010 (0, 5.47) (2010 -0.47))	Ising Itrated 5; Heung et sed algorithms ine learning Learning.











CLORPT



- Theoretically speaking, PSM is largely based on CLORPT.
- where cl stands for climate, o for organisms (including humans), r is relief, p is parent material or geology and t is time (originally presented by Jenny; 1994).

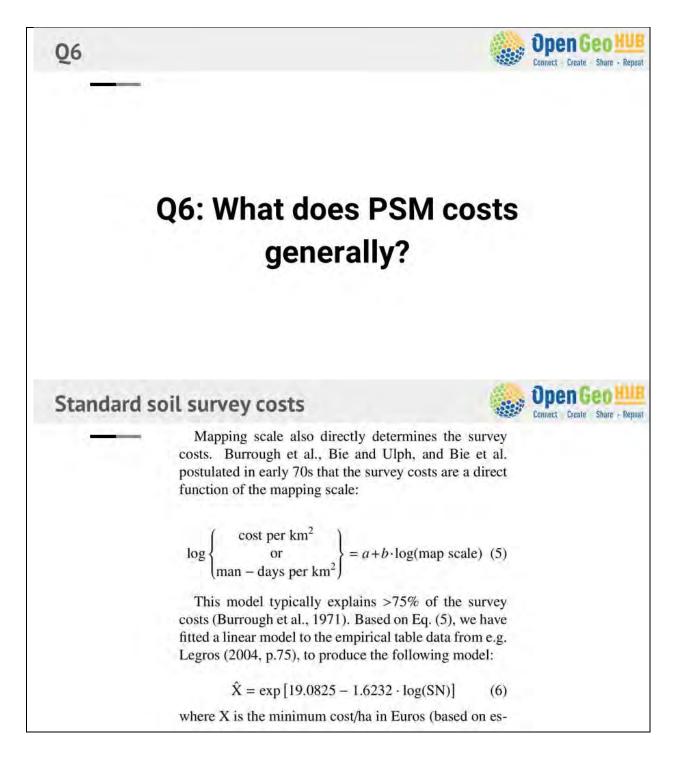


PSM basic concepts

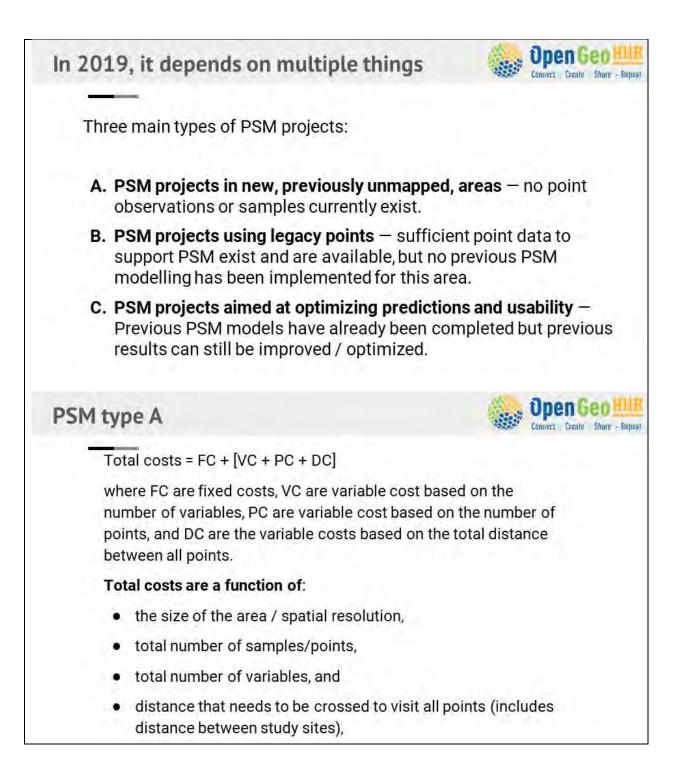


- In statistical terms, the main objective of soil mapping is to describe the spatial complexity of soils, then represent this complexity using maps, summary measures, mathematical models and simulations. From the application point of view, the main application objective of soil mapping is to accurately predict response of a soil(-plant) ecosystem to various soil management strategies.
- The objective of PSM is to produce optimal unbiased predictions of a mean value at some new location along with the uncertainty associated with the prediction, at the finest possible resolution.

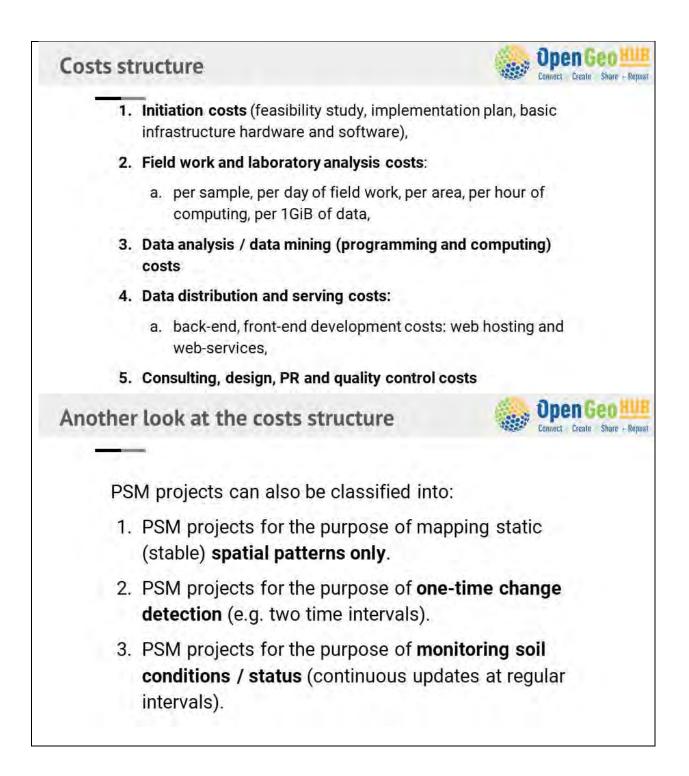




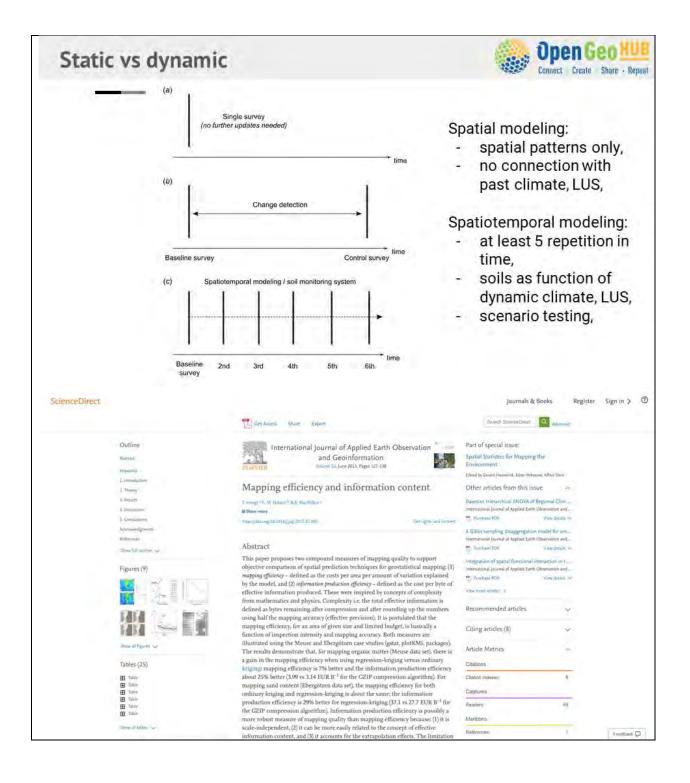




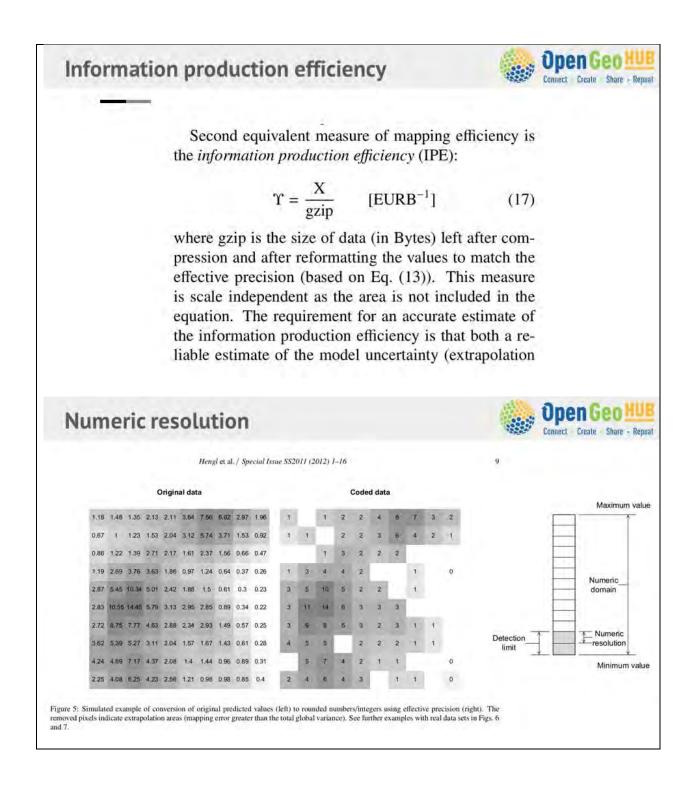




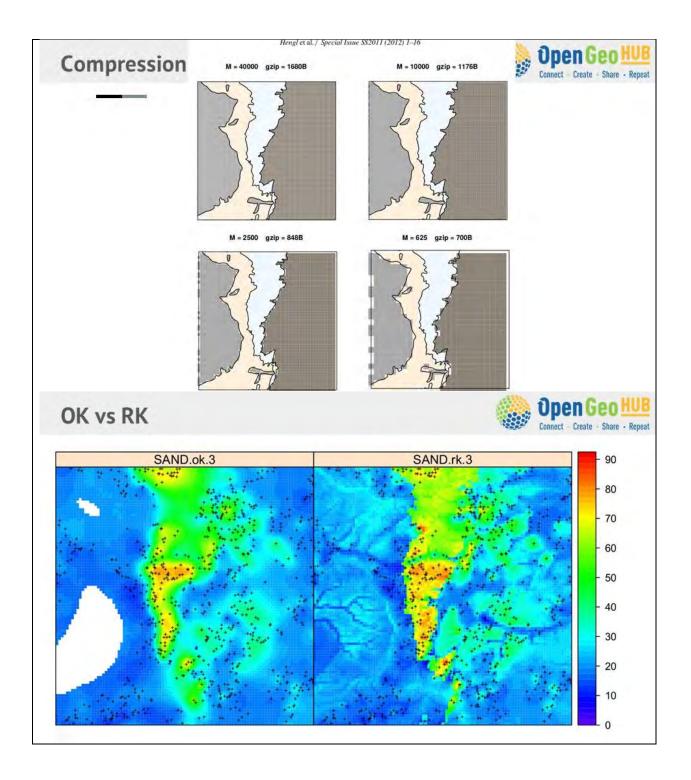




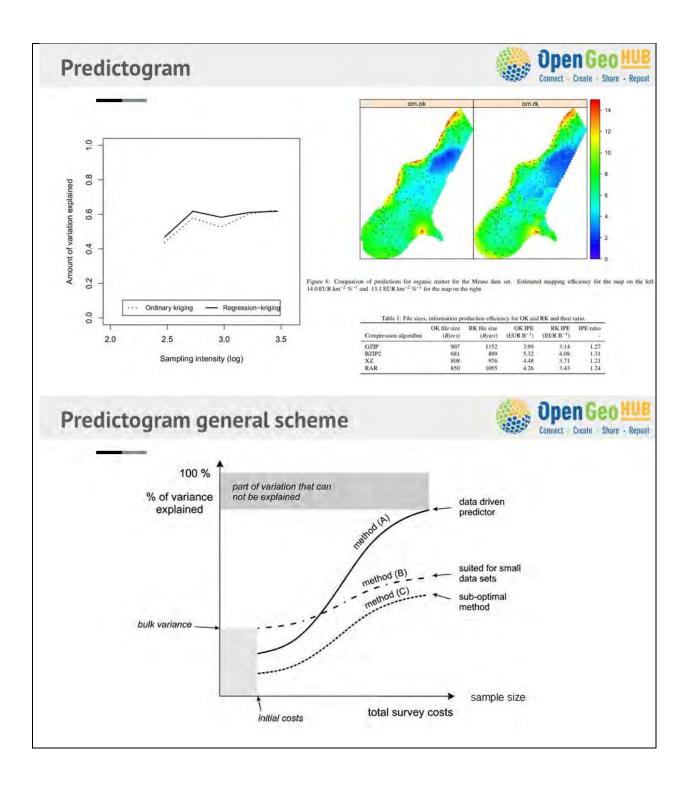




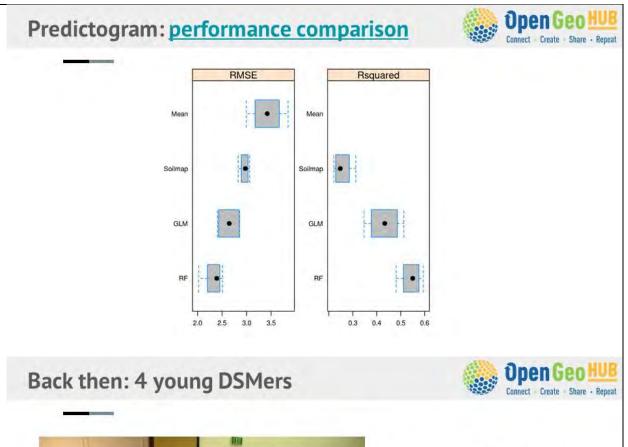












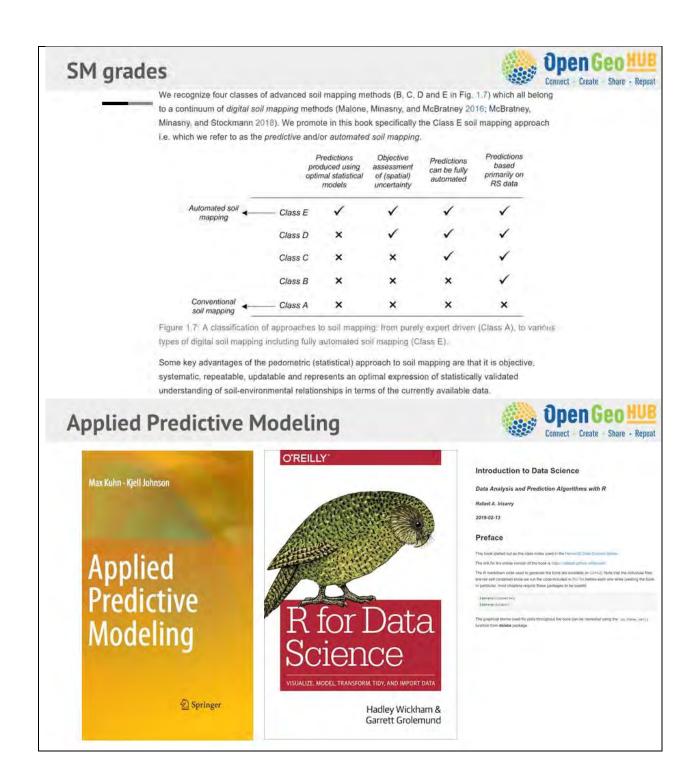


A conventional soil mapper (CSMer) knows how to draw polygon maps.

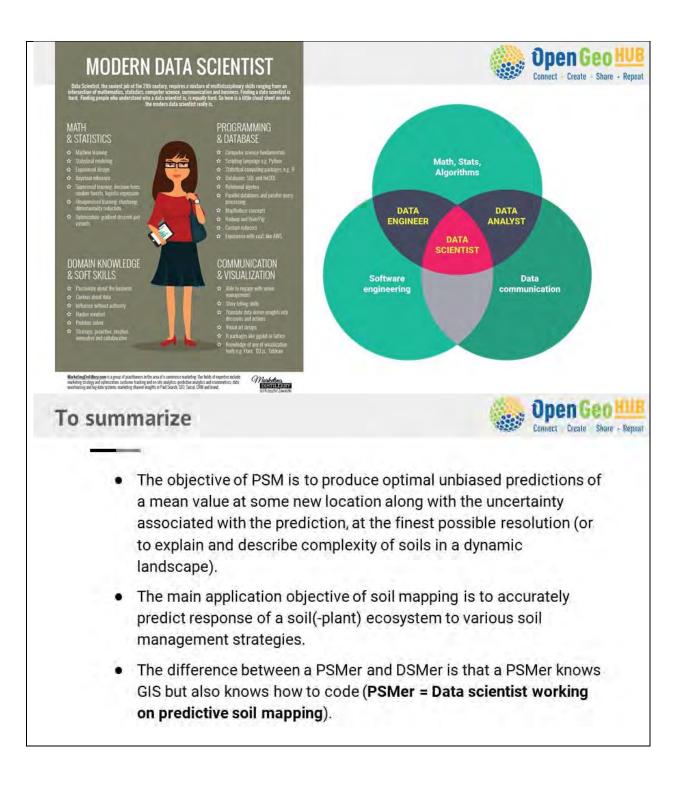
The difference between a CSMer and a digital soil mapper (DSMer) is that a DSMer knows how to use GIS.

The difference between a DSMer and PSMer is that **a PSMer knows how to code** (R, Python, Julia etc)!

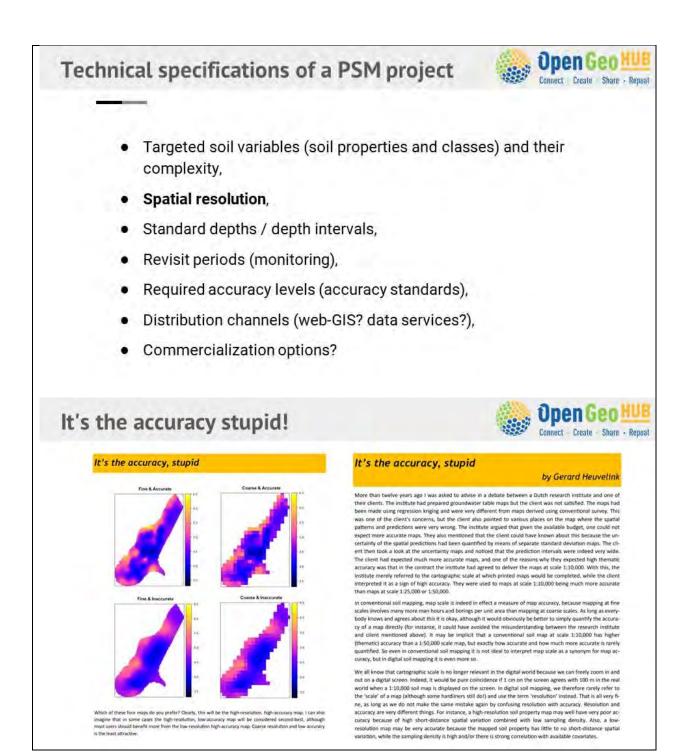














Success of a PSM project



It is NOT only about thematic accuracy! Success of soil maps is typically a product of multiple things:

= relevance for decision making / spatial planning × level of detail (spatial accuracy) × thematic (attribute) accuracy × completeness × consistency × accessibility × price

= RELEVANCE × LA × TA × COMP × CONS × ACCESS × PRICE

http://www.pedometrics.org/Pedometron/Pedometron38.pdf

Regression-kriging



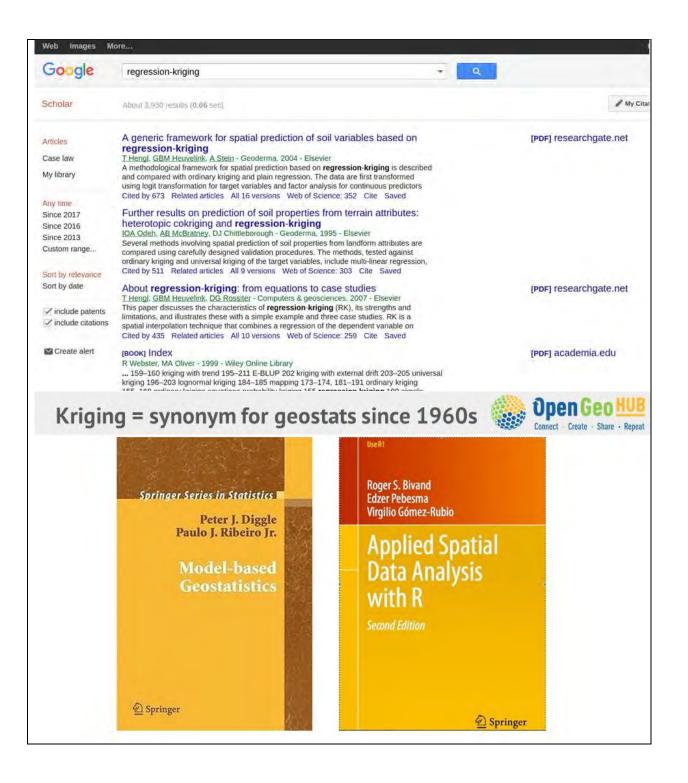
5.2.5 Regression-kriging (generic model)

Ignoring the assumptions about the cross-correlation between the trend and residual components, we can extend the regression-kriging model and use any type of (non-linear) regression to predict values (e.g. regression trees, artificial neural networks and other machine learning models), calculate residuals at observation locations, fit a variogram for these residuals, interpolate the residuals using ordinary or simple kriging, and add the result to the predicted regression part. This means that RK can, in general, be formulated as:

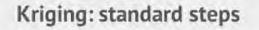
> $\label{eq:prediction} {\rm prediction} \ = \ \frac{{\rm trend\ predicted}}{{\rm using\ regression}} \ + \ \frac{{\rm residual\ predicted}}{{\rm using\ kriging}}$ (5.15)

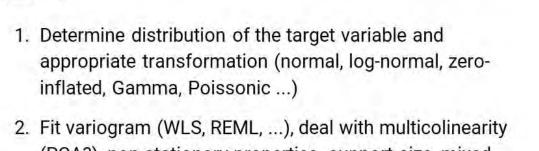
Again, statistical inference and prediction is relatively simple if the stochastic residual, or a transformation thereof, may be assumed normally distributed. Error of the regression-kriging model is likewise a sum of the regression and the kriging model errors.











- (PCA?), non-stationary properties, support size, mixed effects...
- 3. Predict (mean values and uncertainty)
- 4. Validate predictions (mapping accuracy)

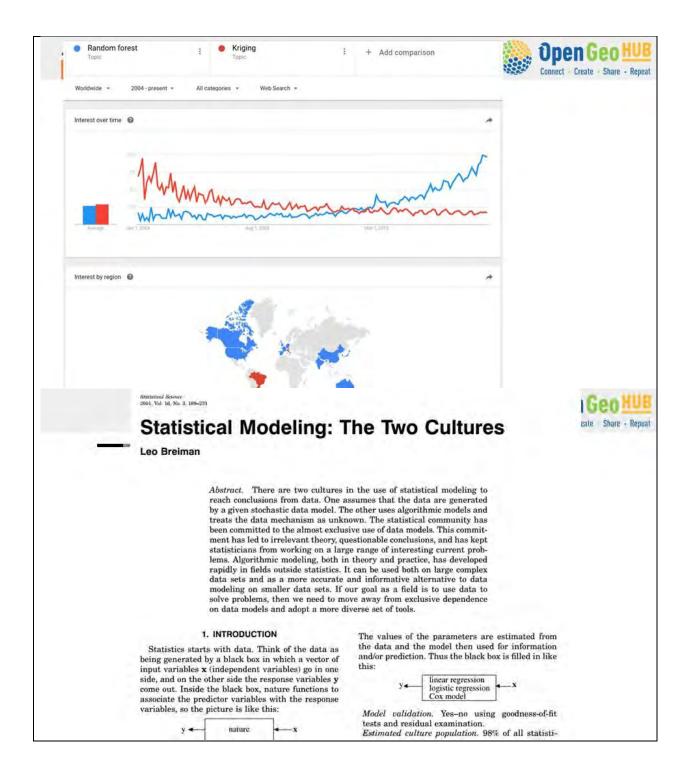
Variogram modeling and kriging

```
R> zinc.vgm <- likfit(zinc.geo, lambda = 0,
ini=c(var(log1p(zinc.geo$data)), 500), cov.model
= "exponential")
```

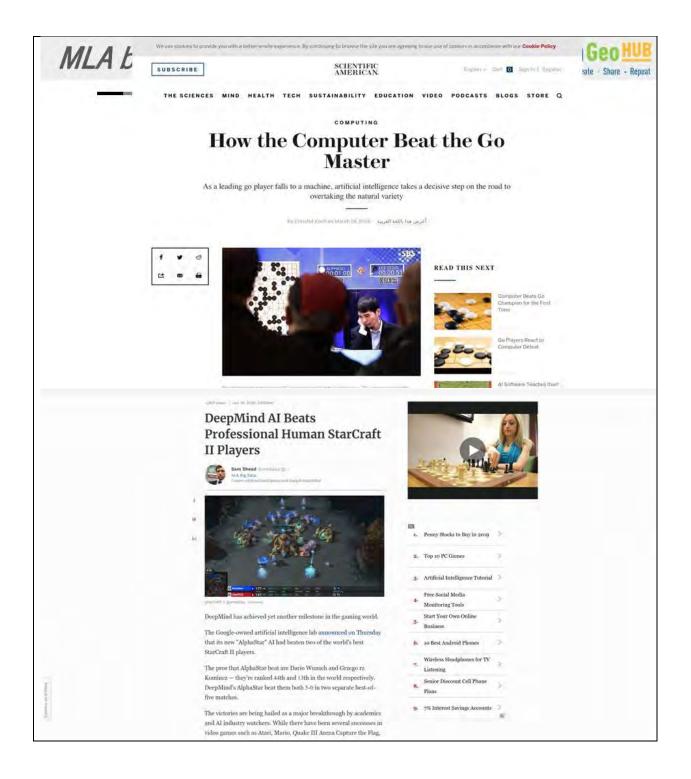
```
R> zinc.ok <- krige.conv(zinc.geo, locations =
locs, krige = krige.control(obj.m = zinc.vgm))
```

krige.conv: model with constant mean krige.conv: performing the Box-Cox data transformation krige.conv: back-transforming the predicted mean and variance krige.conv: Kriging performed using global neighbourhood





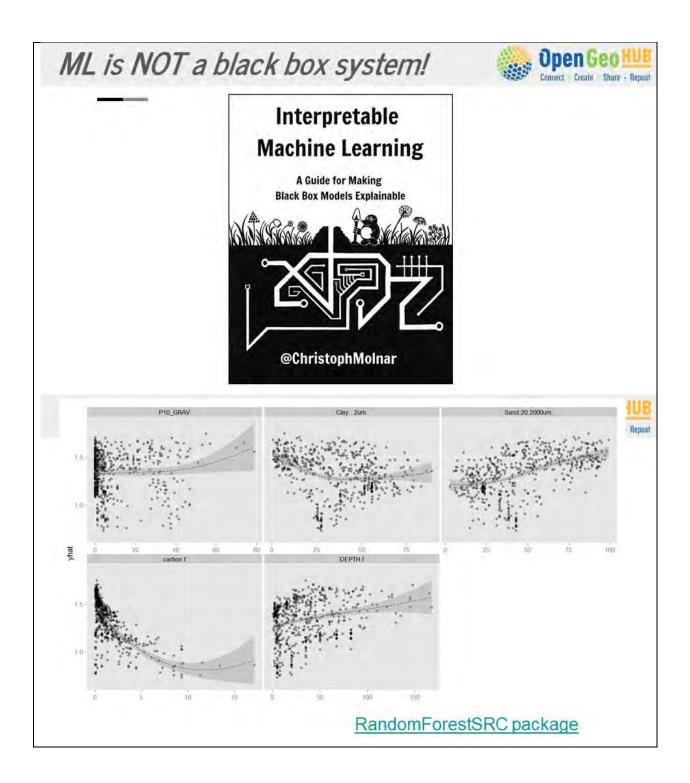




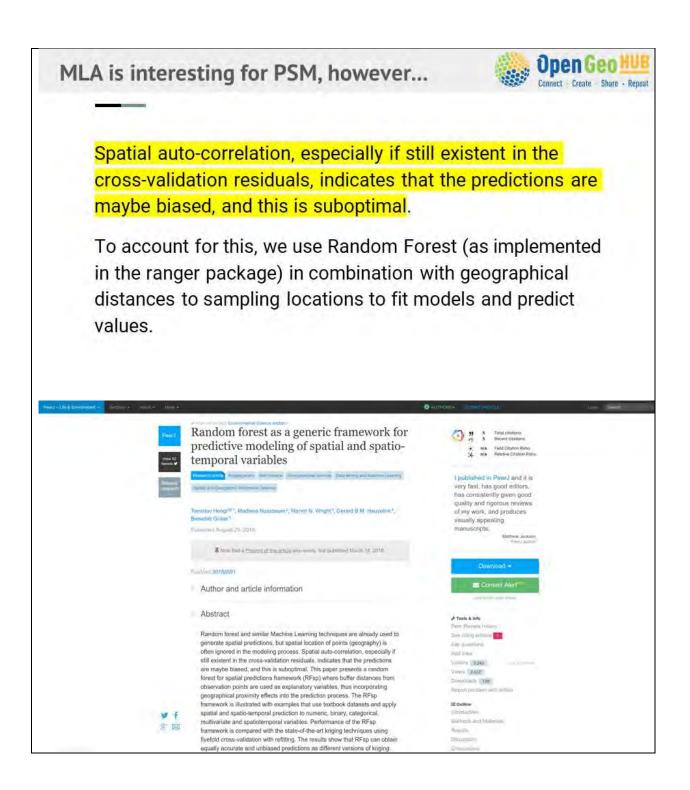


















Solution: RFsp

$$Y(\mathbf{s}) = f(\mathbf{X}_G, \mathbf{X}_R, \mathbf{X}_P)$$
(18)

where \mathbf{X}_{G} are covariates accounting for geographical proximity and spatial relations between observations

$$\mathbf{X}_G = (d_{p1}, d_{p2}, \dots, d_{pN}) \tag{19}$$

where d_{pi} is the buffer distance (or any other complex proximity upslope/downslope distance, as explained in the next section) to the observed location pi from s and N is the total number of training points. \mathbf{X}_R are surface reflectance covariates, i.e. usually spectral bands of remote sensing images, and \mathbf{X}_P are process-based covariates.

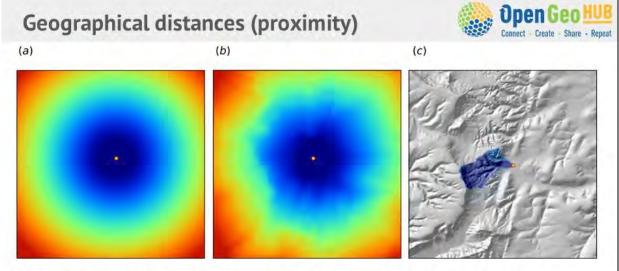
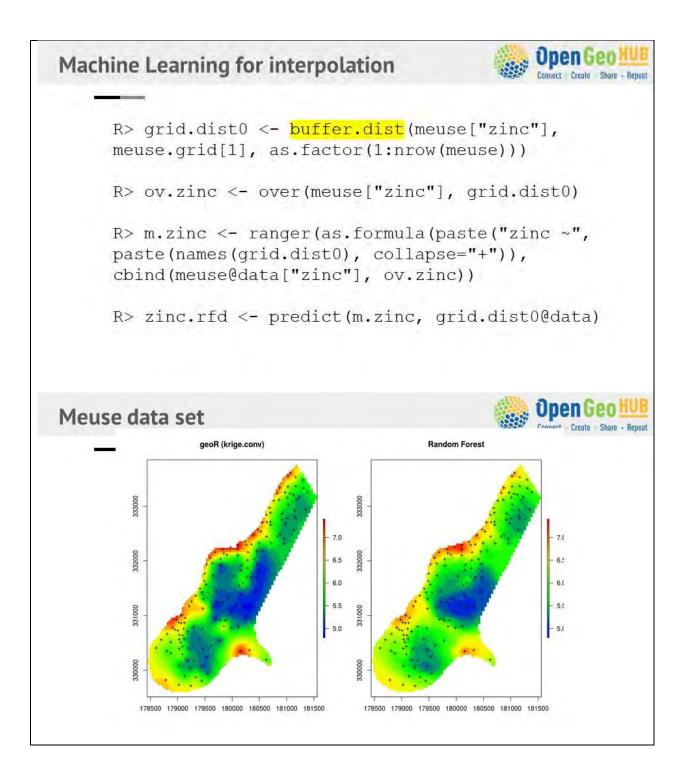
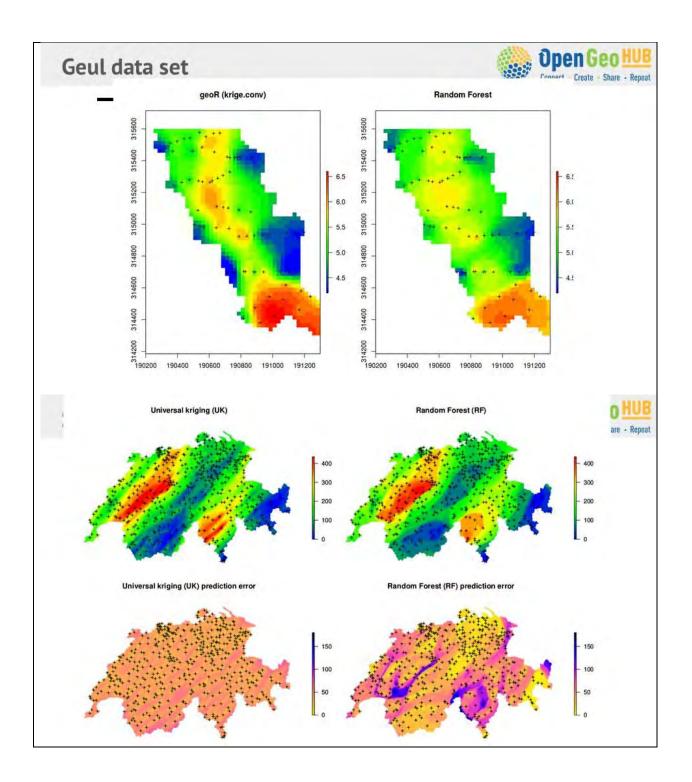


Figure 2. Examples of distance maps to some location in space (yellow dot) based on different derivation algorithms: (a) simple Euclidean distances, (b) complex speed-based distances based on the gdistance package and Digital Elevation Model (DEM) (van Etten, 2017), and (c) upslope area derived based on the DEM in SAGA GIS (Conrad et al., 2015). Case study: Ebergötzen (Böhner et al., 2006).

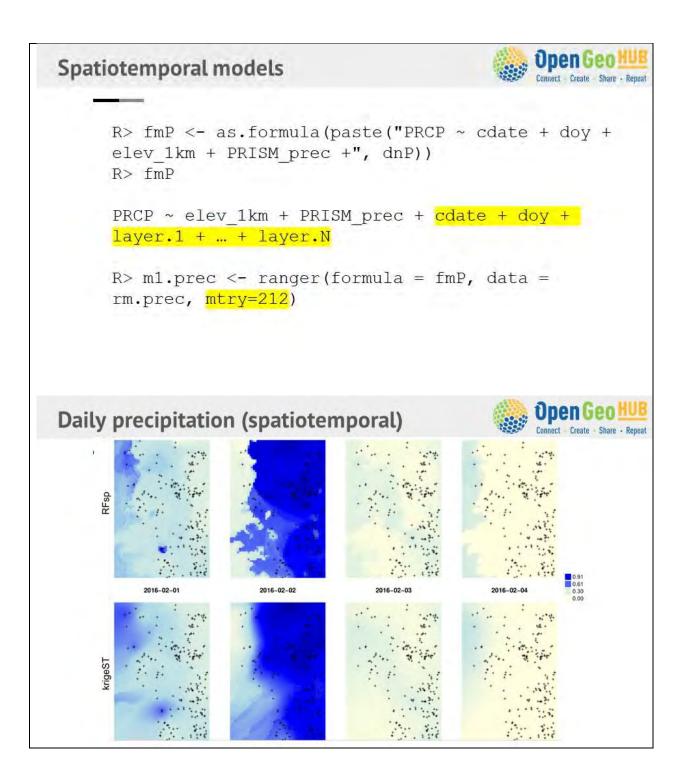




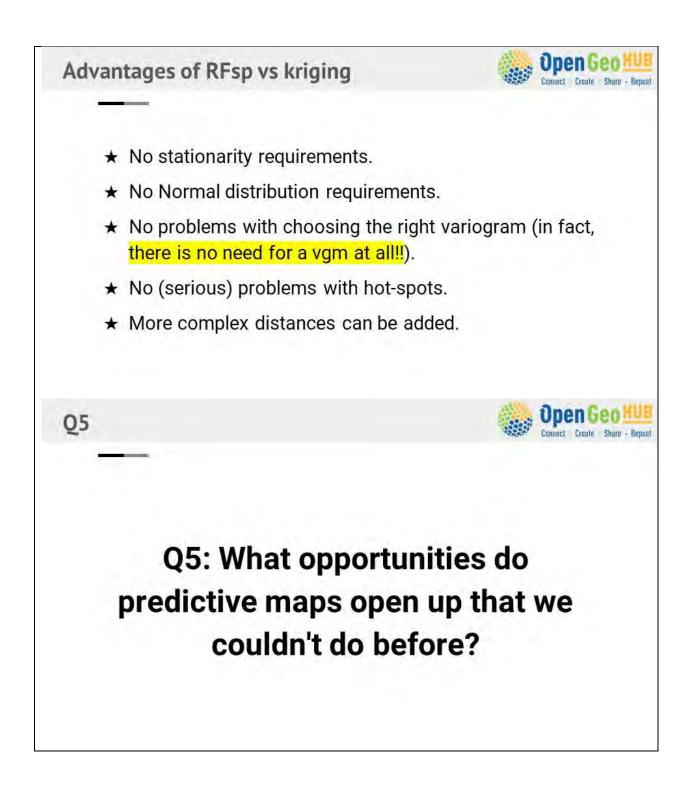




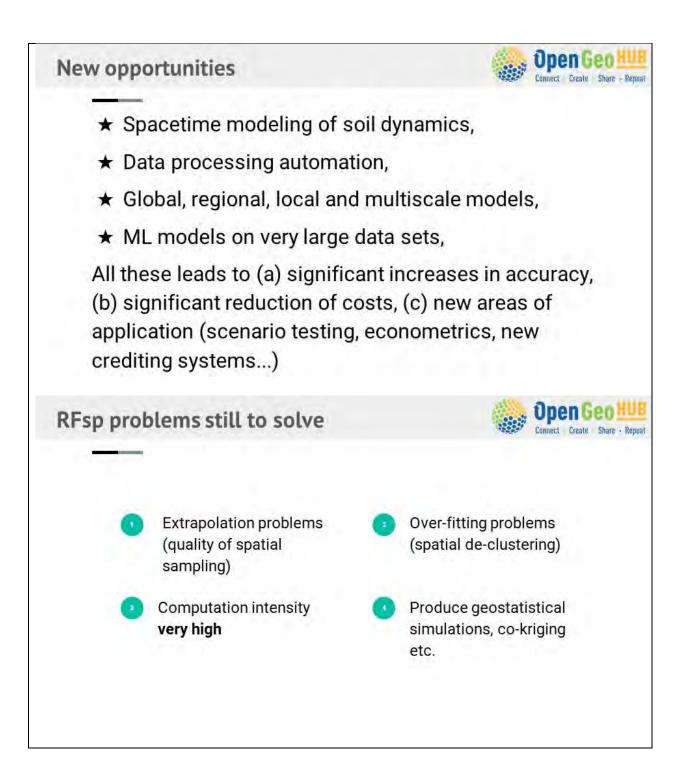




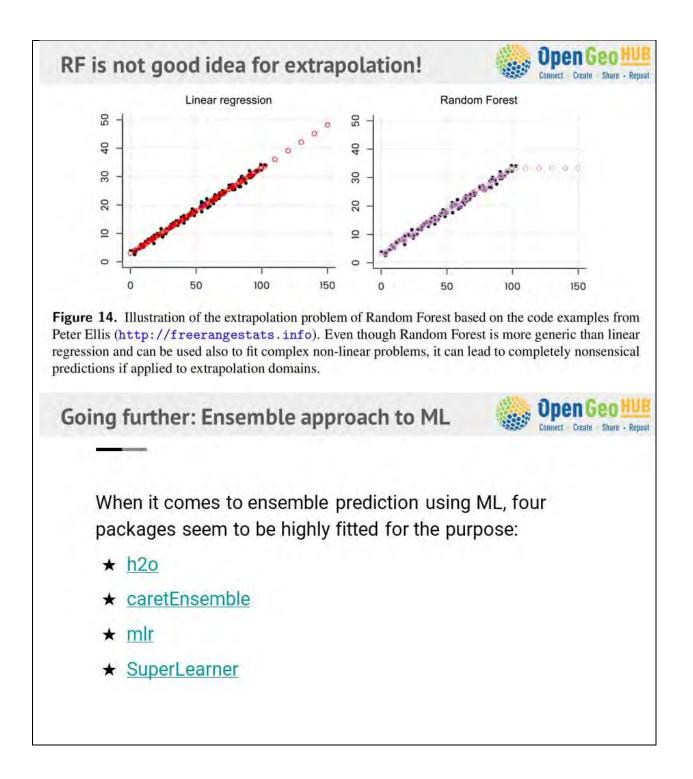




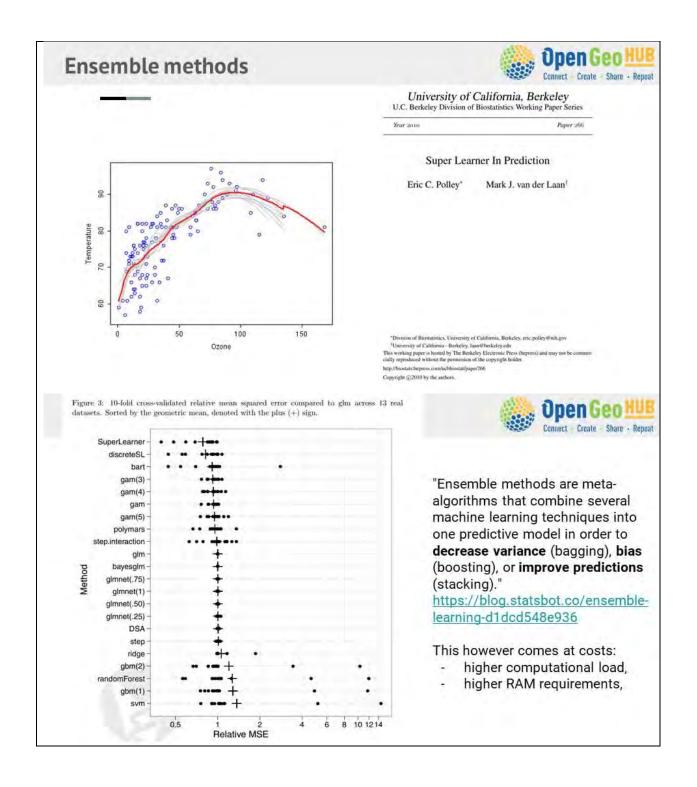




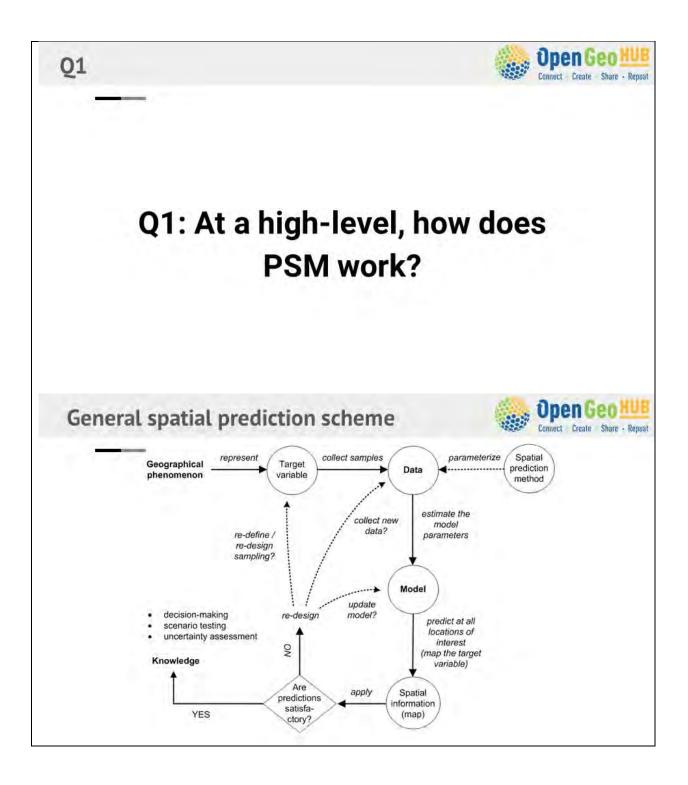




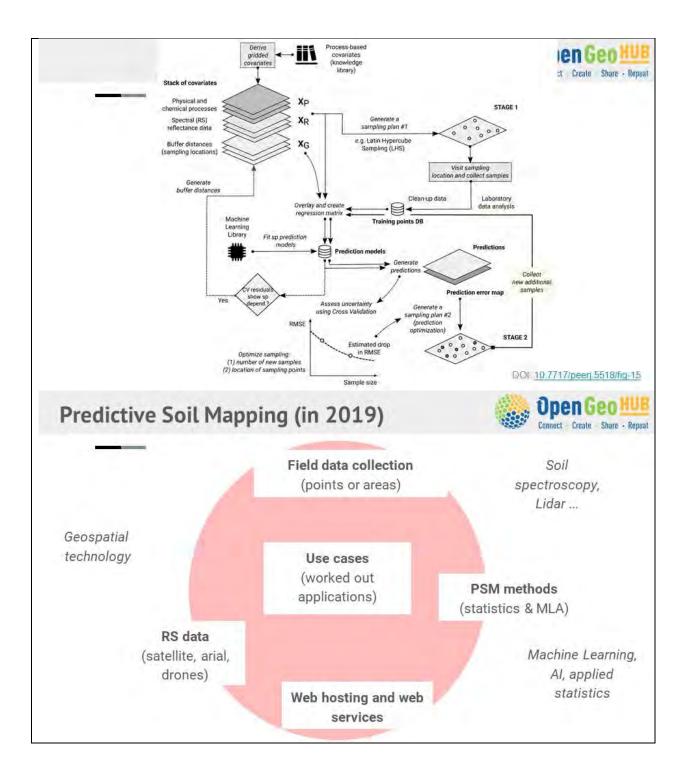




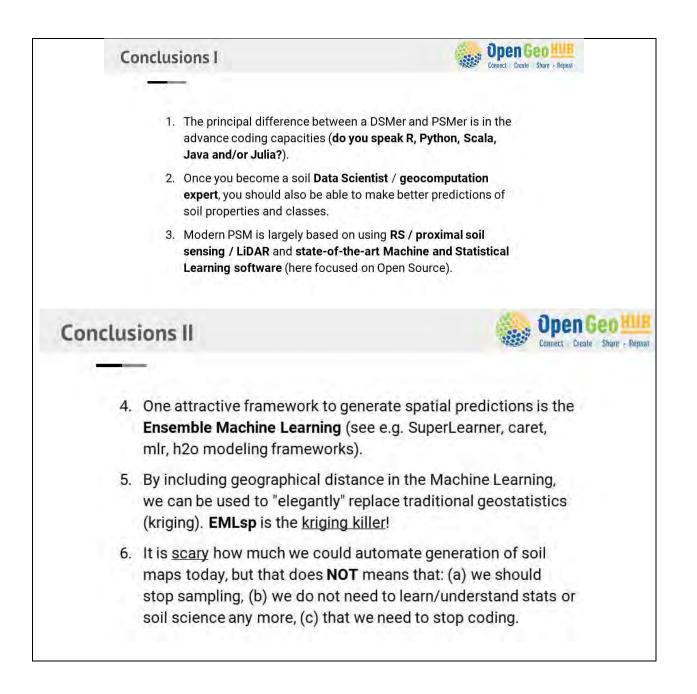




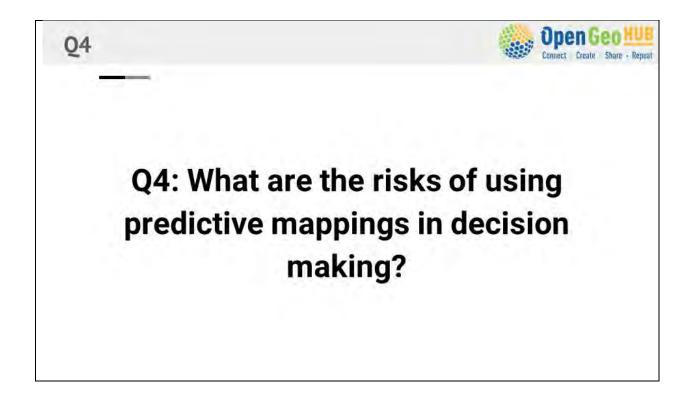














Technological and methodological advances in soil mapping and monitoring and opportunities for Alberta / Canada – Tom Hengl

These slides are periodically updated at the following link – https://urldefense.proofpoint.com/v2/url?u=https-

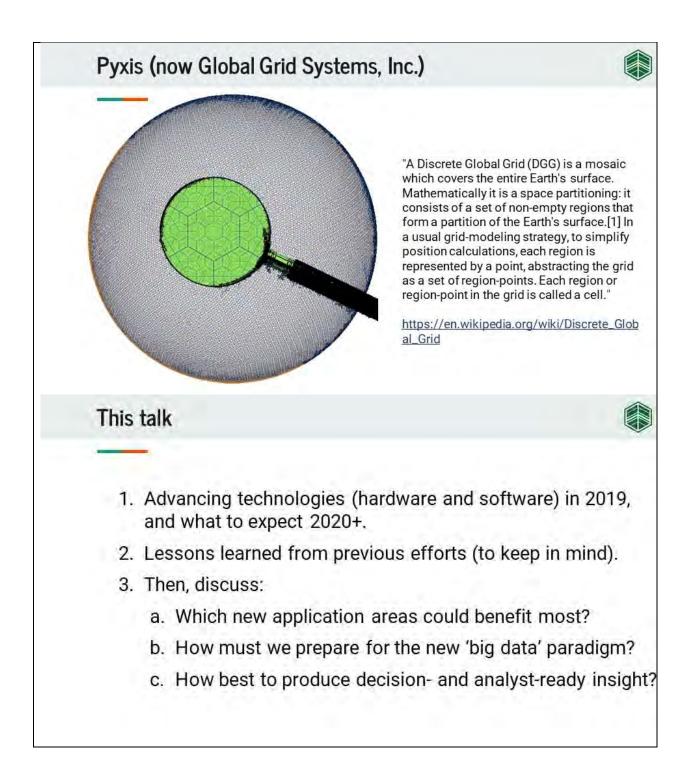
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<u>g&c=Nx4cNT2ND5PKJMUw1Yiqvt5PYVXmyHyY3_zNPmJl6pU&r=Eh0WZEy_sZ0Bli5Pzh7zGn81ISx1CpSbaY</u> <u>WJwZLAAGXAm2j72_VH5SiSG3Ku4GWQ&m=QXDQubowTMU4-pnSyOb5aqFK9N8zii4DXay-</u> <u>DWYvTu0&s=9dIFUdIX4JvofmBfvO-YM7vRFcOtdJ0Crhkh4N4LTwM&e=</u>

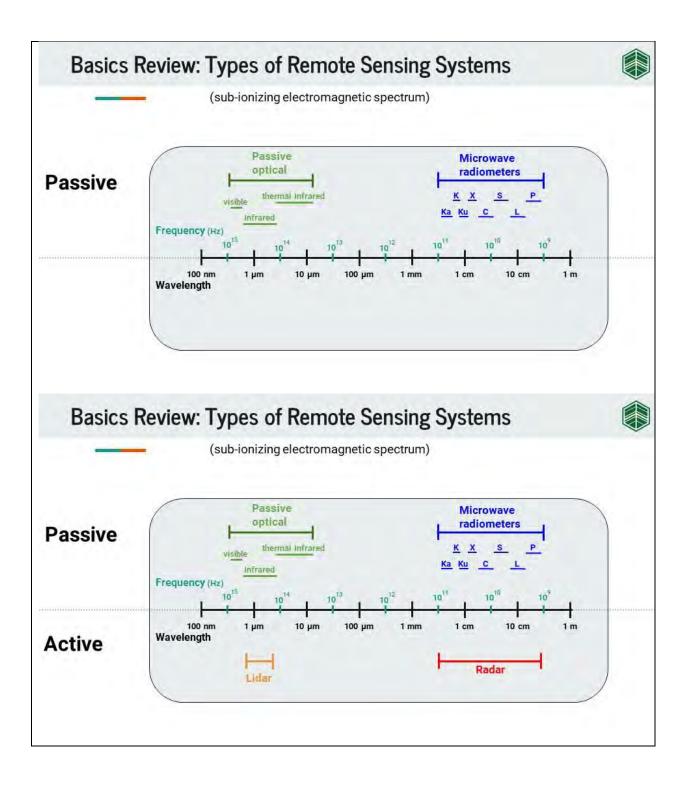




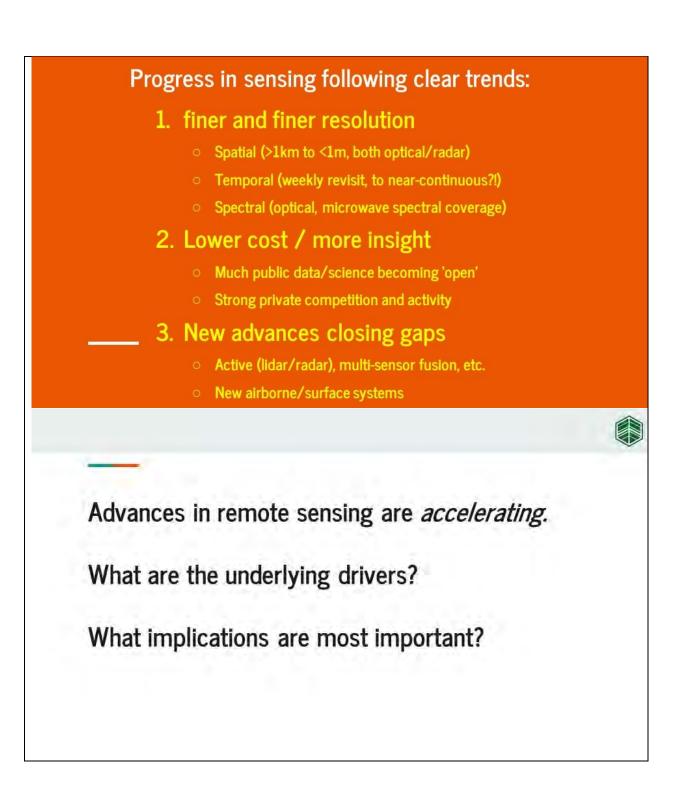




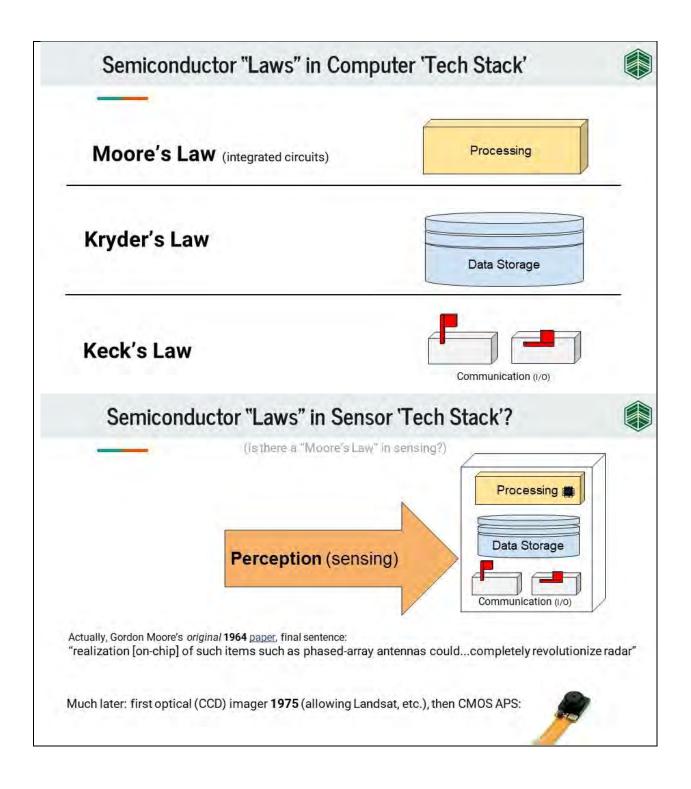




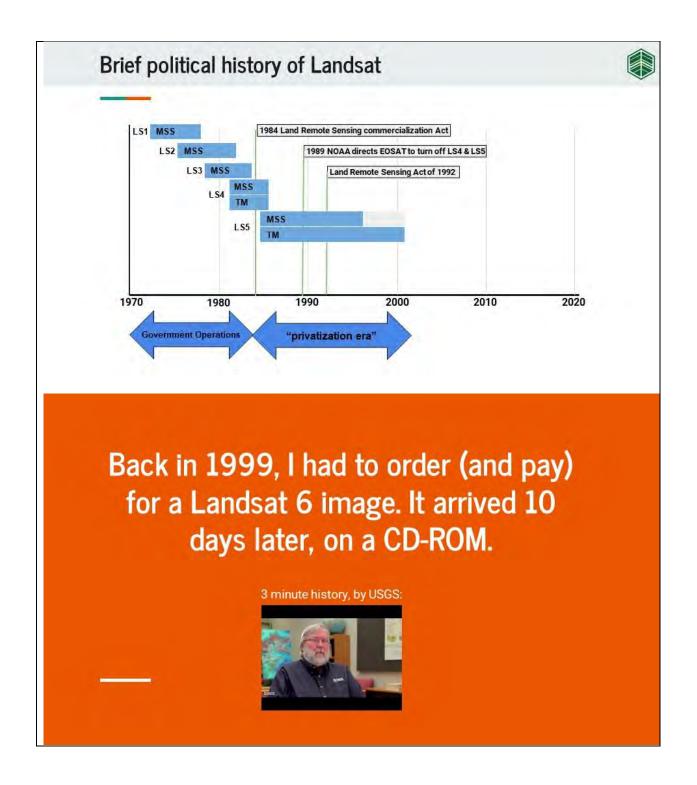




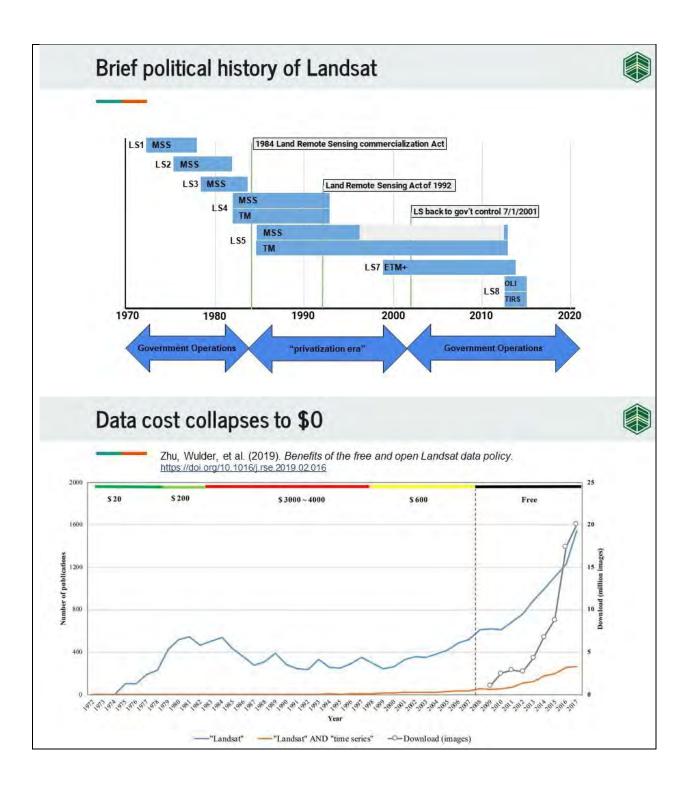








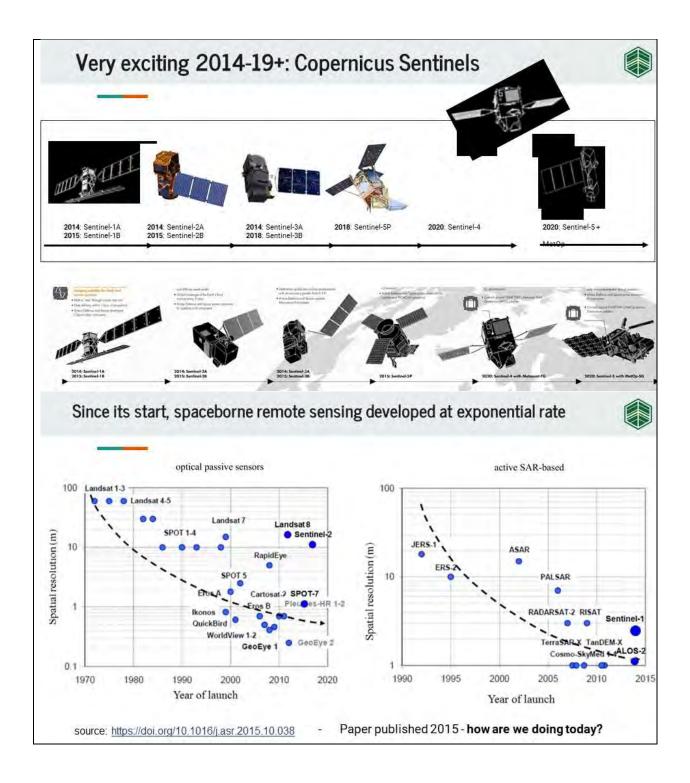




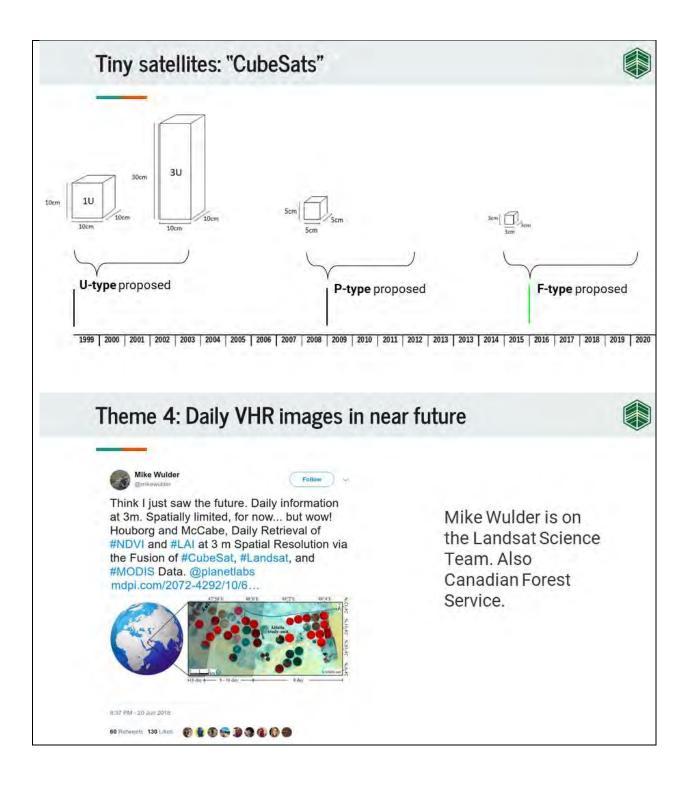








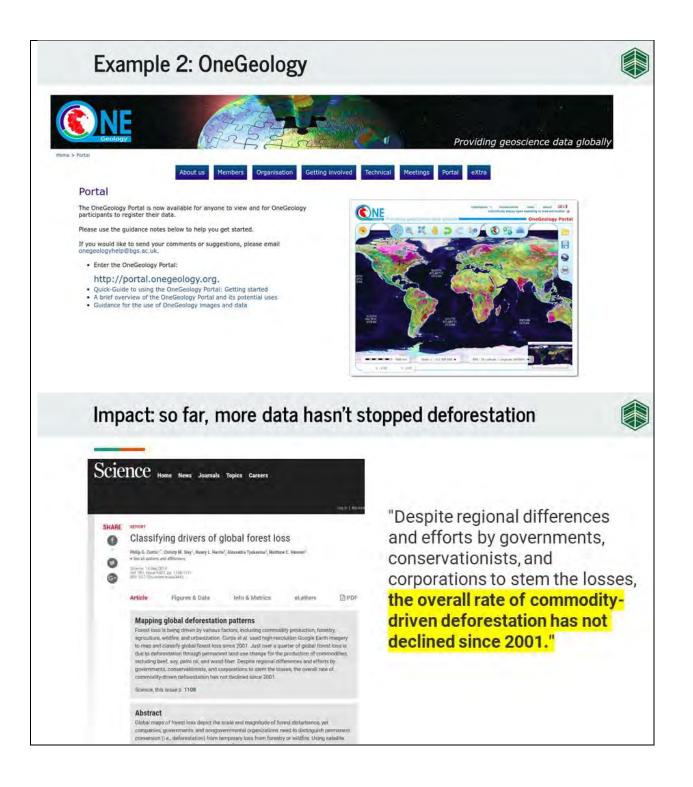






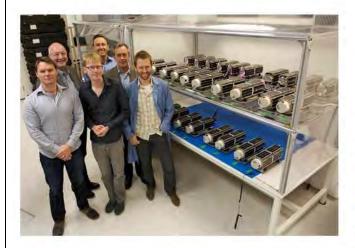
But things don't always go smoothly. Some not-so-successful examples: Example 1: Dry matter productivity in kg/ha/day **Copernicus Global Land Service** opernicus Product Access Products News Viewing Library Derived differences in DMP from MODIS and/or Copernicus do not match available Burnt Area Land Cover deforestation maps (e.g. from NDVI the GlobalForestWatch). FAPAR Soil Water Index Possible explanations: FCOVER VCI Leaf Area Index eriging the Harris VPI high noise in data? ٠ model parameters for DMP product updates **Dry Matter Productivity** Pail Since survey of DMP and G some areas (tropics) atter Productivity (DMP) represents the overall growth rate or dry biomass increase of tion and is directly related to ecosystem Net Primary Productivity (NPP), however with ized for agro-statistical purposes (kg/ha/day). Thu, 00 Feb 2018 inaccurate? Thu, 06 Feb 2018 Similarly the Gross Dry Matter Productivity (GDMP) is equivalent to Gross Primary Productivity (GPP) cloud cover problems? The main difference between DMP and GDMP lies in the inclusion of the autotrophic respira **DMP** product types DMP and GDAP 14m







Data explosion - new technical and ethical questions



In Feb. 2017 Planet Labs, Inc. (AKA Google) claimed to collect a 50 Terapixel image every day whole earth at 5m resolution.

In 2019, at least 8 competitors, proposing to collect much more!

Are we in danger to be overwhelmed with data we do not need?

These companies sell only to those who pay! Ethics, inequality issue?

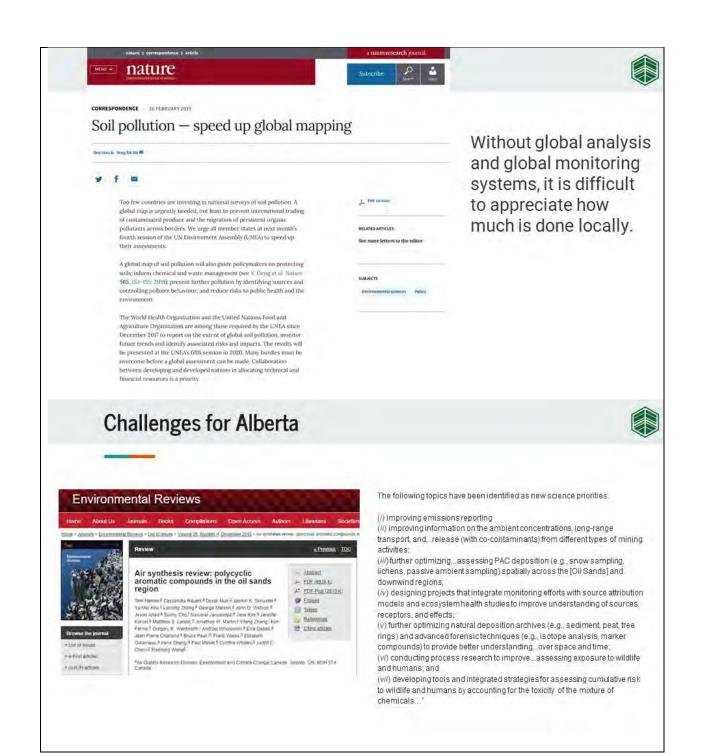
Not clear if applied work will be easier

"The rich "network effects" made possible by chained Web services, GRID computing, sensor webs, geospatial semantics, and online catalogs for data, services and schemas hold great promise, but there is no guarantee that this promise will be fulfilled.

The question is, can we find the institutional will - in academia and government - to make changes that enable societies around the world to make the most of these new tools?"

> Prof. Mike Jackson, David Schell and Prof. D.R. Fraser Taylor: https://www.directionsmag.com/article/2366







We are now in 2019,

What are the most exciting new global data releases?

What new application areas will result from these data?

Theme 1: Copernicus land products









Theme 3: TANDEM-x forest/non-forest map at 50 m



Forest/Non-forest map of the world at very high accuracy and 50 m resolution (coming out soon)

Figure 17: TanDEM-X Forest/Non-Forest Map example over the Amazon Rainforest (image credit: DLR)

Theme 3: TANDEM-x global DEM at 100 m

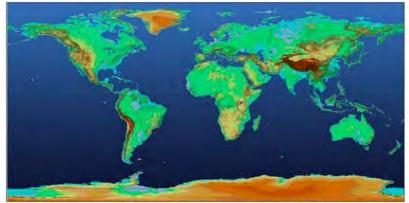
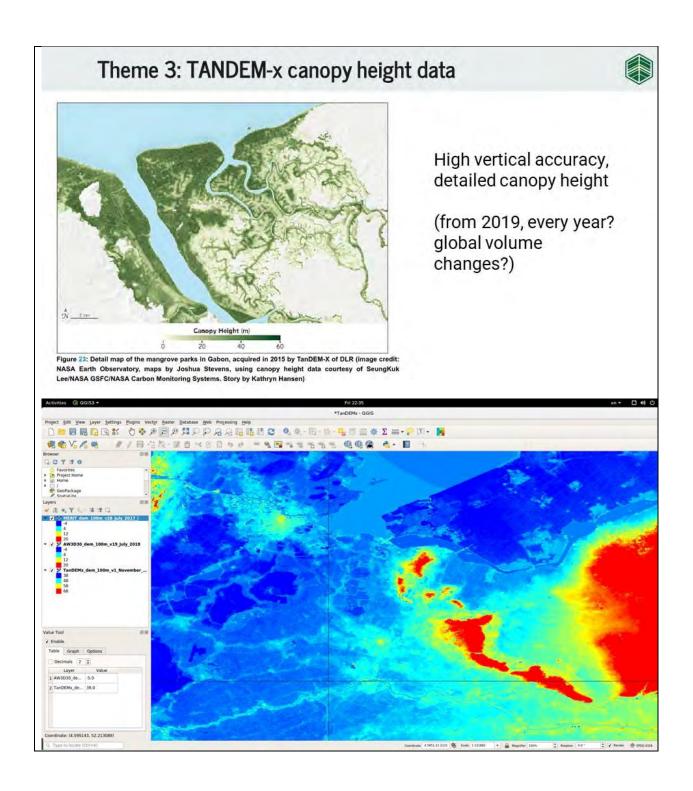


Figure 19: The global TanDEM-X DEM is a consistent data set covering all land surfaces at unprecedented absolute height accuracy of about 1m at a horizontal sampling of 12 m by 12 m. Between 2011 and 2014 at least two acquisitions have been collected by the bistatic TanDEM-X SAR interferometer, mountainous areas have covered up to six times (image credit: DLR)

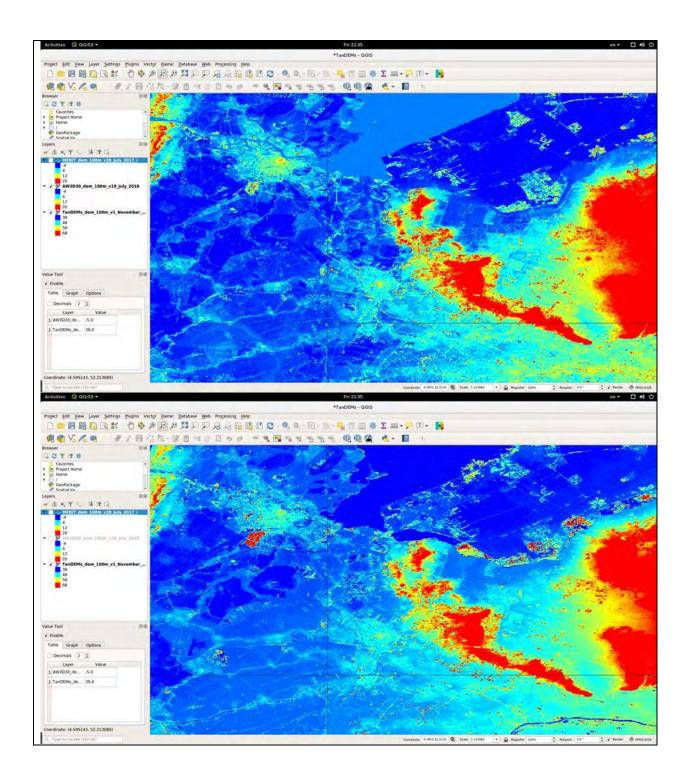
Global land surface model at 100 m OPEN DATA LICENSE? (release date: end of 2018?)

MirrorSAR (6 m?)







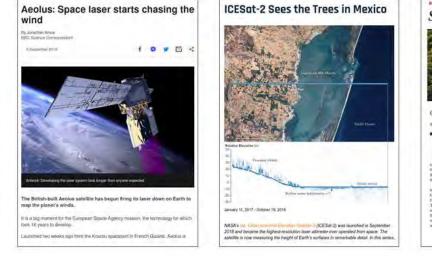




Some other exciting developments to anticipate in 2019/2020...

More "active"-type sensing

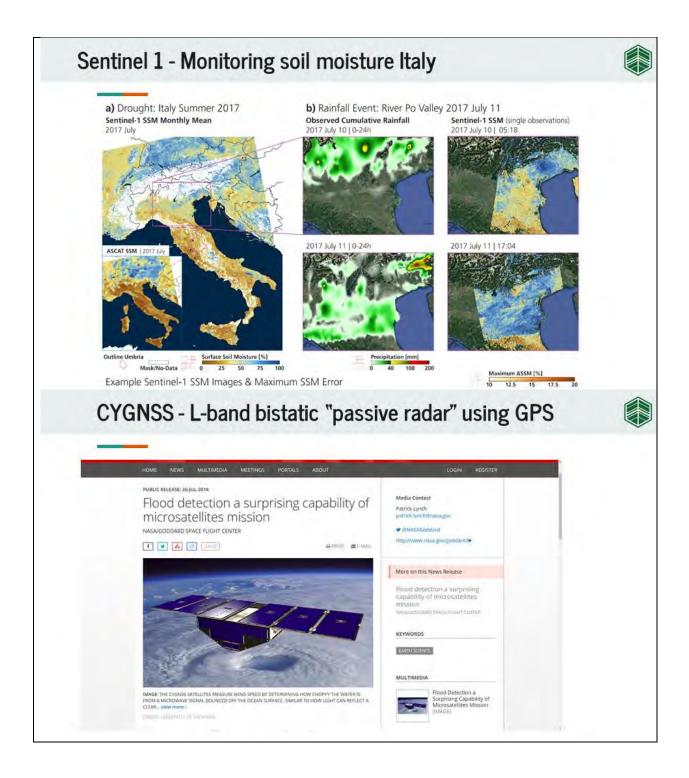
3x spaceborne Lidar outlook 2019: Aeolus, ICESAT-2, GEDI



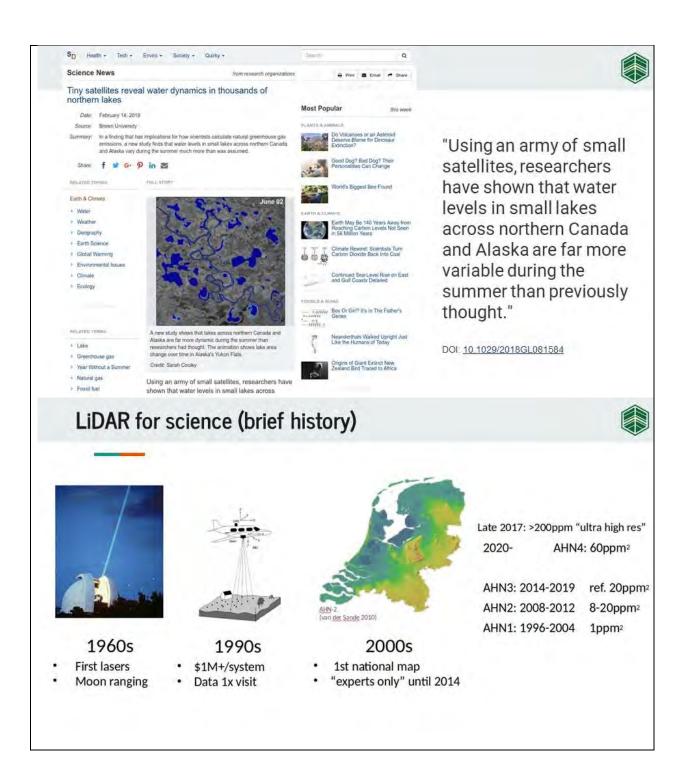


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CInnoTech









[176]

LiDAR in 2019 (Commercial acceleration)



2005-2015 DARPA & SV VC

Cost: >\$75k in 2011, <\$20k 2016

• SWaP limit uses (e.g. no UAVs)

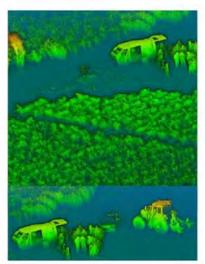
· Computers limit real-time use



2017- New commercial lidars

Cost: \$10k-\$4k in 2018, <\$1000 2019

- + 6000ppm unprecedented resol./cost
- Still need dedicated scan unit/team
- + This ensures good surveys/processing



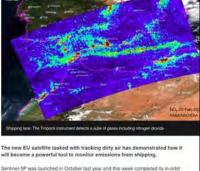
Video

Copernicus 5-P (precursor)

Science & Environment

Prometra 2007 provide transformed and transfo

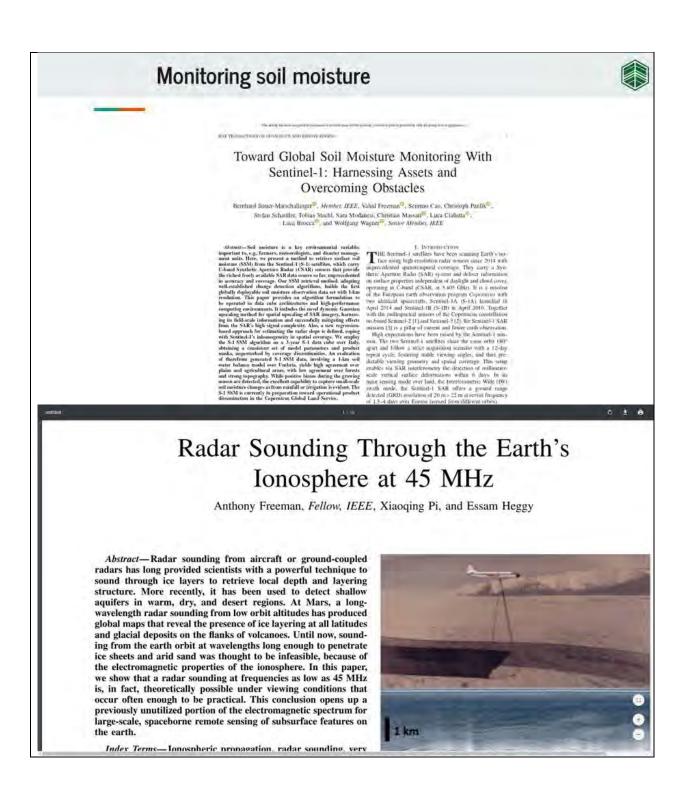
working less than a month but already the UK-Dutch-built Sentinel Ite is returning spectacular new views of Earth's atmosphere. Sentinel tracks ships' dirty emissions from orbit By Jonathan Arros Bibl Somere Correspondent 27 Aeri2018 f 0 y 12 < 50 Correct and the correspondent



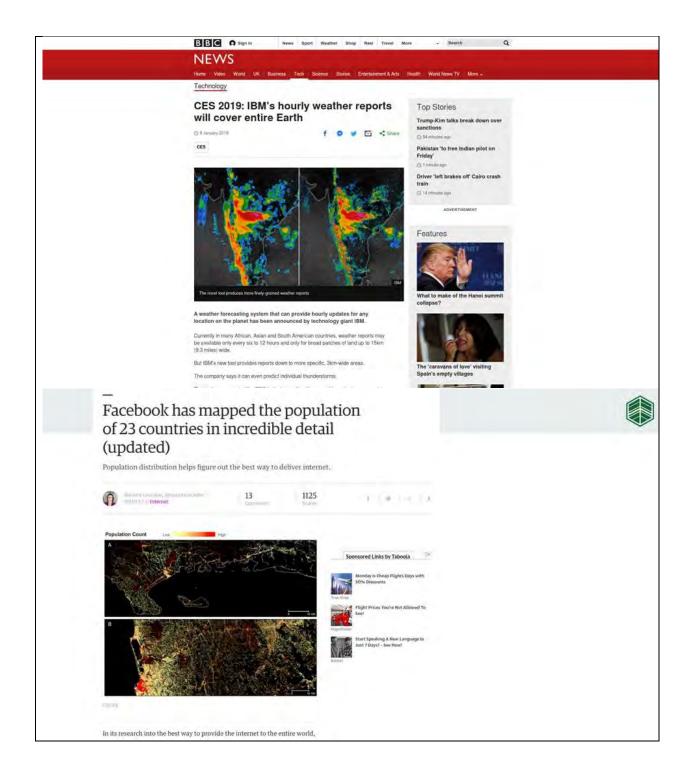
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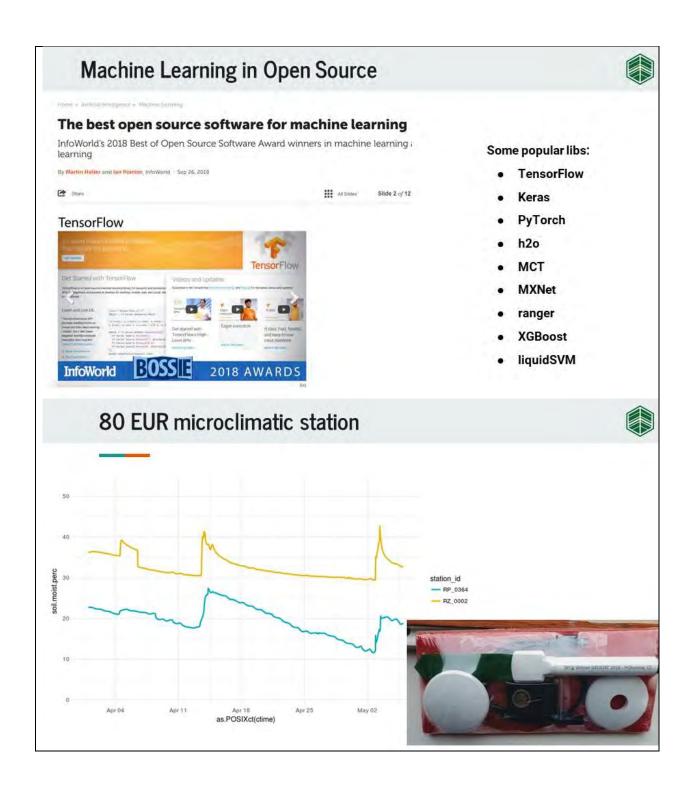
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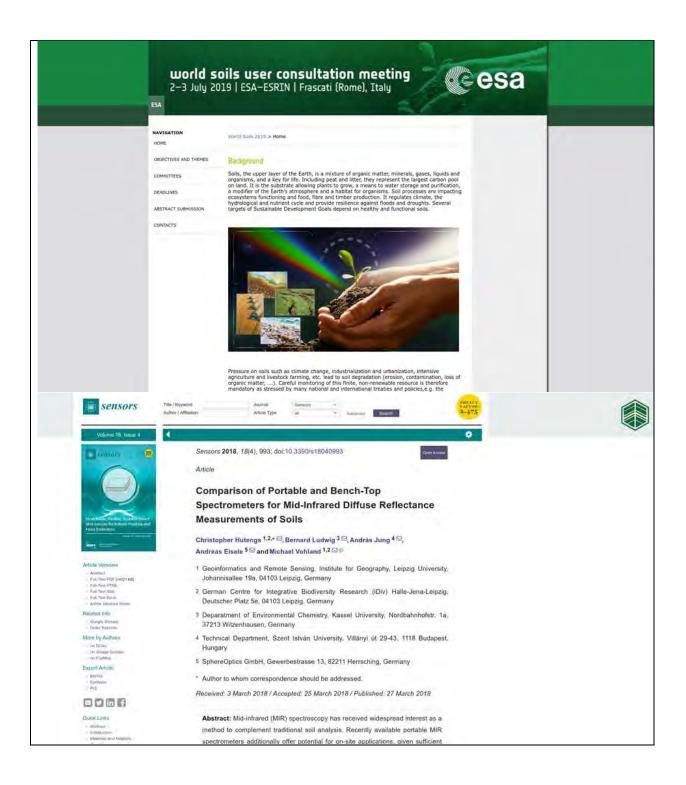




Figure 2. MIR spectrometers used in this study: (a) Bruker Tensor 27 bench-top instrument with EasyDiff diffuse reflectance accessory (back, in the sample "Our findings suggest that compartment) and Ulbricht sphere (front); (b) Agilent 4300 portable FTIR instruments Handheld FTIR measurement with custom sample cup. are a viable alternative for MIR measurements in the b) Agilent 4300 Handheld FTIR a) Bruker Tensor 27 laboratory and offer great potential for on-site applications." agrocares Services Products About us News Shop **Our revolutionary** products At AgroCares, we offer out ts and other key parameters in Select your product



Lab-in-the-box

n-life access to testing servi

only wet chemistry laboratories could provide until now Read more about the Lab-in-a-box ->

Soil spectroscopy

[182]

Scanner

ore about the Scanner

Read m

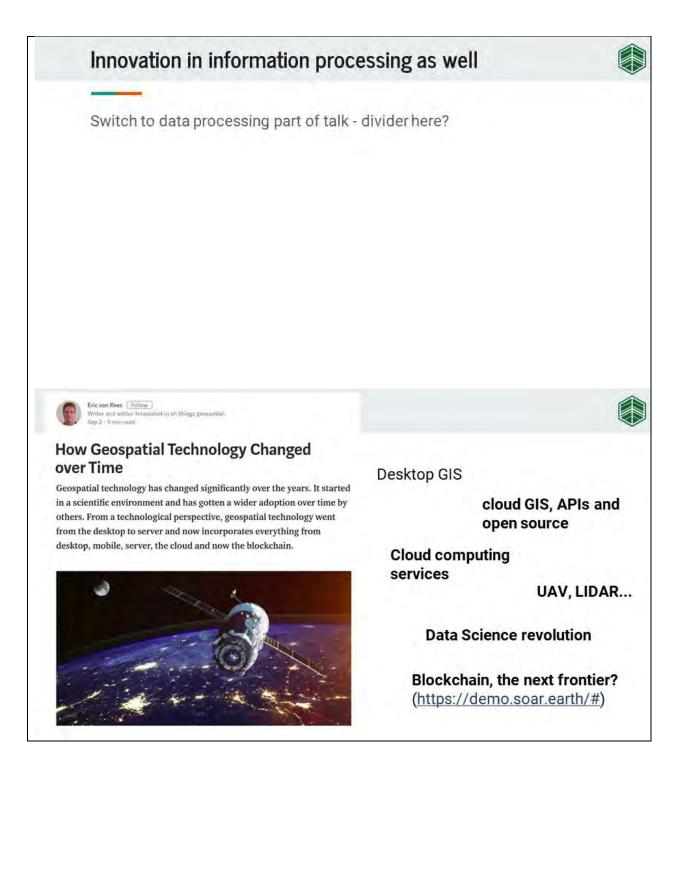
Scoutbox

Read more about the Scoutbox ->

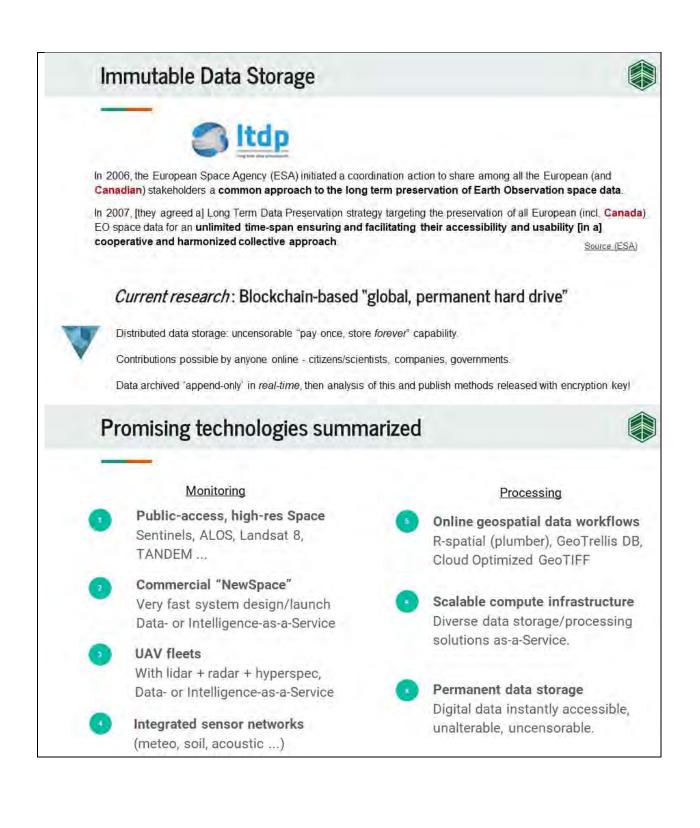
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Remotely-pilo	ted aircraft (RP	A)		
	orkflow automation raise	s data quality/cons	istency.	
Short range	Medium range		Long range	
		Delair DT26-X 10 km ² range Lidar (70ppm ²)+RGB		AeroVe • 1000 km ² • Multispec • VTOL
		Marlyn Atmos 12 km² range/batt. Modular payloads Automated, VTOL		Delair N 1 Lidar flights Congo, etc.
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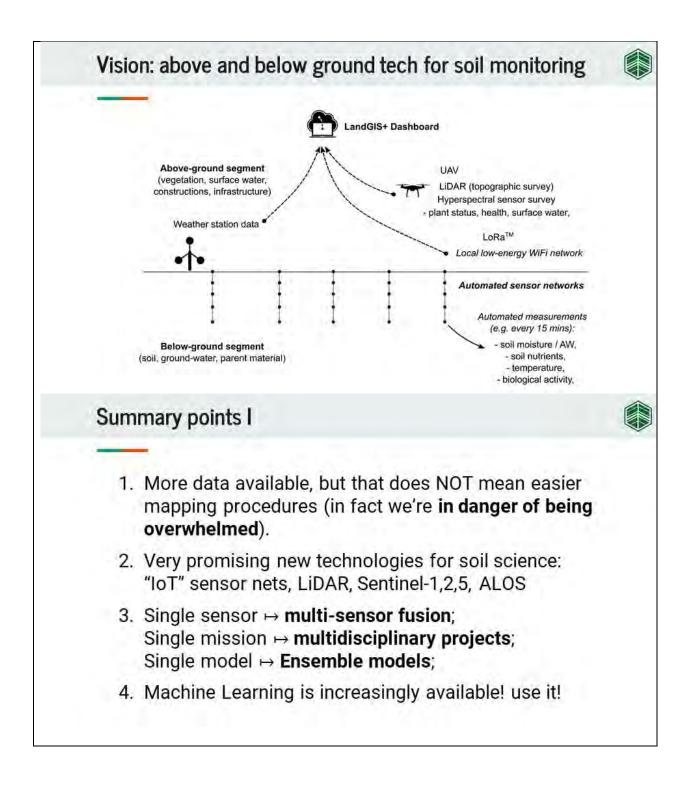




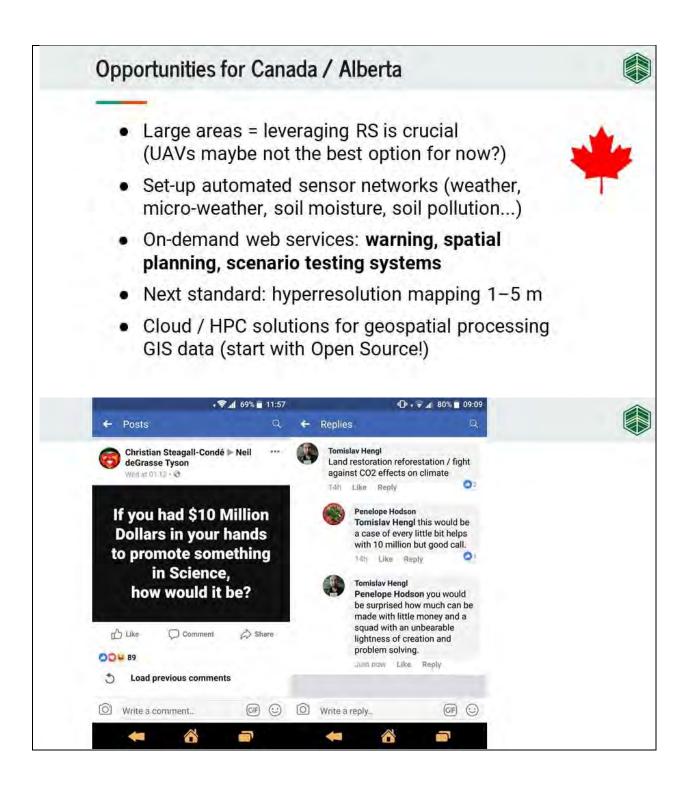














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Quote of the day



"Never doubt that a small group of thoughtful, committed, citizens can change the world. Indeed, it is the only thing that ever has."

– Margaret Mead

